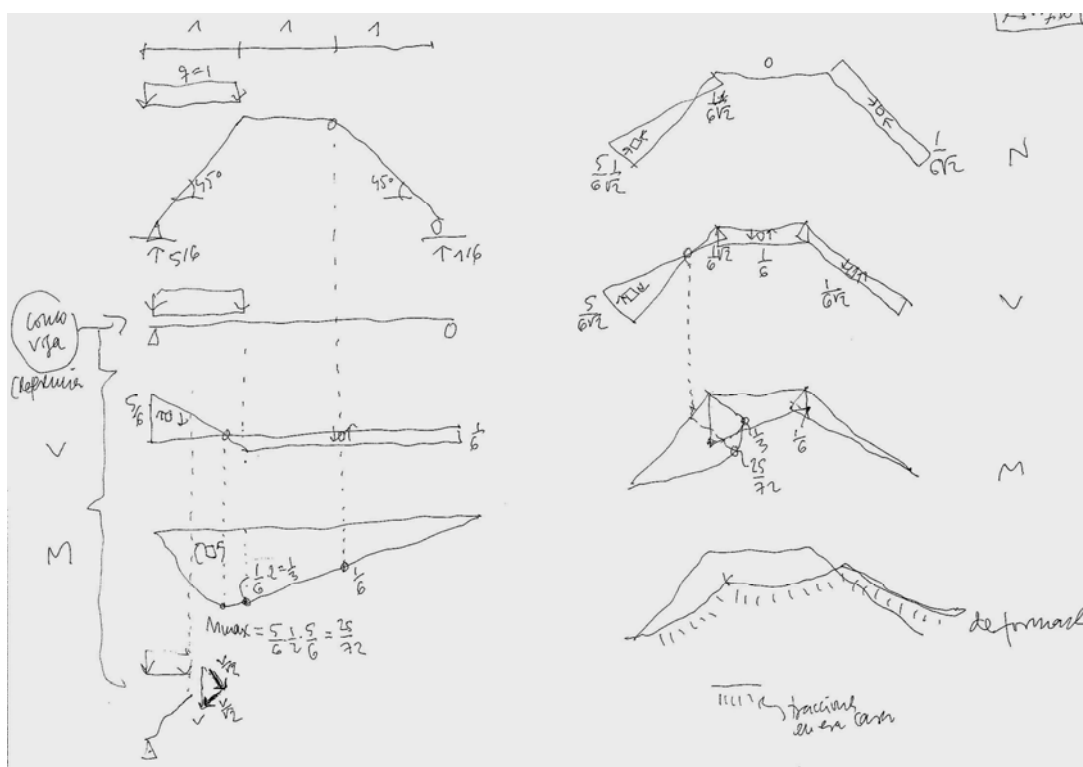



ESTRUCTURAS I: EJERCICIOS DE DIAGRAMAS DE ESFUERZOS

**MADRID, Abril 2012 (v3)**

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Reconocimiento - NoComercial - SinObraDerivada (by-nc-nd)

DIAGRAMAS de ESFUERZOS

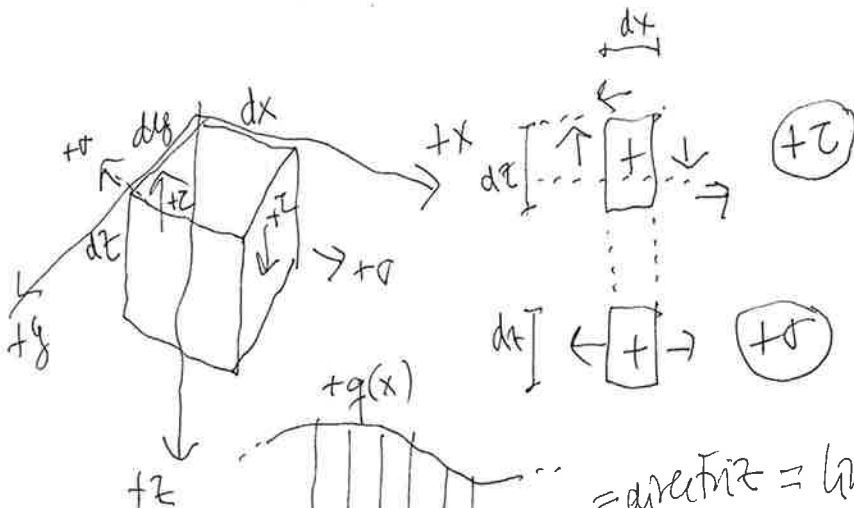
Normales o Axiles, Cortantes, Momentos Flectores

(N)

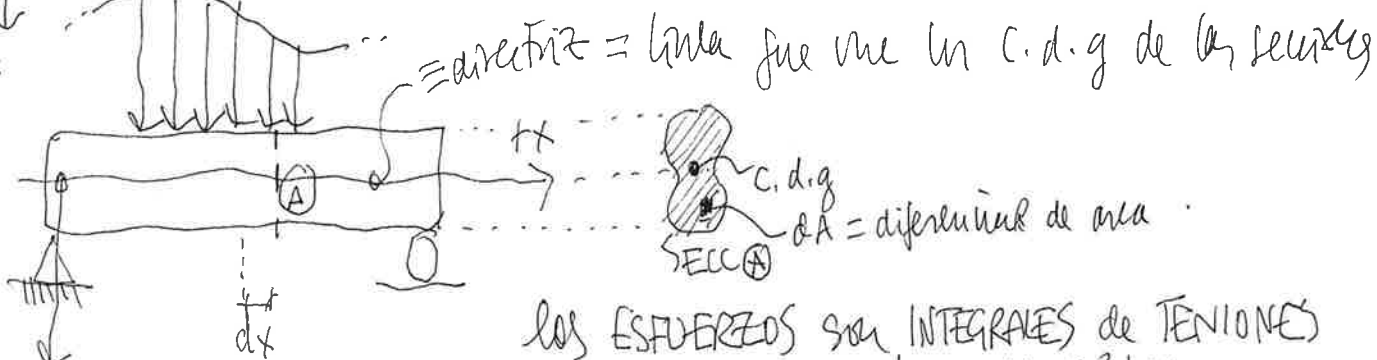
(V)

(M)

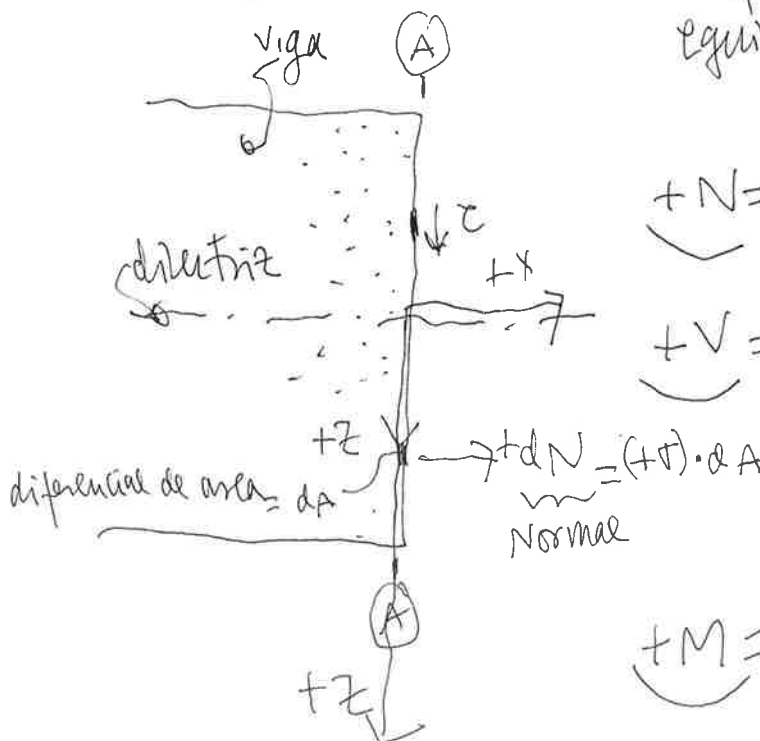
Convenio de signos \longleftrightarrow vinculado al de las tensiones $\begin{cases} \text{Normales} = \sigma \\ \text{Tangenciales} = \tau \end{cases}$



Consideraremos sólo esfuerzos en el plano xz i.e. decir, nos limitamos a 2D



los ESFUERZOS son INTEGRALES de TENSIONES de forma que producen un sistema equivalente de cara al EQUILIBRIO general.

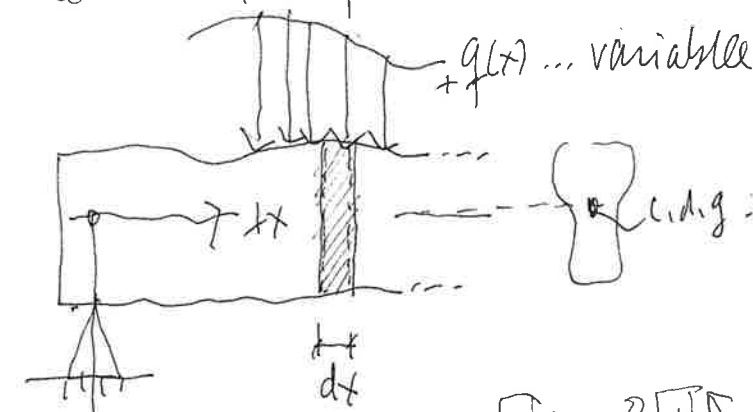


$$+N = \int +\sigma \cdot dA \Rightarrow \leftarrow \boxed{+} \rightarrow (+N)$$

$$+V = \int +\tau \cdot dA \Rightarrow \uparrow \boxed{+} \downarrow (+V)$$

$$+M = \int (+\sigma) \cdot dA \cdot (+z) \Rightarrow \curvearrowright \boxed{+} \curvearrowleft (+M)$$

Relaciones diferenciales entre cortante y flector (\rightarrow FLEXION)



$+x$

$+z$

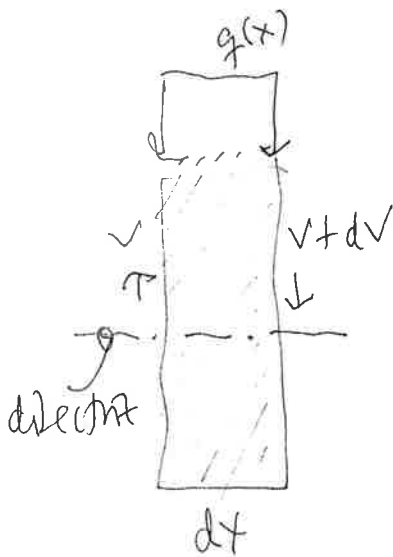
$\left\{ \begin{array}{l} \text{Acciones} \dots \\ +q(x) = \text{carga lineal} \dots \\ +V(x) = \text{cortante} \dots \\ +M(x) = \text{momento} \dots \end{array} \right.$

τ

σ

\checkmark

M



$$\sum F_z = 0 \quad + \downarrow$$

$$q \cdot dx - V + V + dV = 0 \Rightarrow q \cdot dx + dV = 0$$

$$\boxed{q = -\frac{dV}{dx}} \quad \dots \circ \dots$$

$$V = \int_A^B -q \cdot dx$$

no suele usarse

$$\sum M_O = 0 \quad + \curvearrowright$$

$$M - M - dM + q \cdot dx \cdot \frac{dx}{2} + V \cdot dx + dV \cdot dx = 0$$

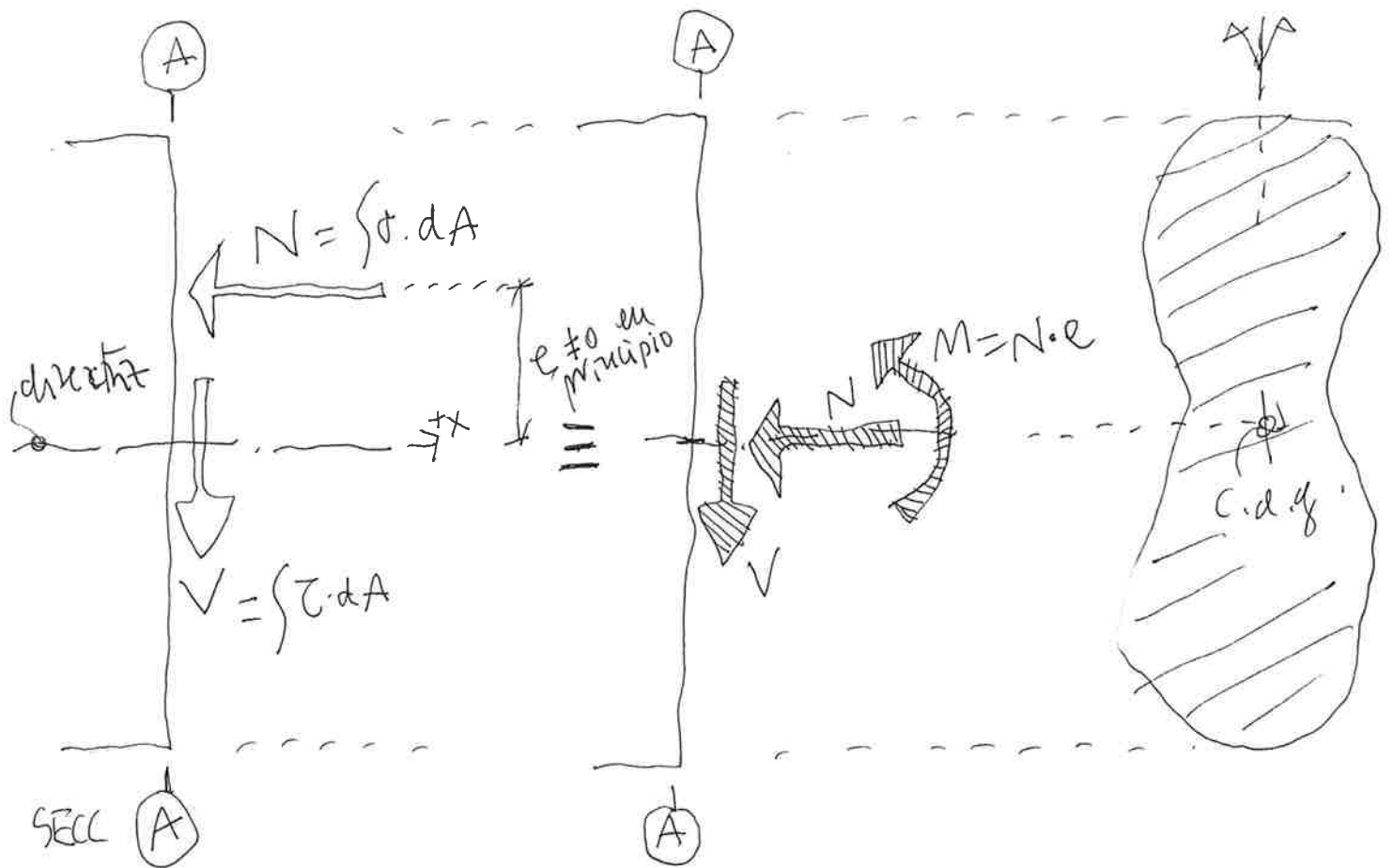
$$-dM + V \cdot dx = 0$$

$$\boxed{\frac{dM}{dx} = V} \quad \dots \circ \dots$$

$$M_{AB} = \int_A^B V \cdot dx$$

diferencia o salto de momento entre dos secciones A y B.

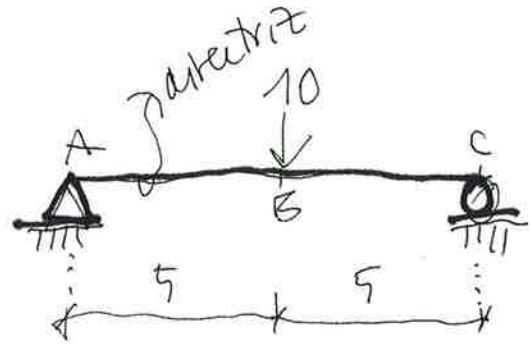
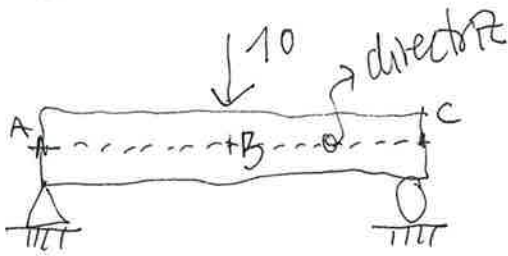
el normal N no interviene ni en $\sum F_z = 0$ ni en $\sum M = 0$, ya que en el segundo caso además es con referencia a la directriz



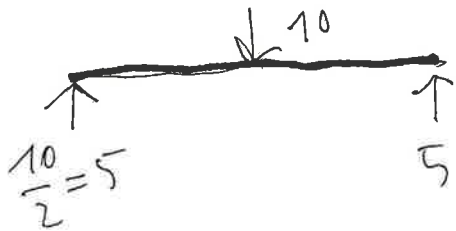
Solo son necesarios (y suficientes) tres esfuerzos, resultantes de las tensiones σ y τ , tomando además como referencia la directriz de la pieza.

N , M y V representan, en forma de tres resultantes equivalentes, las fuerzas que, en ese corte, y de cara al equilibrio general (no a nivel diferencial) ejerce la parte de la estructura que es eliminada sobre dicho corte.

E1



Equilibrio general \rightarrow relaciones



... simetría ...

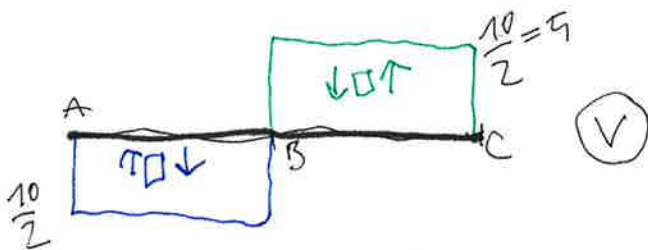
efectivamente:

$$\sum M_A = 0 \rightarrow$$

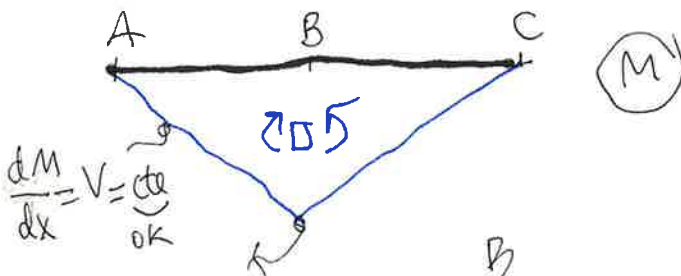
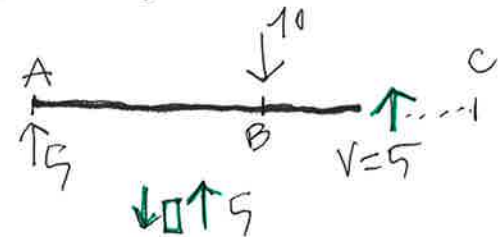
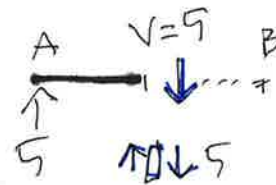
$$10 \cdot 5 - 5 \cdot 10 = 0$$

$$\sum F_x = 0 \Rightarrow 10 - 5 - 5 = 0$$

Esfuerzos:



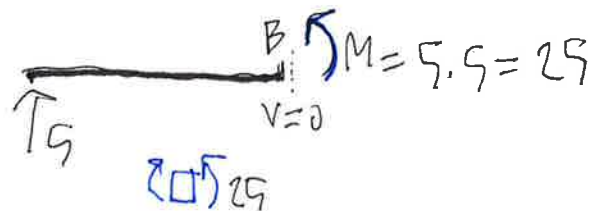
$$\frac{dV}{dx} = -q = 0 \quad \text{OK}$$

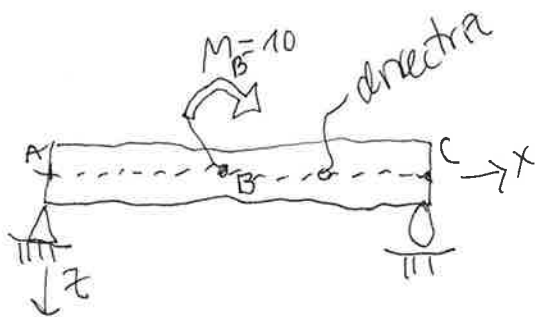


$$25 = M_{AB} = \int_A^B V dx$$

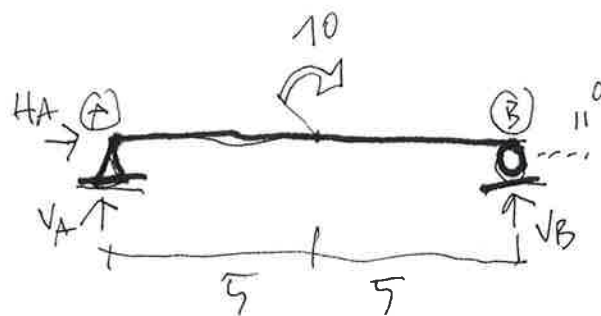
$$M_{AB} = \int_0^5 10 dx$$

area gráfica de constantes
entre las secciones A y B





Equilibrio general
→ reacciones.



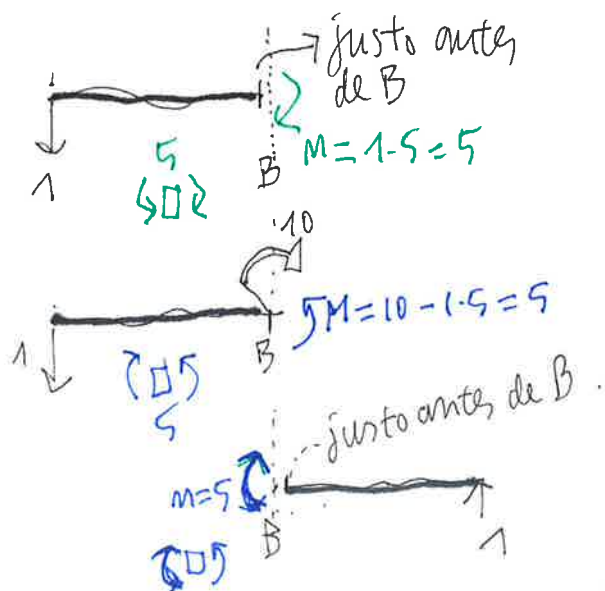
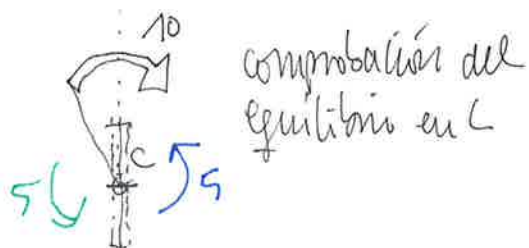
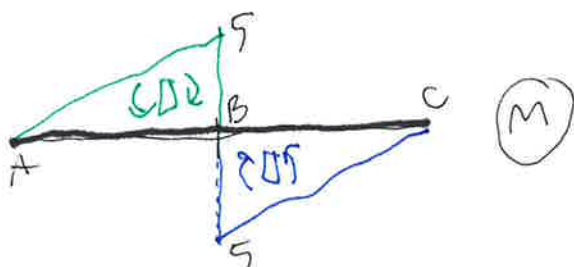
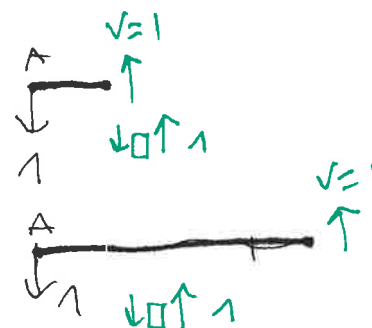
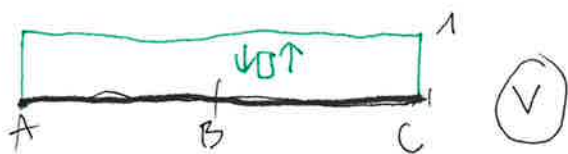
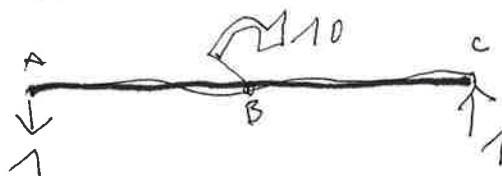
$$\sum F_x = 0 \Rightarrow H_A = 0$$

$$\sum M_A = 0 \Rightarrow 10 - V_B \cdot 10 = 0$$

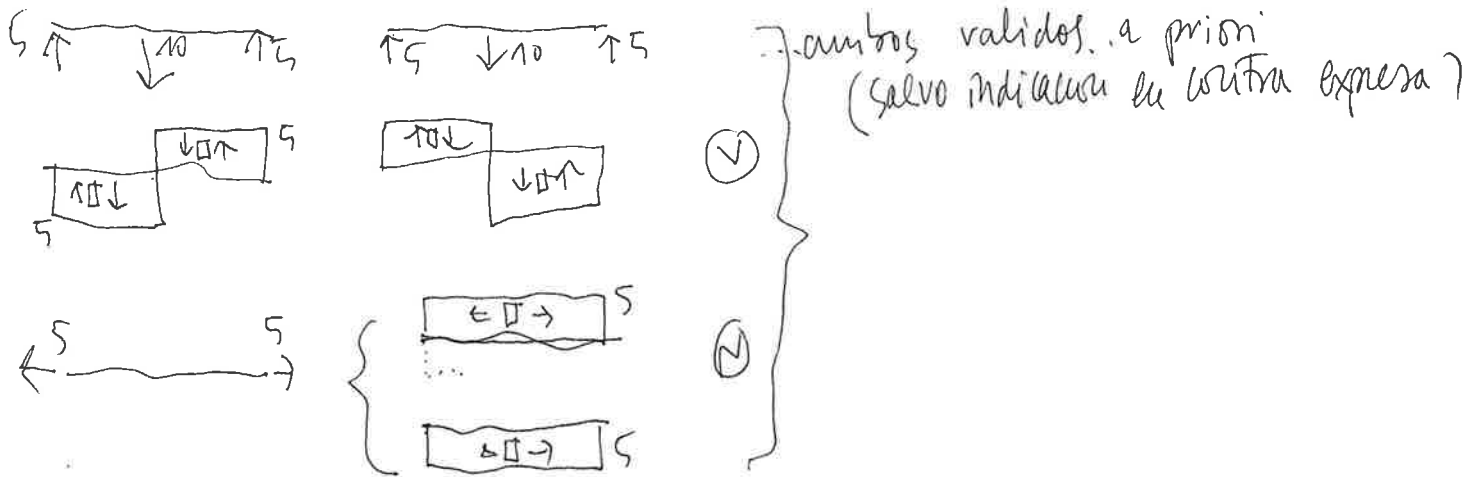
$$V_B = 1$$

$$\sum F_z = 0 \Rightarrow V_A + V_B = 0$$

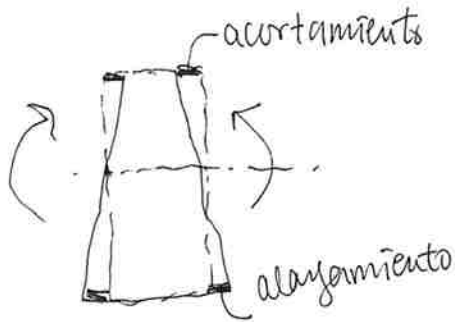
$$V_A = -V_B = -1$$



convencios para dibujar las grietas

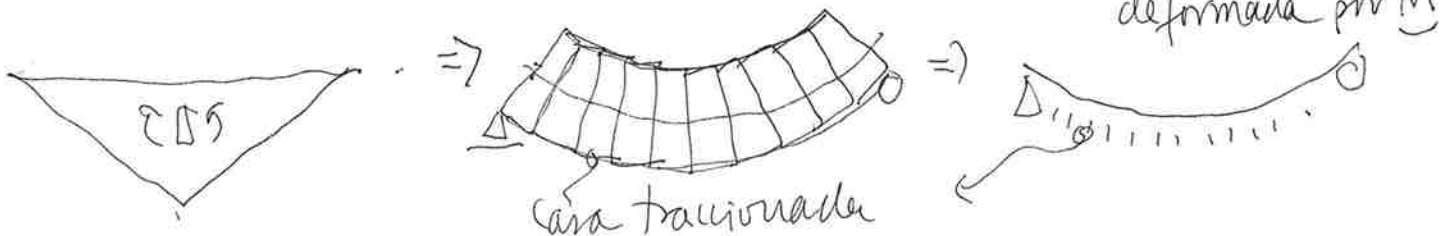
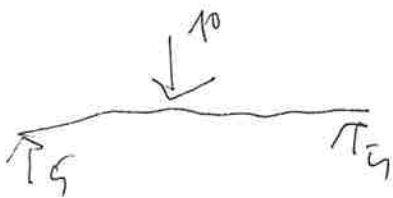


PERO con las FLECTORES si hay CONVENIO general.

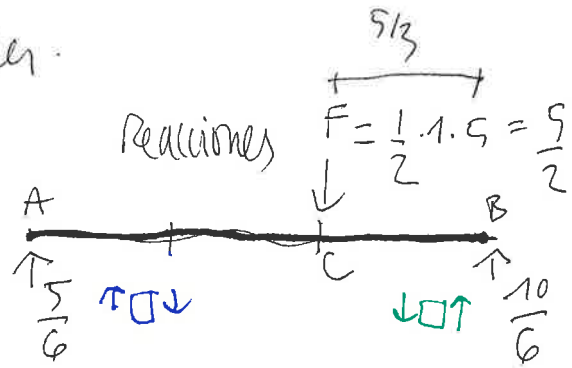
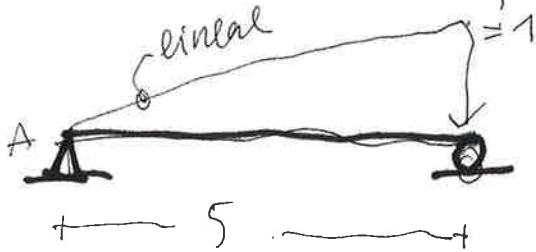


la grieta se dibuja siempre hacia el lado en donde estarian en alargamiento, la cara traccionada.

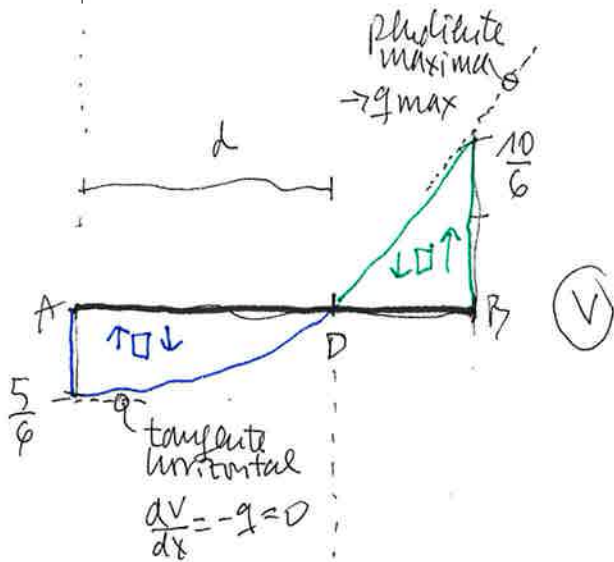
es decir.



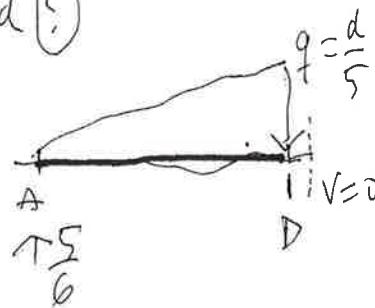
uso de relaciones diferenciales.



$q = \text{lineal} \Rightarrow V = \text{cuadrática} \Rightarrow M = \text{cúbica}$.



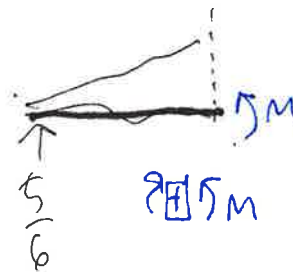
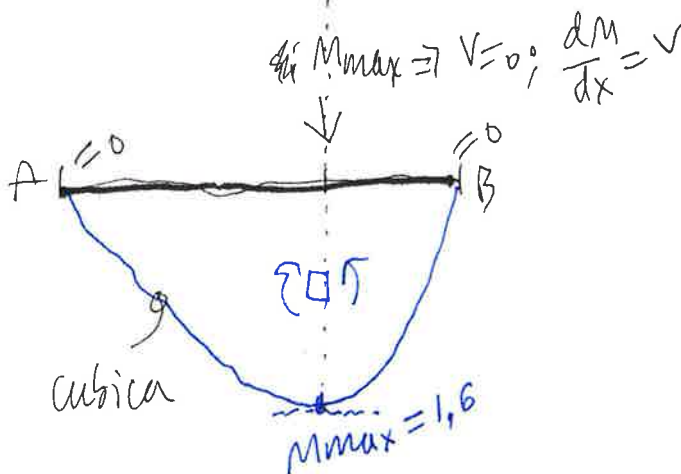
d(?)



$$\sum F_z = 0$$

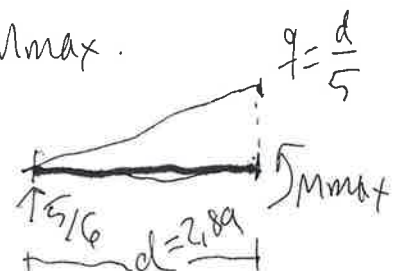
$$\frac{5}{6} = \frac{1}{2} d \cdot \frac{d}{5}$$

$$d = \sqrt{50/6} = 2,89$$



calculo de M_{max} .

• por arts.

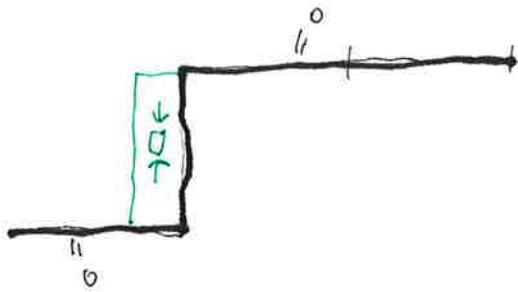
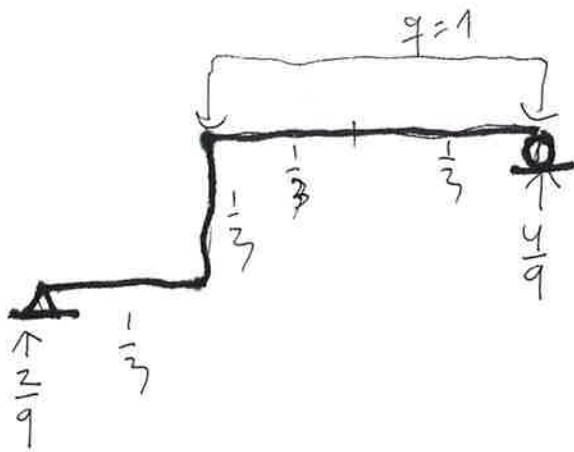


$$M_{max} = \frac{5}{6} \cdot 2,89 - \frac{1}{2} \cdot \frac{2,89}{5} \cdot \frac{2,89}{3} = 1,6$$

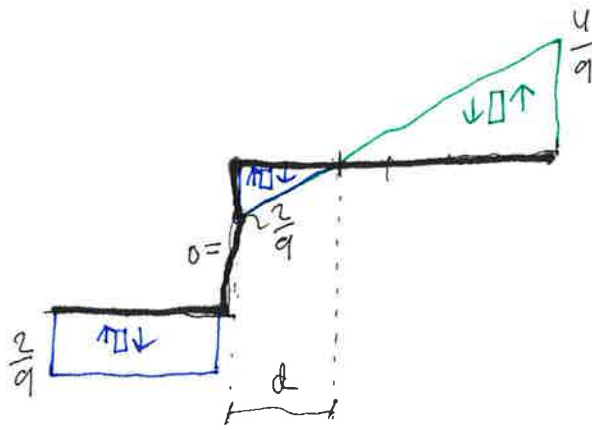
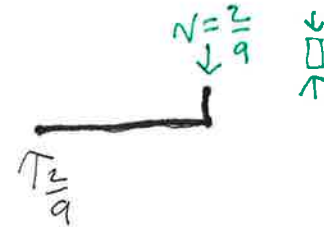
• integrando area de cortantes.

$$M_{max} = \frac{2}{3} \cdot \frac{5}{6} \cdot 2,89 = 1,6$$

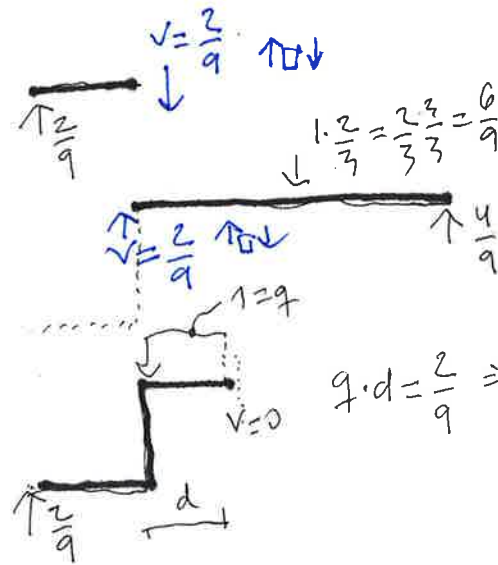




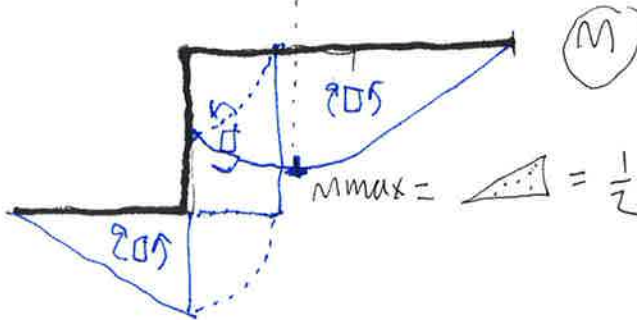
(2)



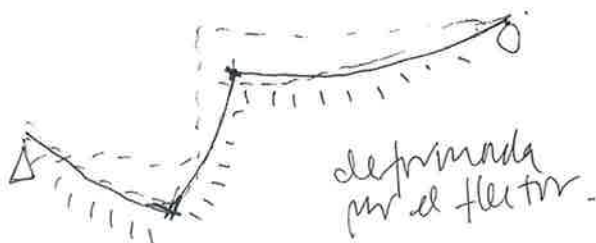
(3)

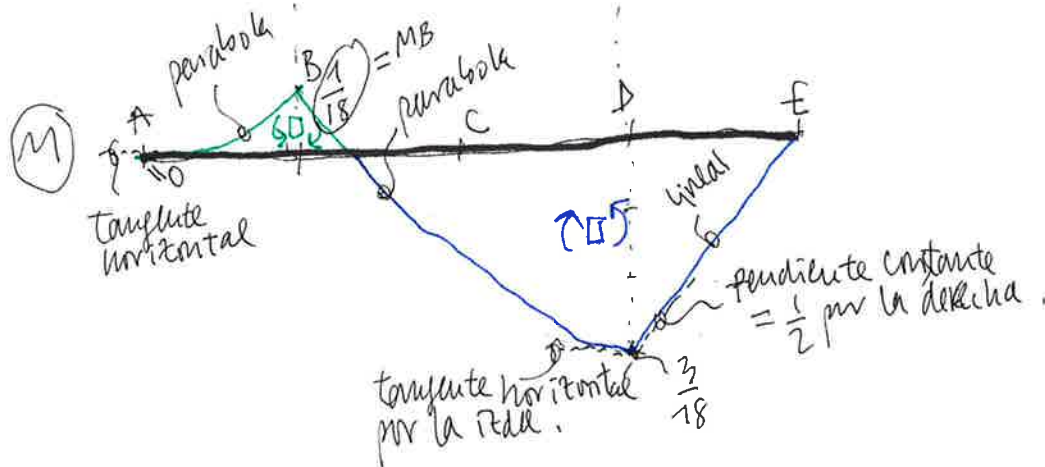
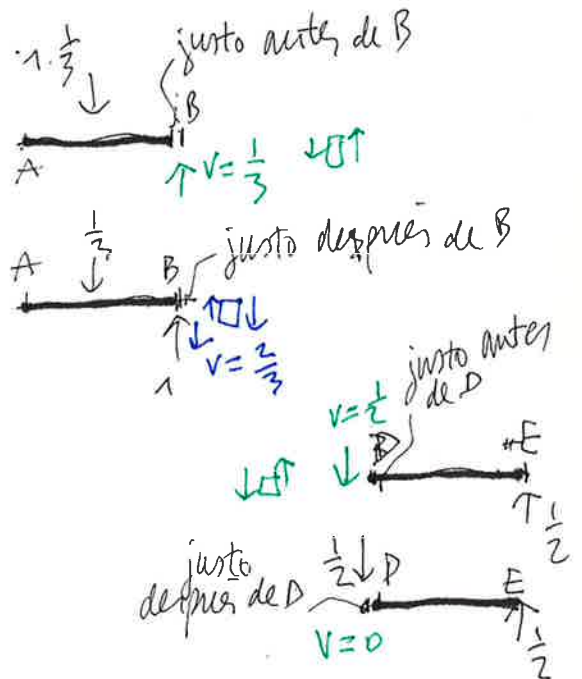
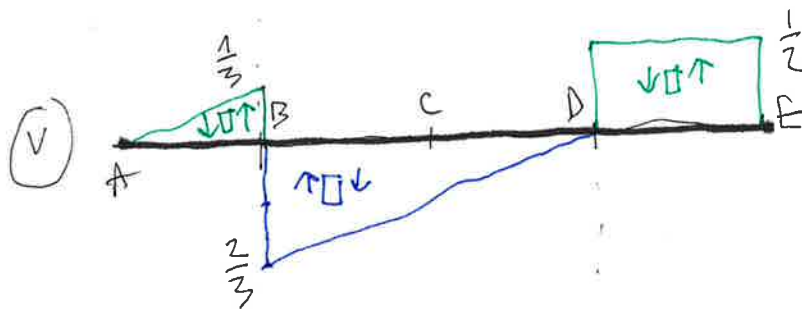
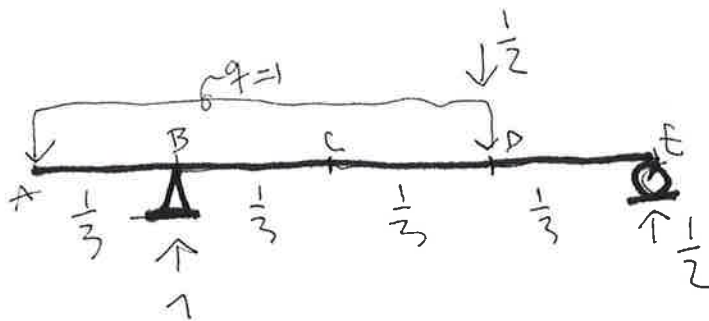


$$q \cdot d = \frac{2}{9} \Rightarrow d = \frac{2}{9} = \frac{1}{4.5}$$



(M)





Integrando áreas de constantes.

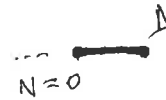
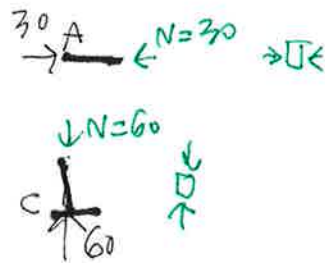
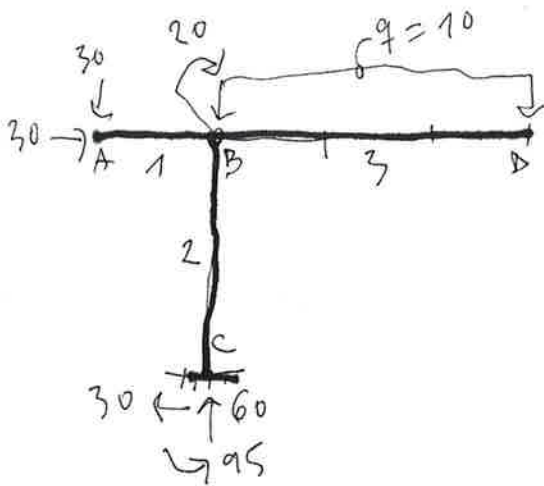
$$M_B = \frac{1}{2} \cdot \frac{1}{3} \cdot \frac{1}{3} = \frac{1}{18}$$

$$M_D = -\frac{1}{18} + \frac{1}{2} \cdot \frac{2}{3} \cdot \frac{1}{3} = -\frac{1}{18} + \frac{1}{9} = \frac{1}{18}$$

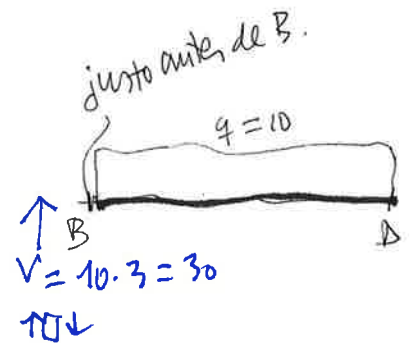
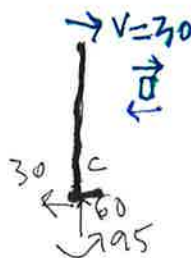
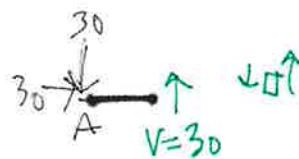
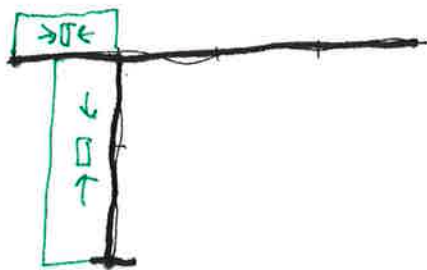
Si ahora se computa el área de constantes por la derecha

$$M_D \equiv \int_E^D V \cdot dx = \frac{1}{2} \cdot \frac{1}{3} = \frac{1}{6} = \frac{3}{18} \cdot \frac{1}{3} = \frac{1}{18}$$

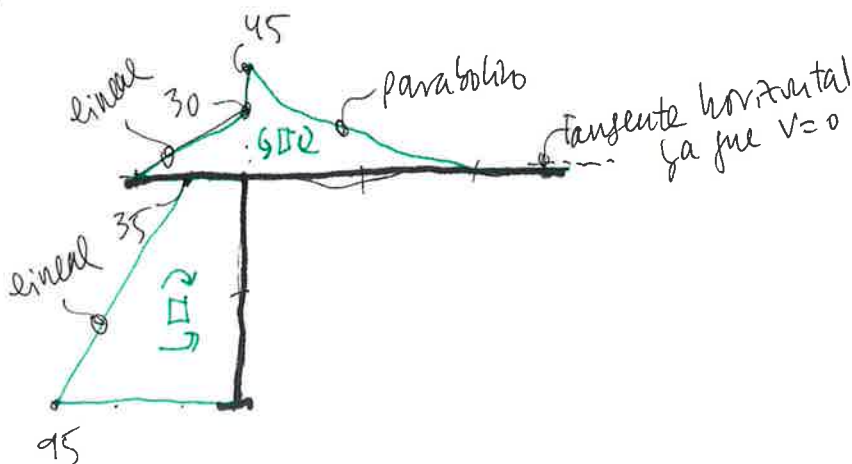
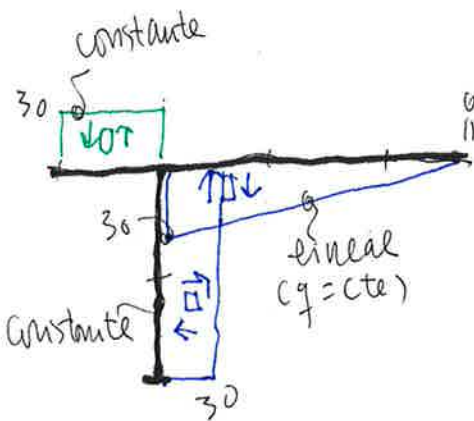
OK



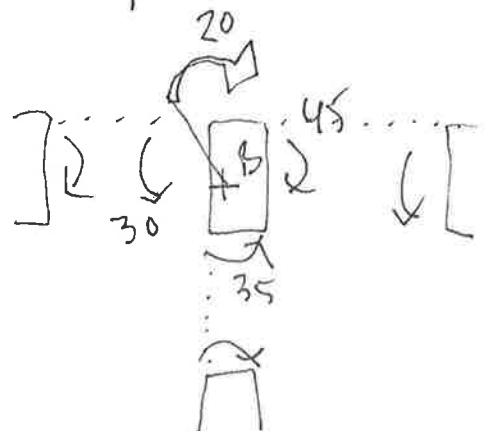
(N)

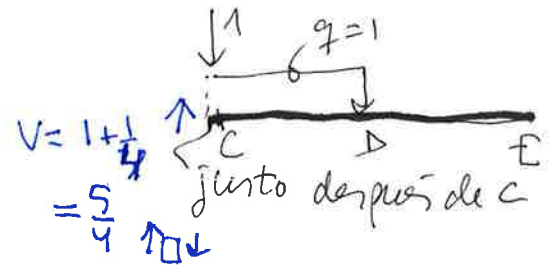
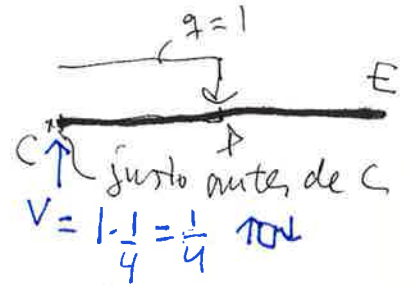
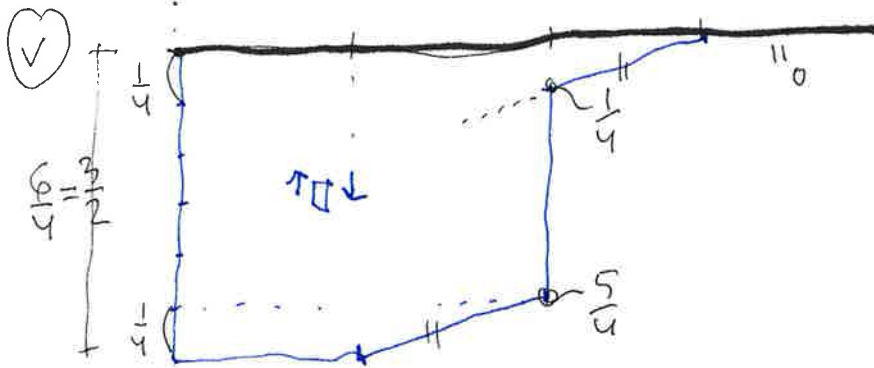
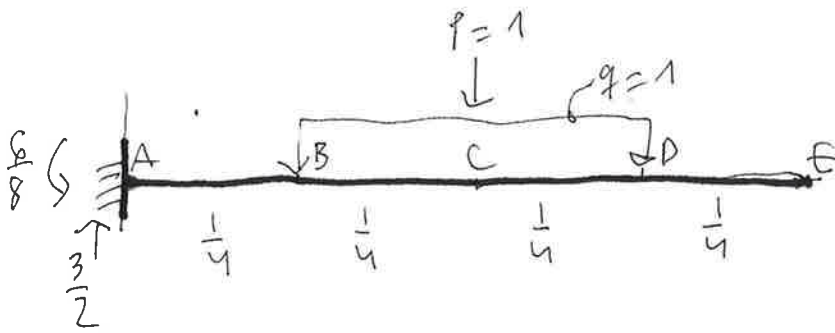


(V)



equilibrio en B

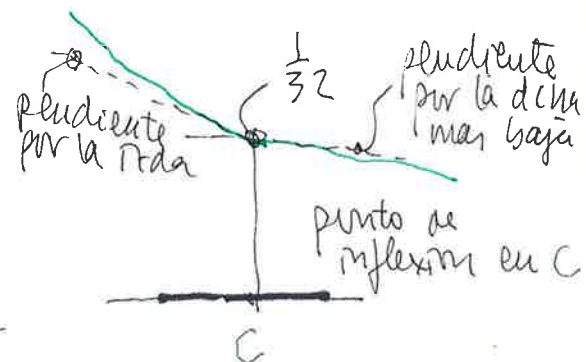
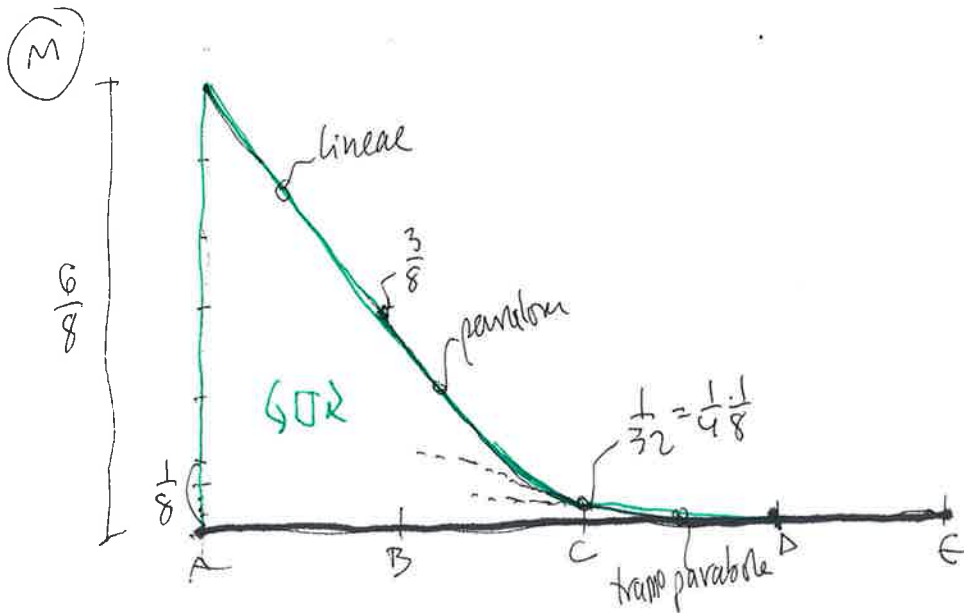


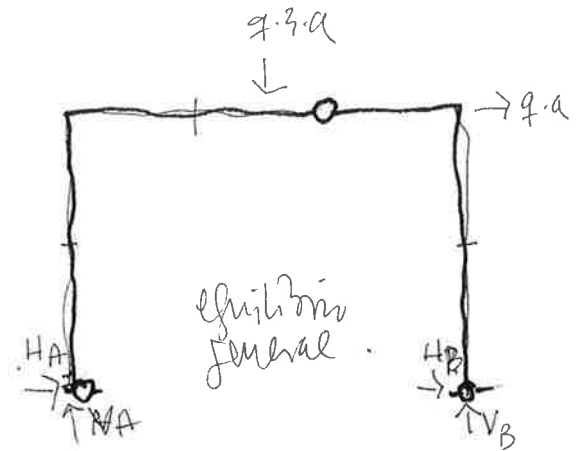
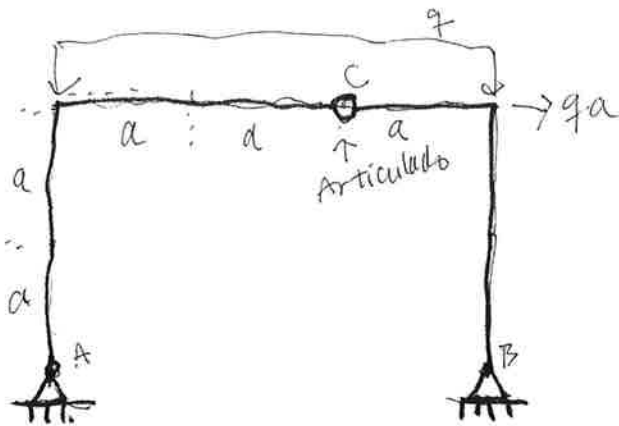


$$M_B = \frac{6}{8} - \left[\frac{1}{4} \cdot \frac{6}{4} \right] = \frac{6}{8} - \frac{1}{4} \cdot \frac{6}{4} = \frac{12-6}{16} = \frac{3}{8}$$



$$M_B = \frac{6}{8} - \frac{3}{2} \cdot \frac{1}{4} = \frac{3}{8}$$



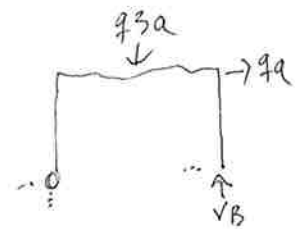


sentido arbitrario a priori

$$\sum M_A = 0 \quad + \curvearrowright$$

$$q \cdot 3a \cdot \frac{3a}{2} + q \cdot a \cdot 2a - V_B \cdot 3a = 0$$

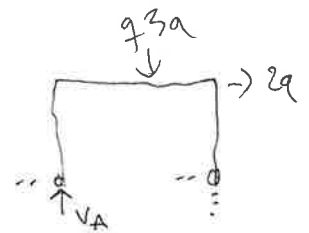
$$q a^2 \left(\frac{9}{2} + 2 \cdot \frac{2}{2} \right) = 3a V_B \quad \Rightarrow \quad \underline{V_B = \frac{13}{6} q a}$$



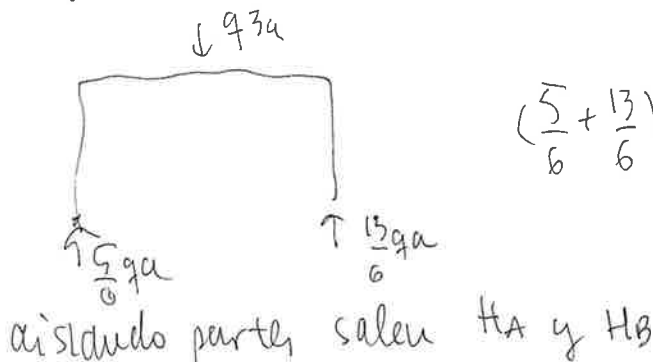
$$\sum M_B = 0 \quad + \curvearrowright$$

$$q \cdot 3a \cdot \frac{3a}{2} - q a \cdot 2a - V_A \cdot 3a = 0$$

$$q a^2 \left(\frac{9}{2} - 2 \cdot \frac{2}{2} \right) = 3a V_A \quad \Rightarrow \quad \underline{V_A = \frac{5}{6} q a}$$

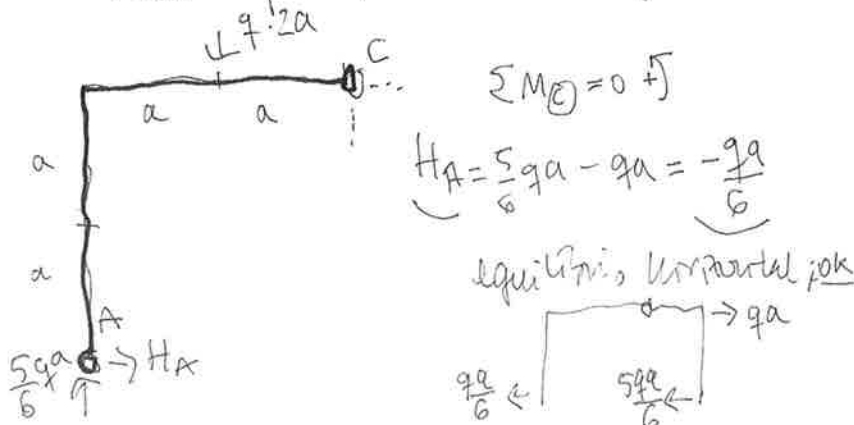


Equilibrio vertical y horizontal de fuerzas.



$$\left(\frac{5}{6} + \frac{13}{6} \right) q a = \frac{18}{6} q a = \underline{\underline{3 q a}} \quad \text{OK}$$

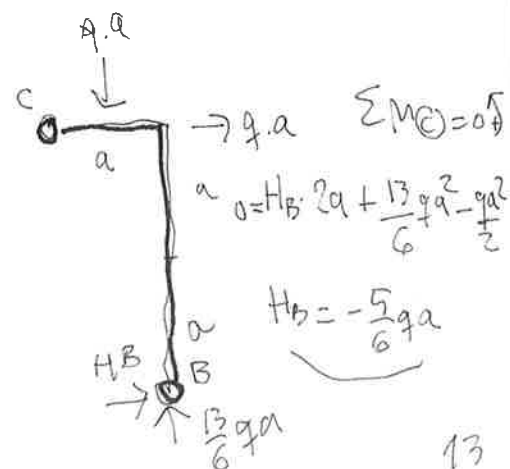
$$\sum F_z = 0 \quad \text{OK}$$



$$\sum M_C = 0 \quad + \curvearrowright$$

$$H_A = \frac{5}{6} q a - q a = \underline{\underline{-\frac{q a}{6}}}$$

equilibrio horizontal ok

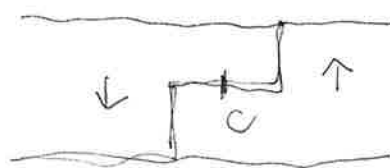
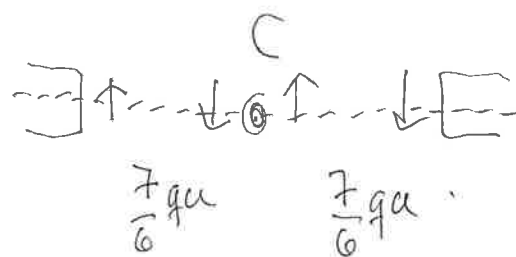
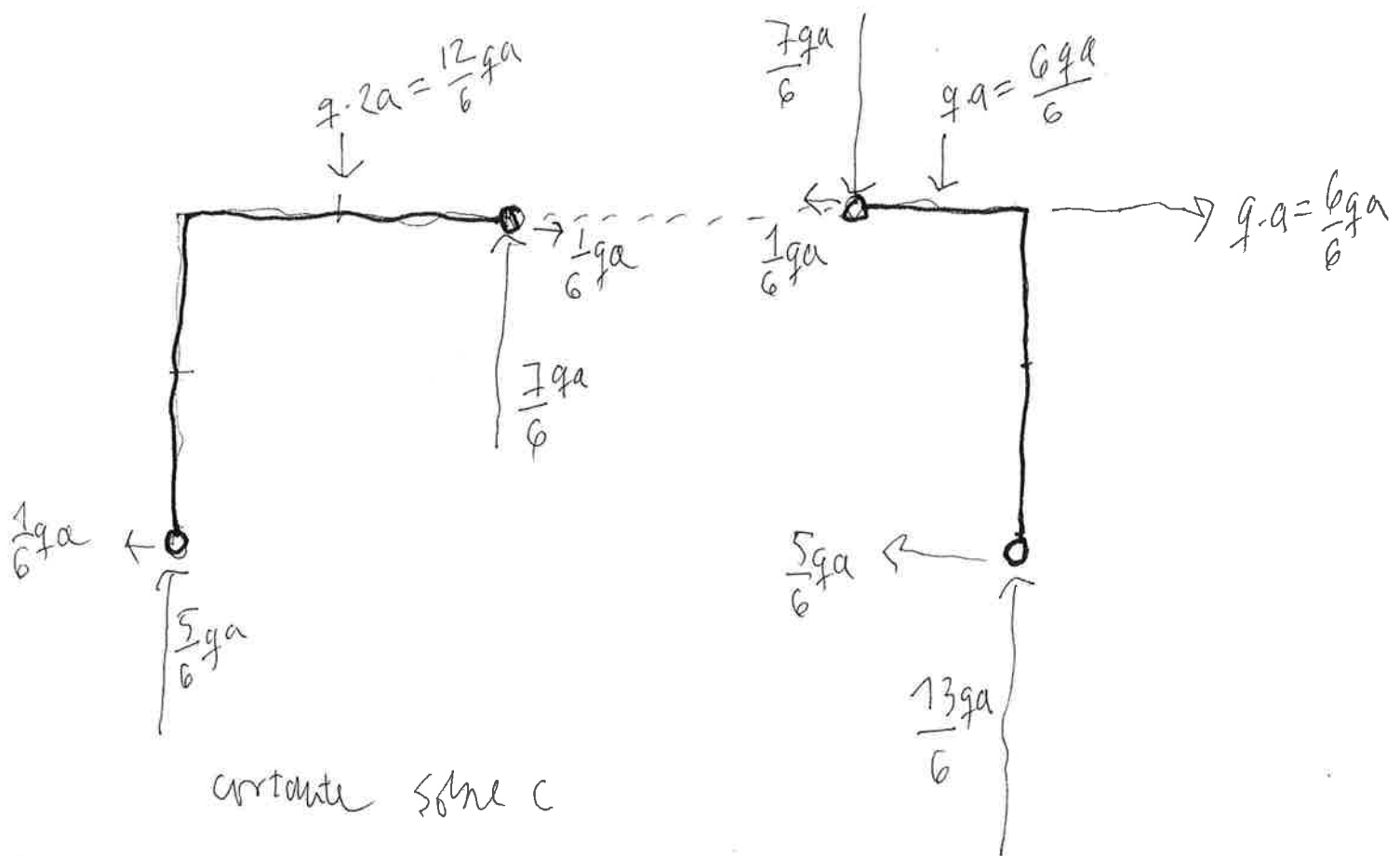


$$\sum M_C = 0 \quad + \curvearrowright$$

$$0 = H_B \cdot 2a + \frac{13}{6} q a^2 - q a^2$$

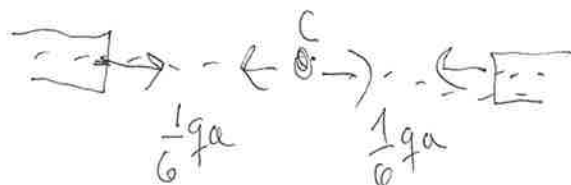
$$H_B = \underline{\underline{-\frac{5}{6} q a}}$$

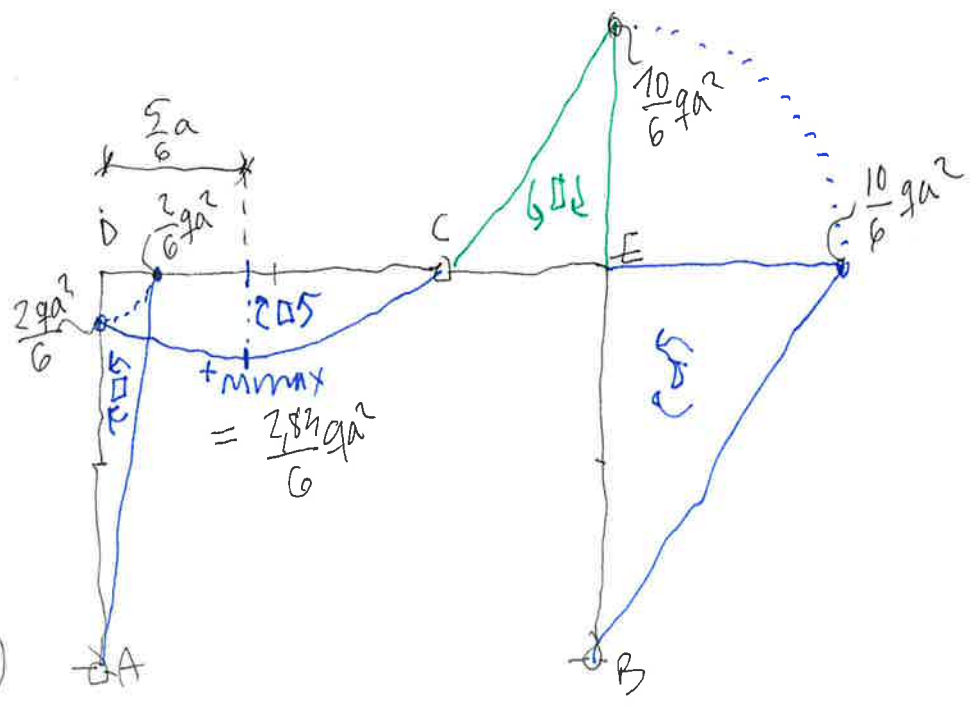
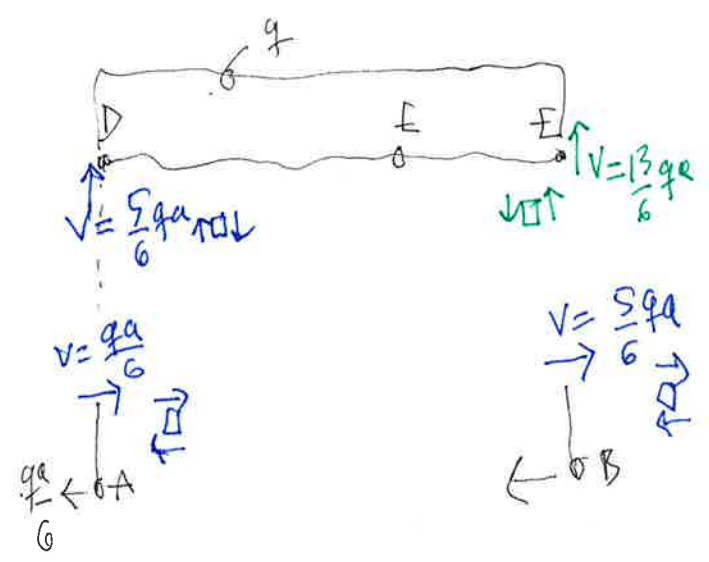
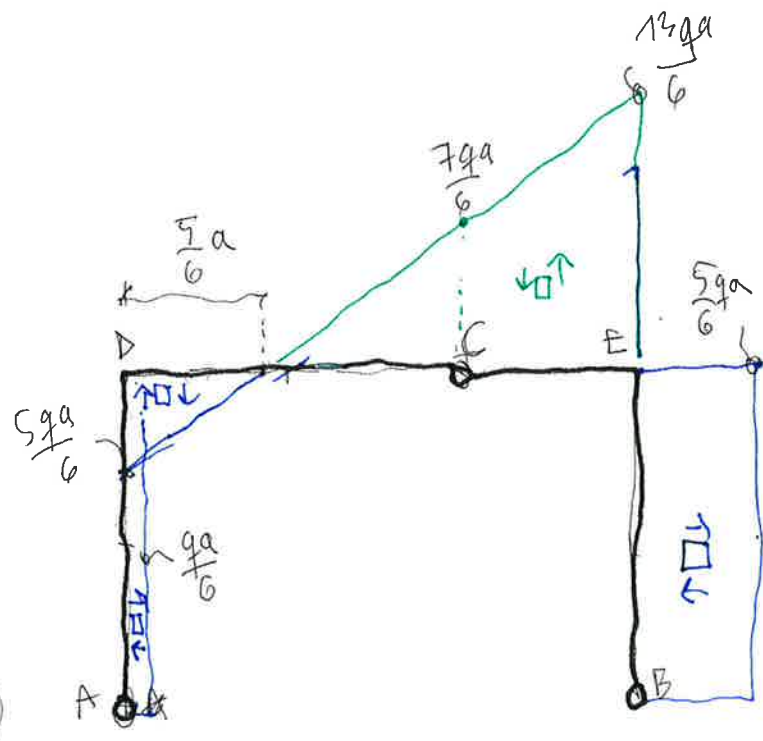
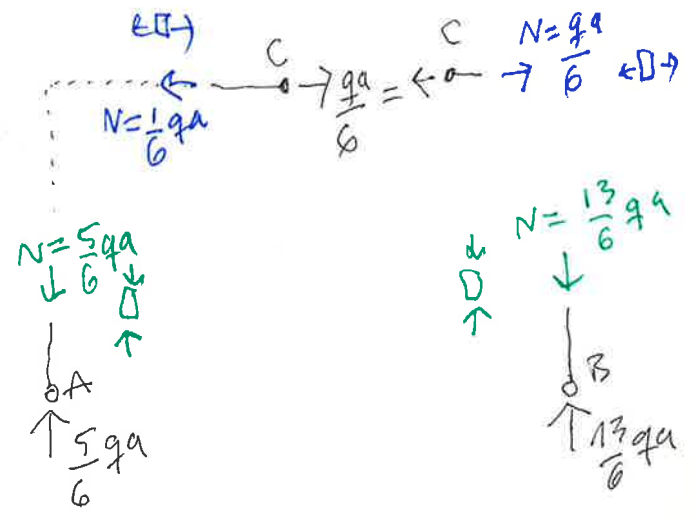
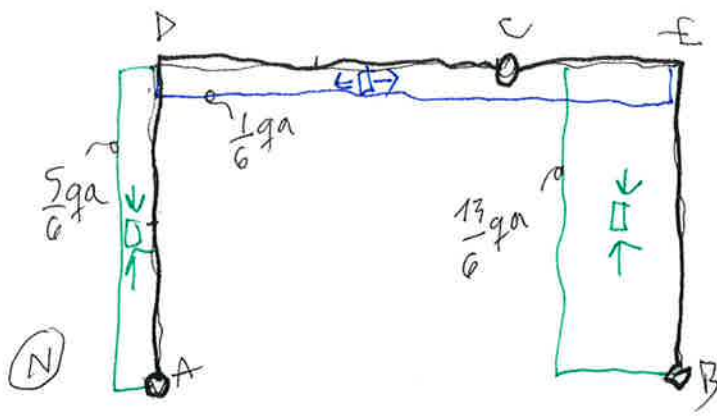
esfuerzos en la articulación central C



valoría media máxima de este modo.

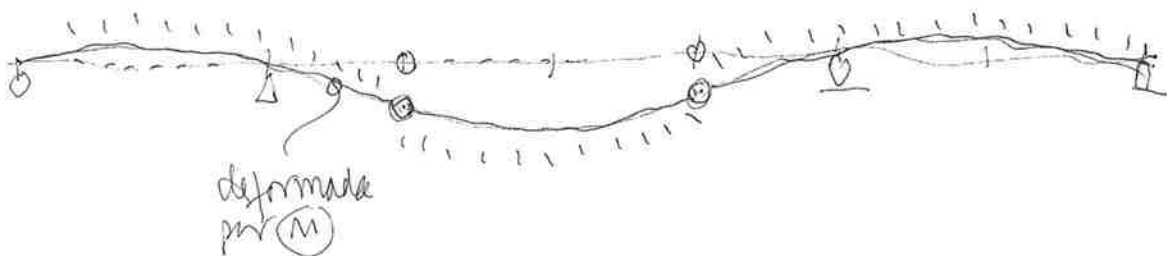
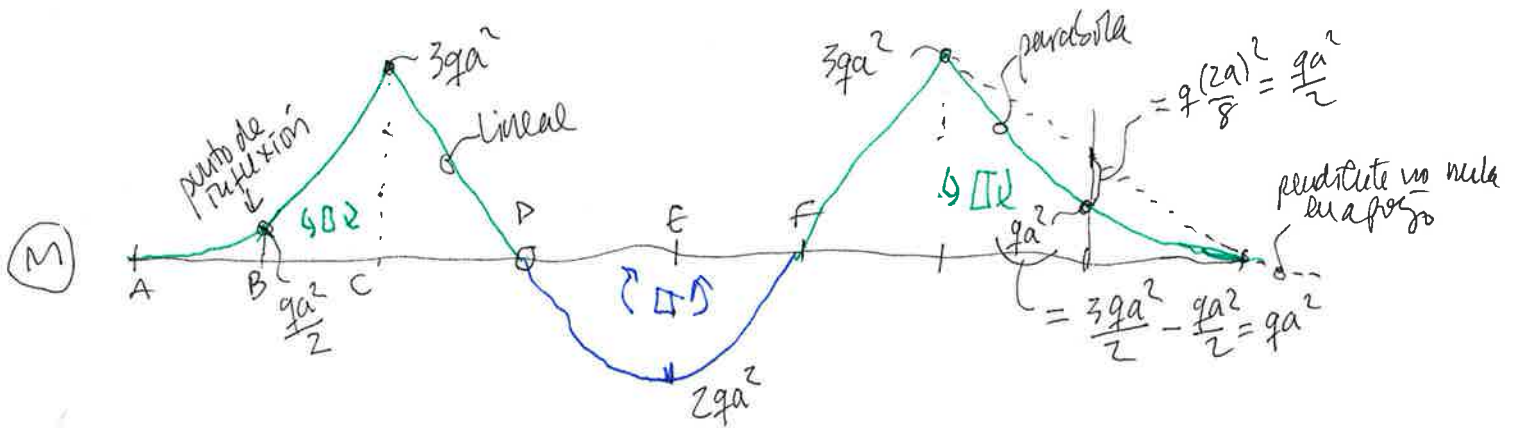
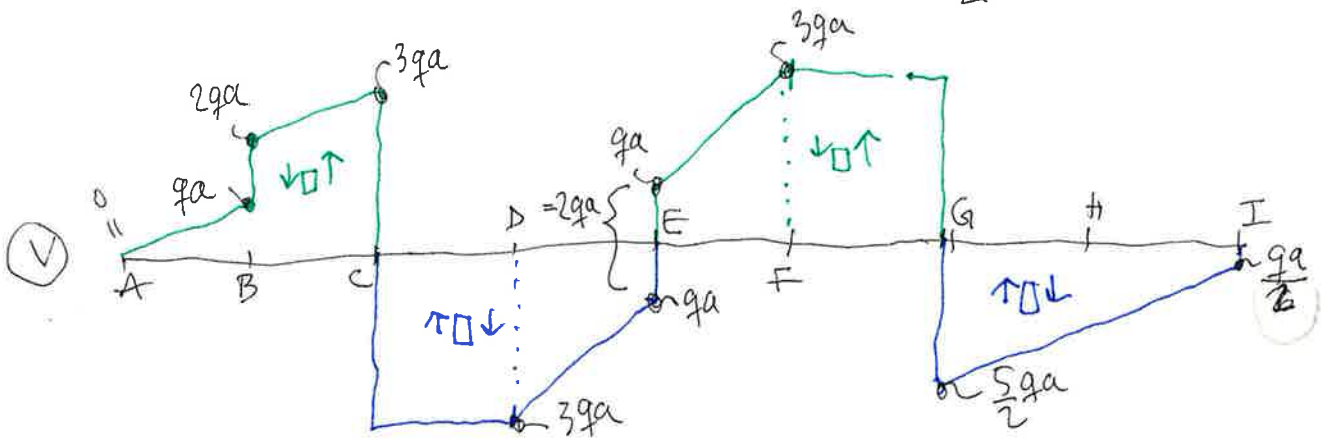
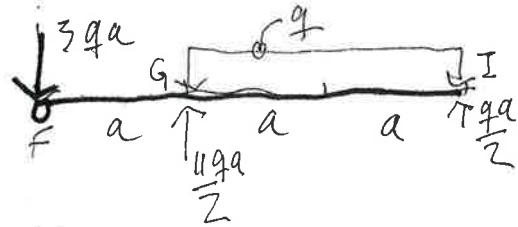
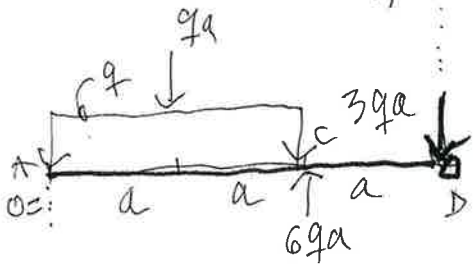
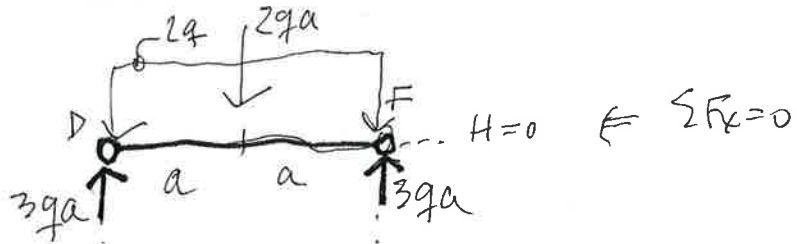
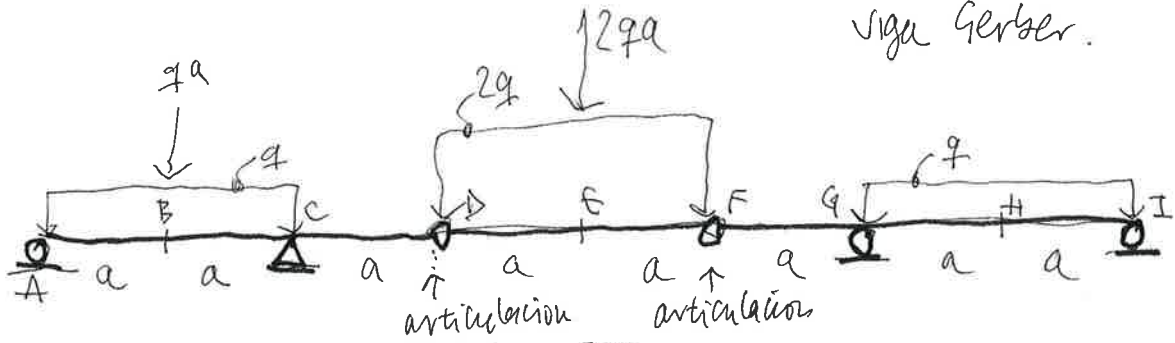
pero hay tracción también sobre ella

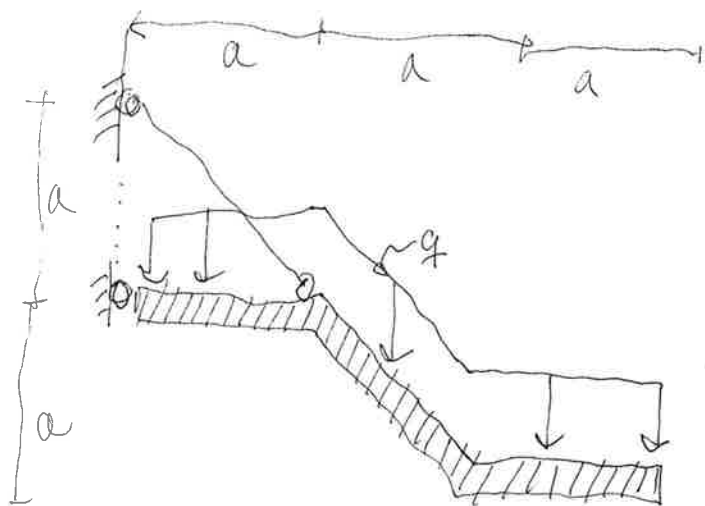




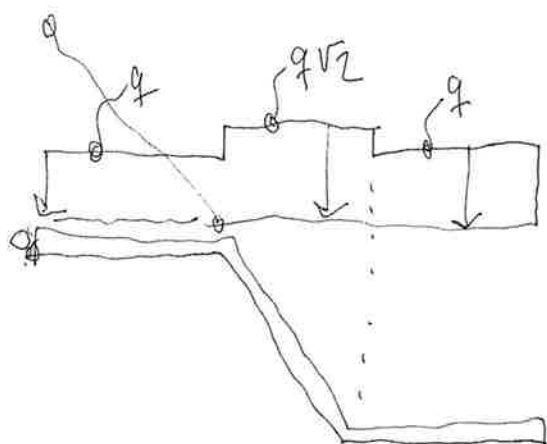
(M)

viga Gerber.

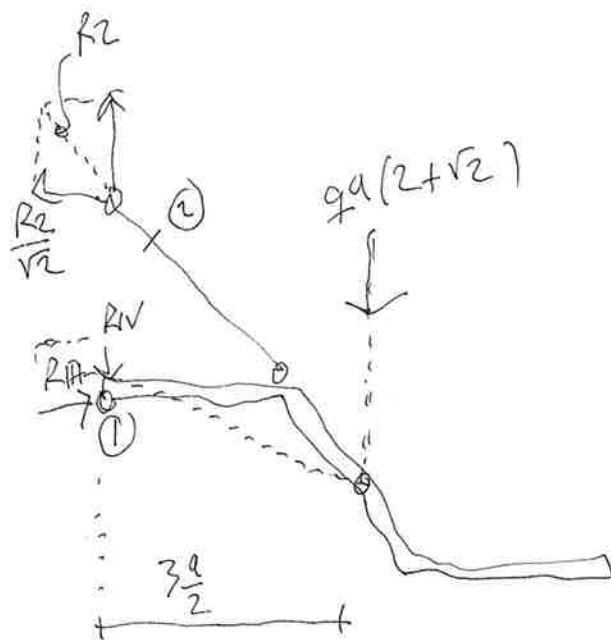




Magnetismus

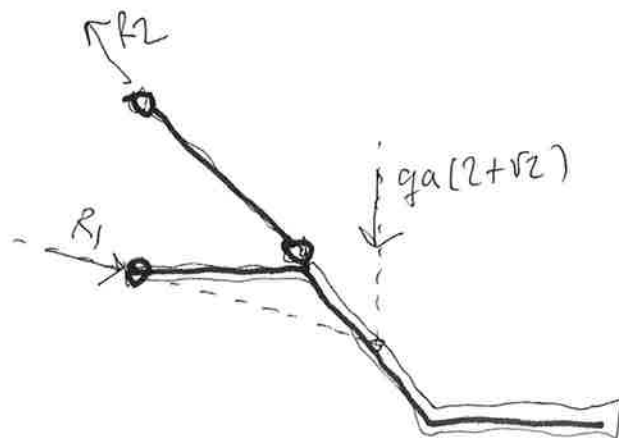
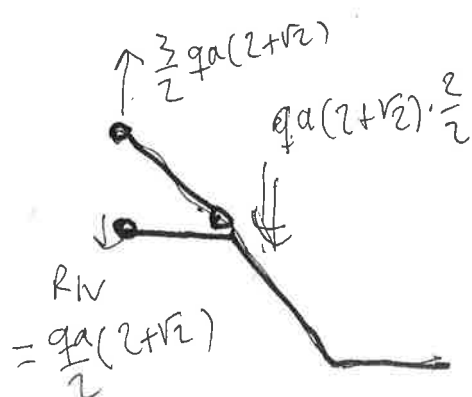


\Rightarrow

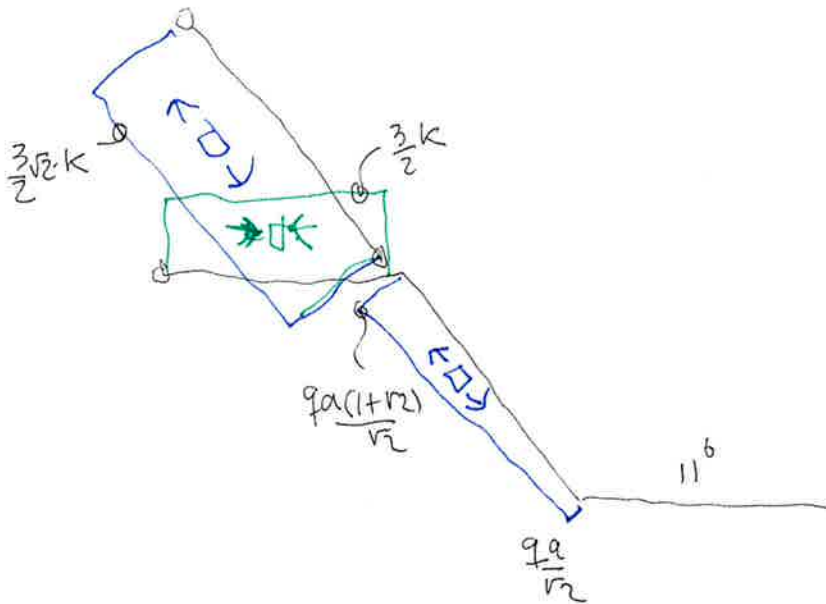


$$\sum M_O = 0 \Rightarrow R_2 = \frac{3\sqrt{2}}{2} (2 + \sqrt{2}) q \cdot a$$

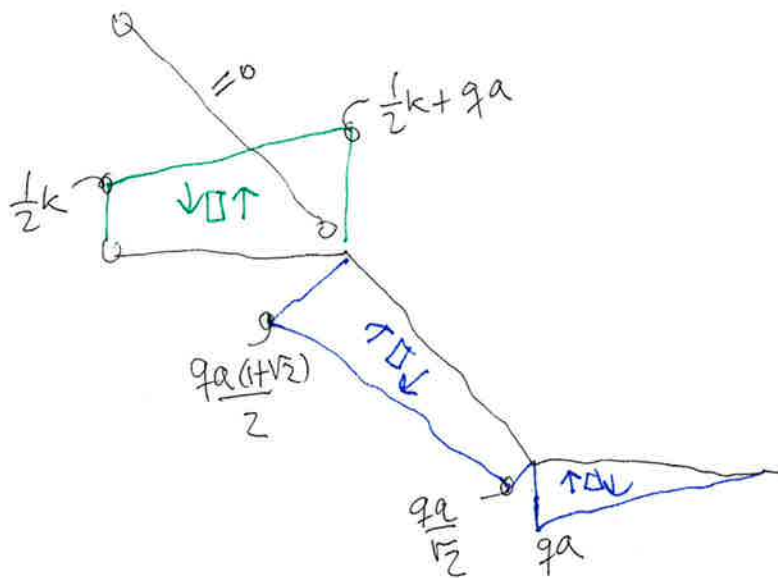
$$R_H = \frac{R_2}{\sqrt{2}} = \frac{3}{2} (2 + \sqrt{2}) q \cdot a$$



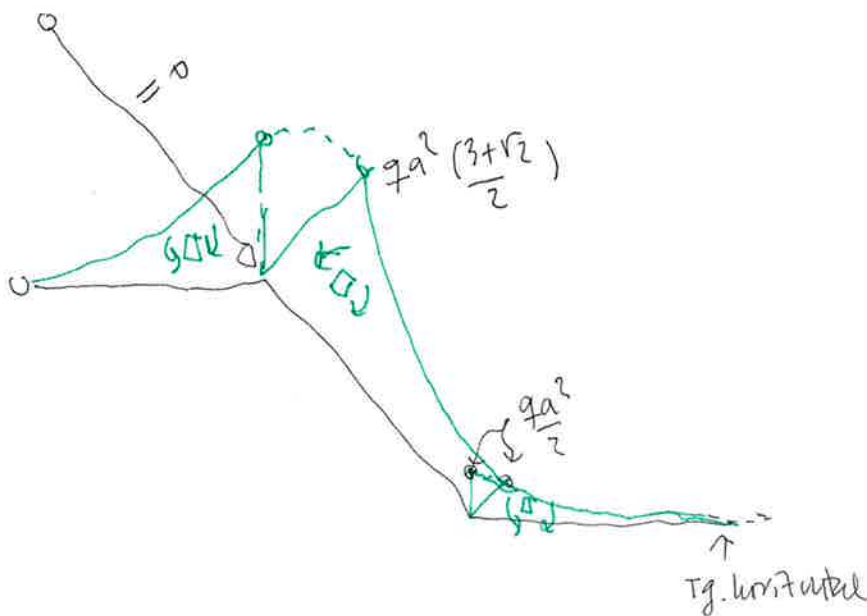
$$K = (2 + \sqrt{2})qa$$



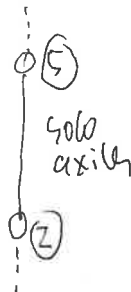
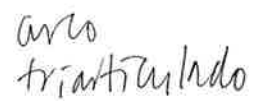
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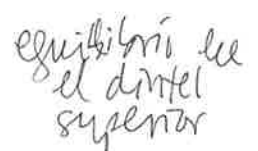
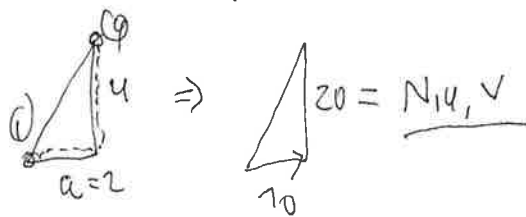
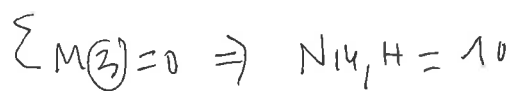
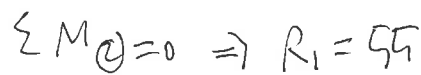
(3)

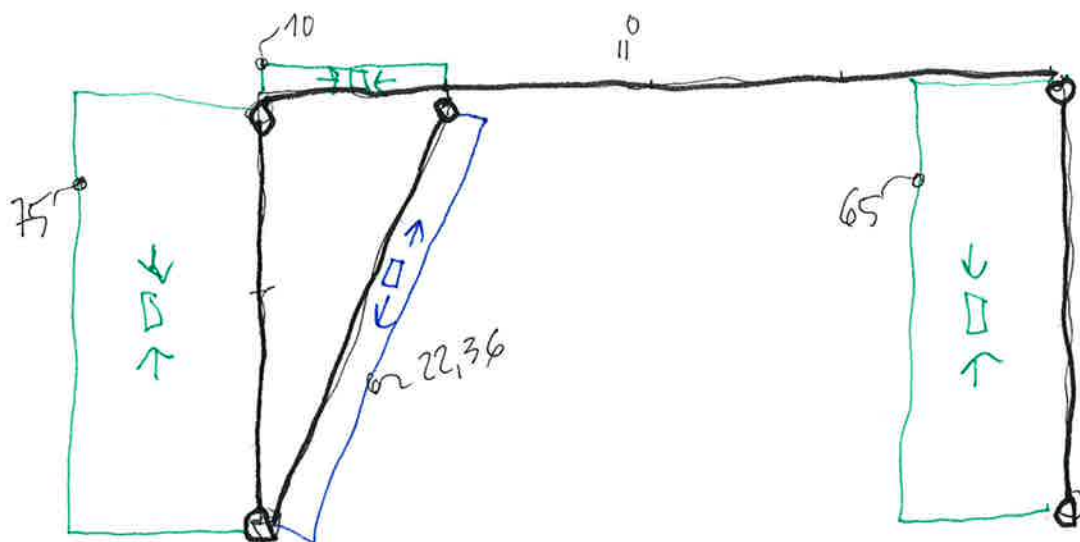


(4)

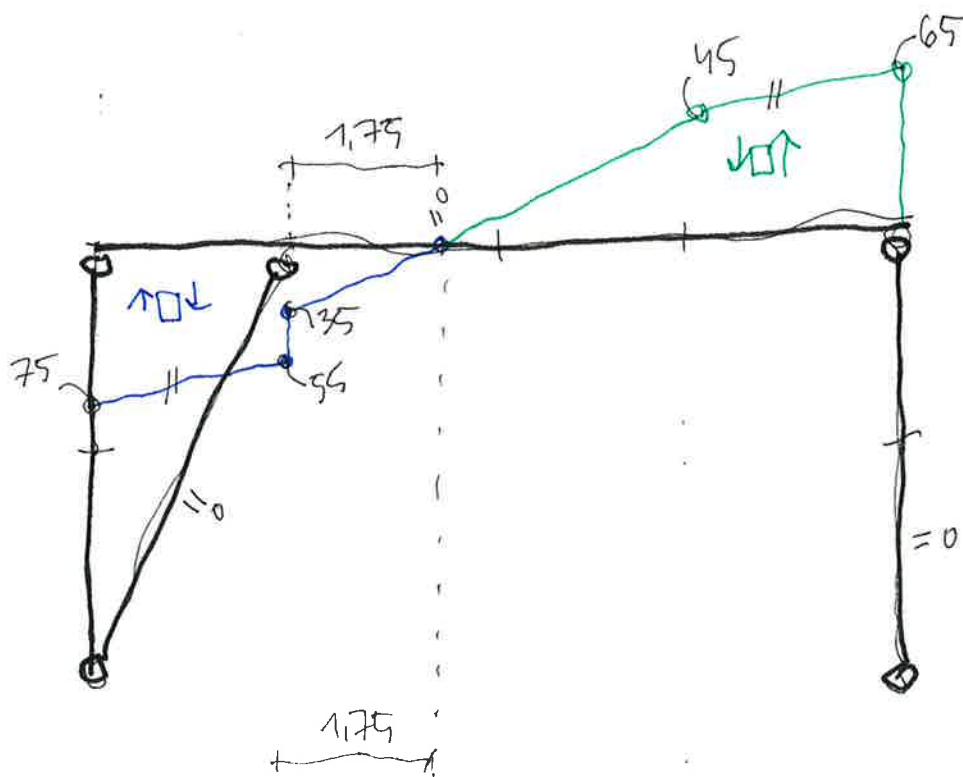


$$\Sigma M_{\odot} = 0$$
$$\Rightarrow R_2 = 65$$

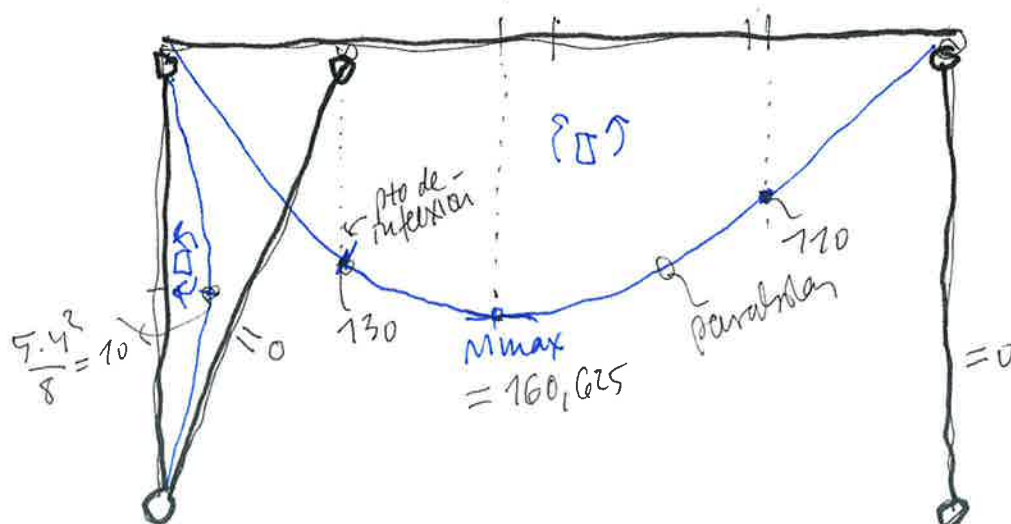




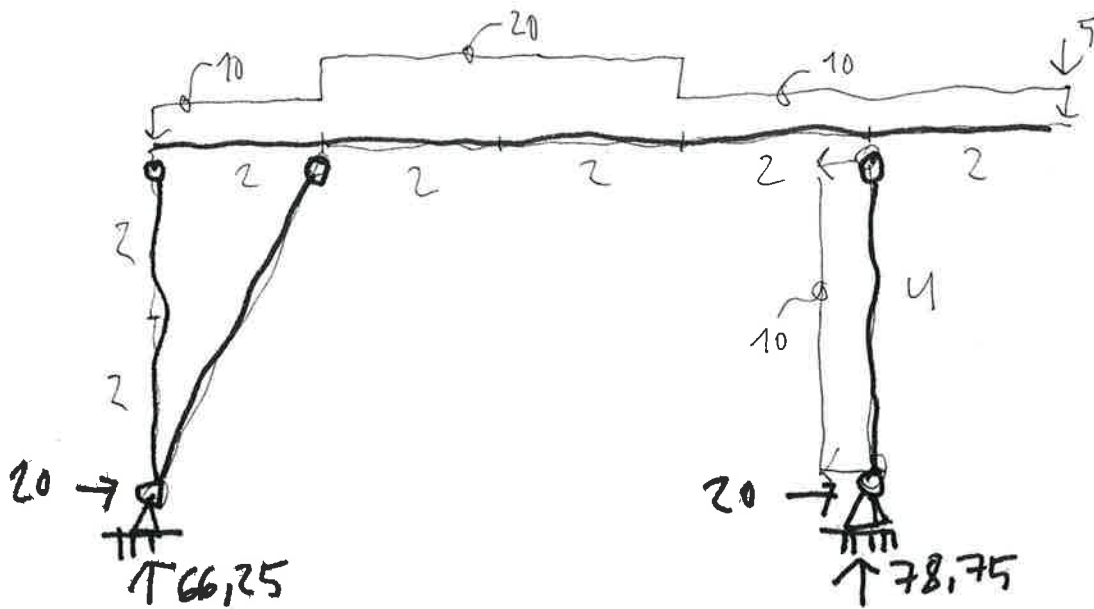
(N)



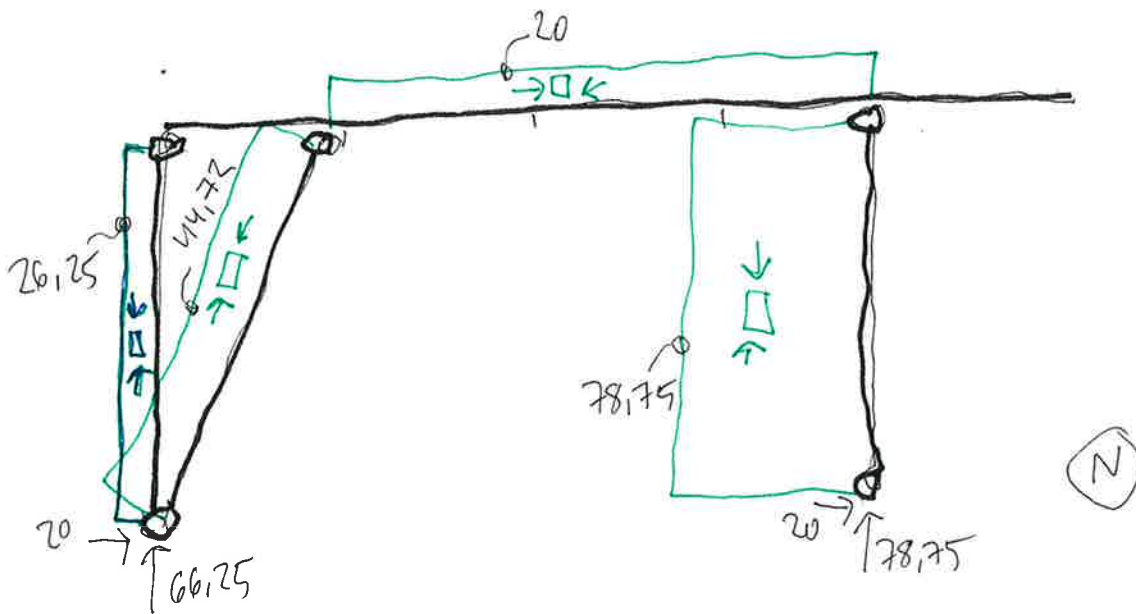
(V)



(M)

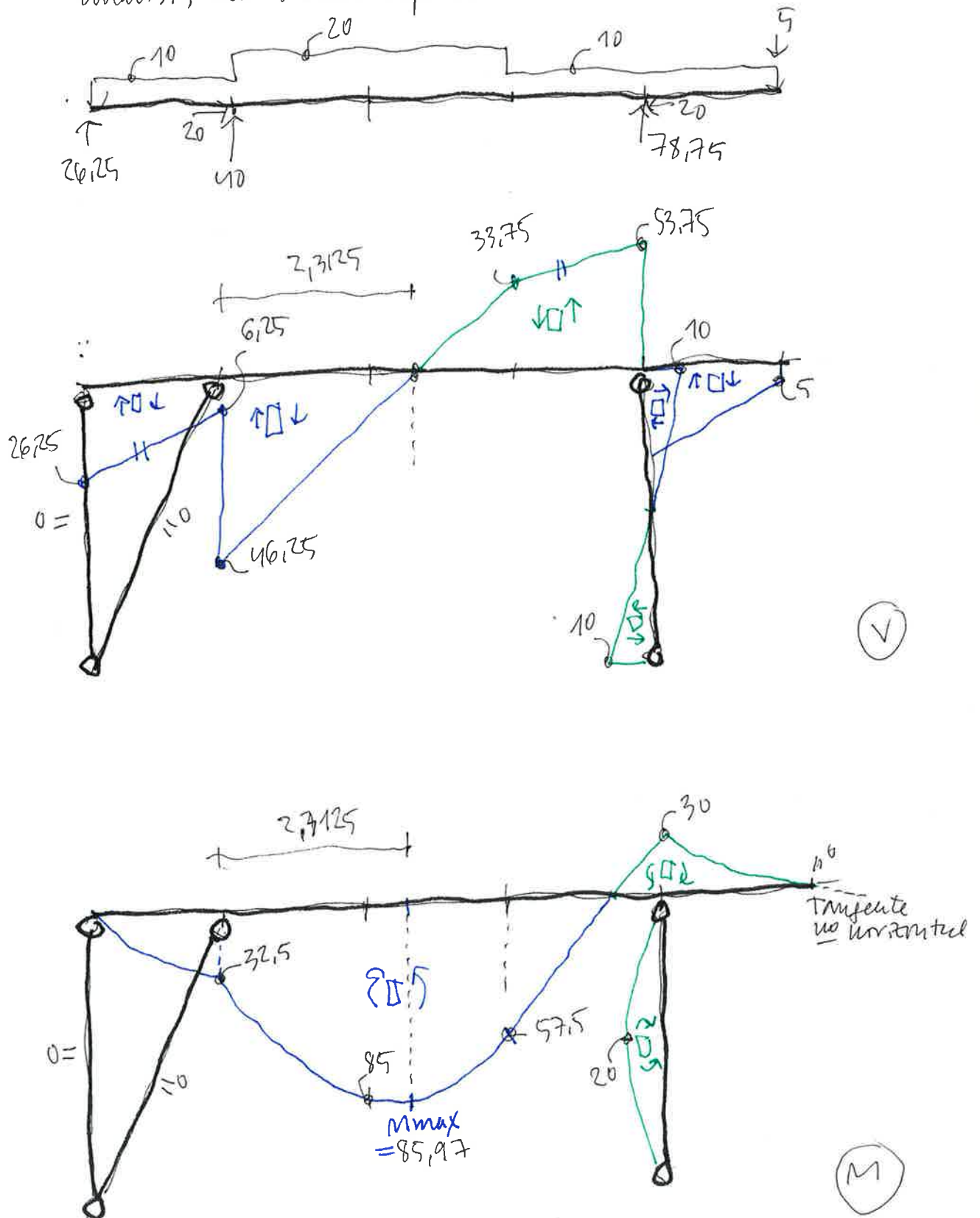


no
fuerza de tracción.



el método para obtener reacciones
y normales es idéntico al caso anterior

análisis del dintel superior



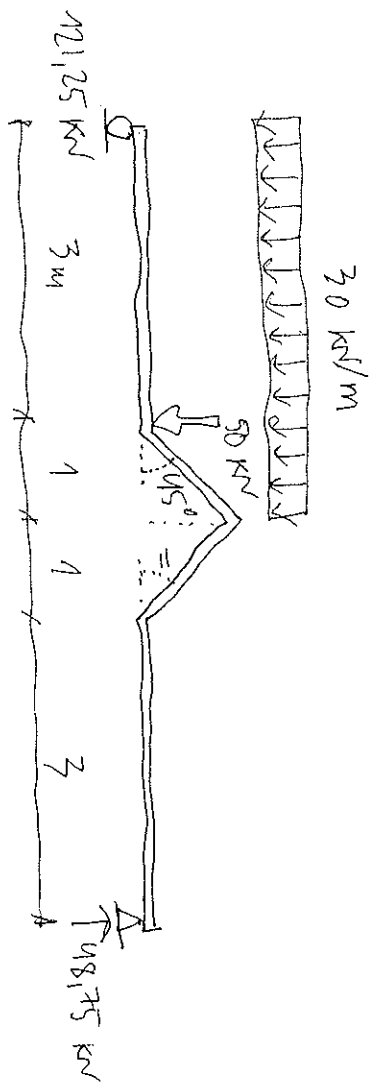
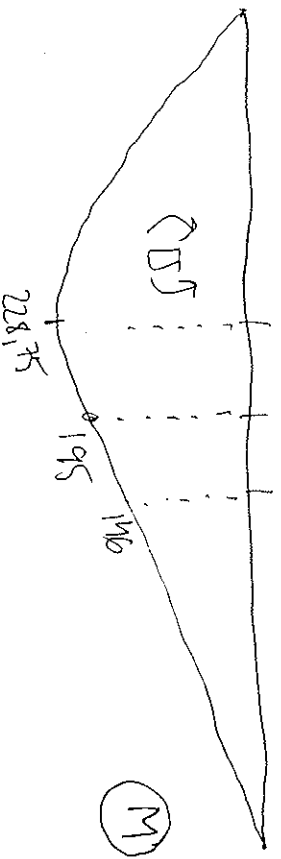
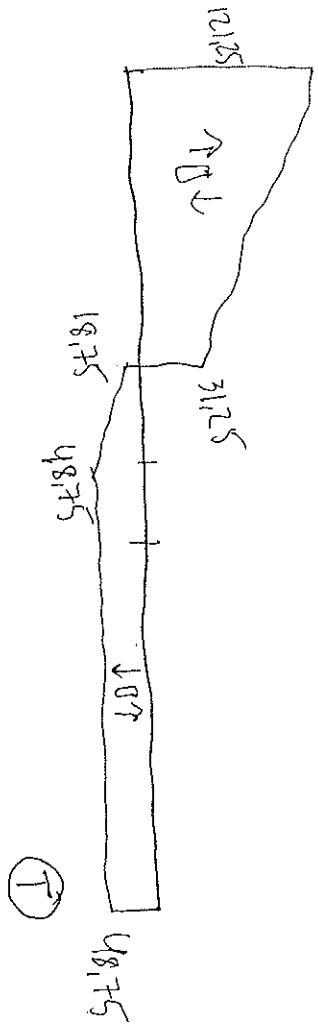
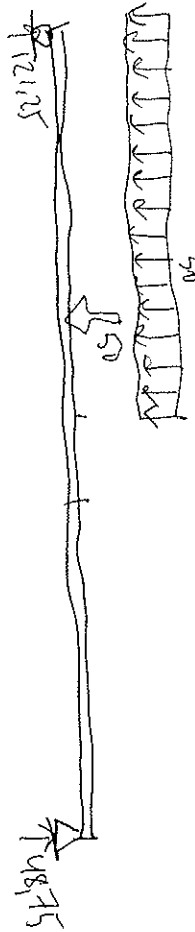
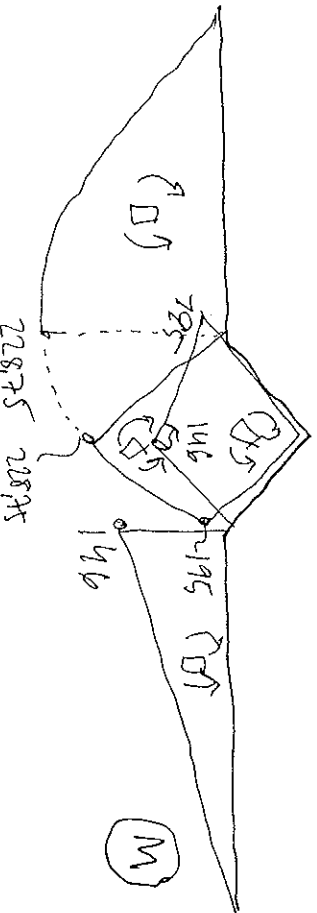
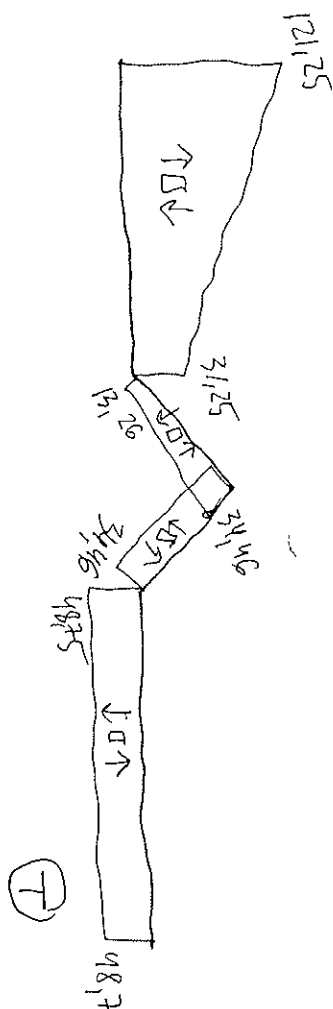


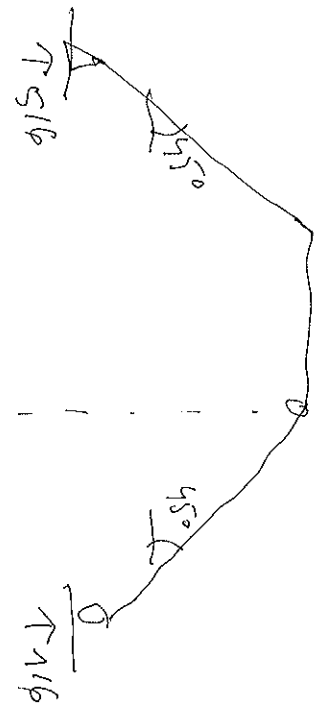
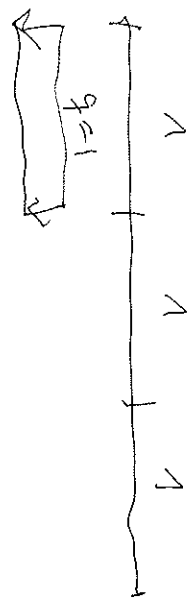
Diagramme de la vige hypergeode de repartition



J. CABO
2007.10
A10 / 10



$\Delta 11/30$

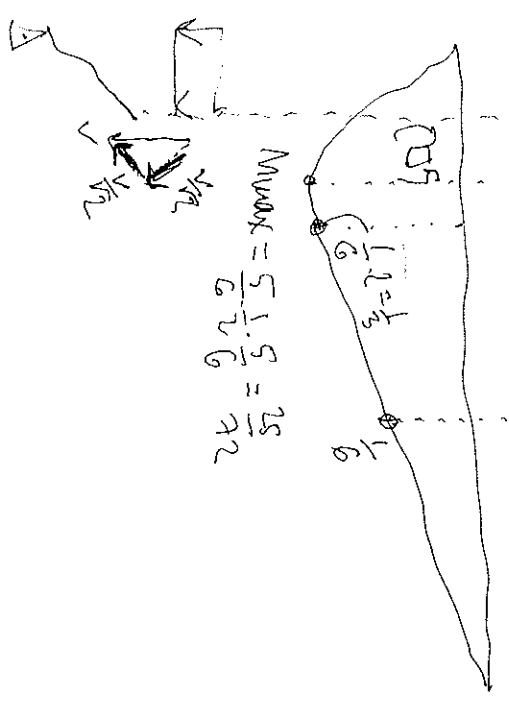


lewis viga

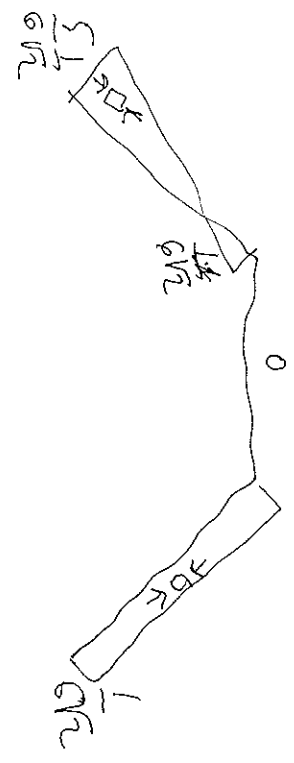
Repluma

V

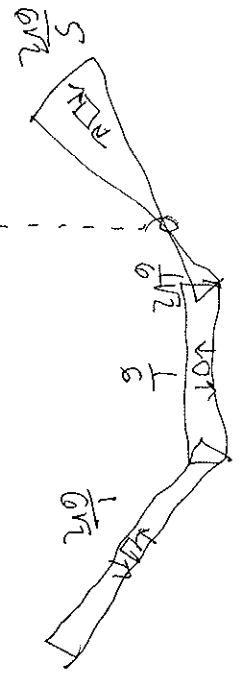
M



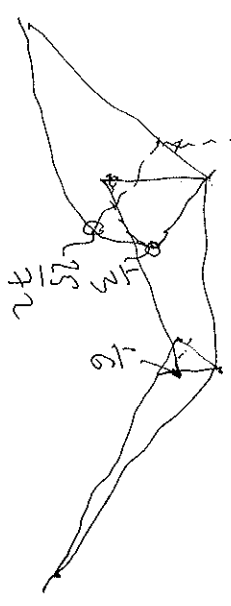
$$M_{max} = \frac{5}{6} \cdot \frac{1}{6} \cdot 3 = \frac{25}{72}$$



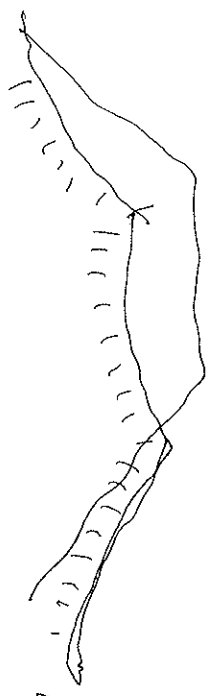
N



V

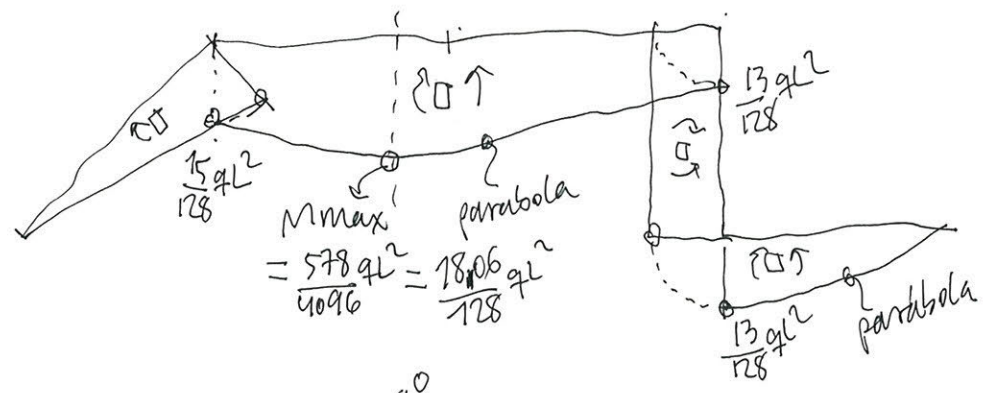
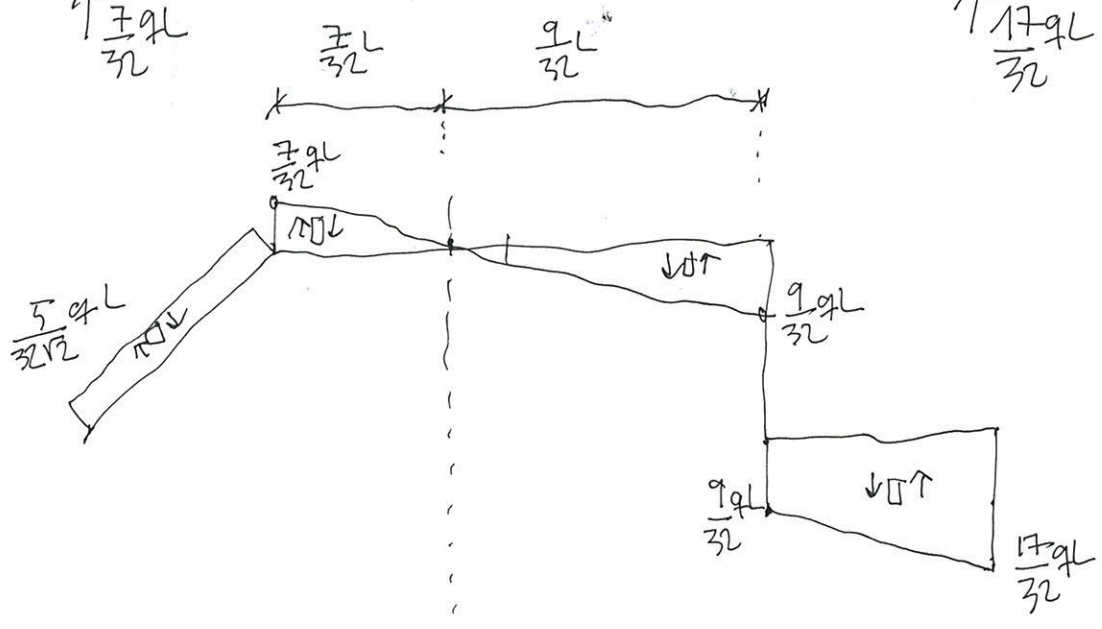
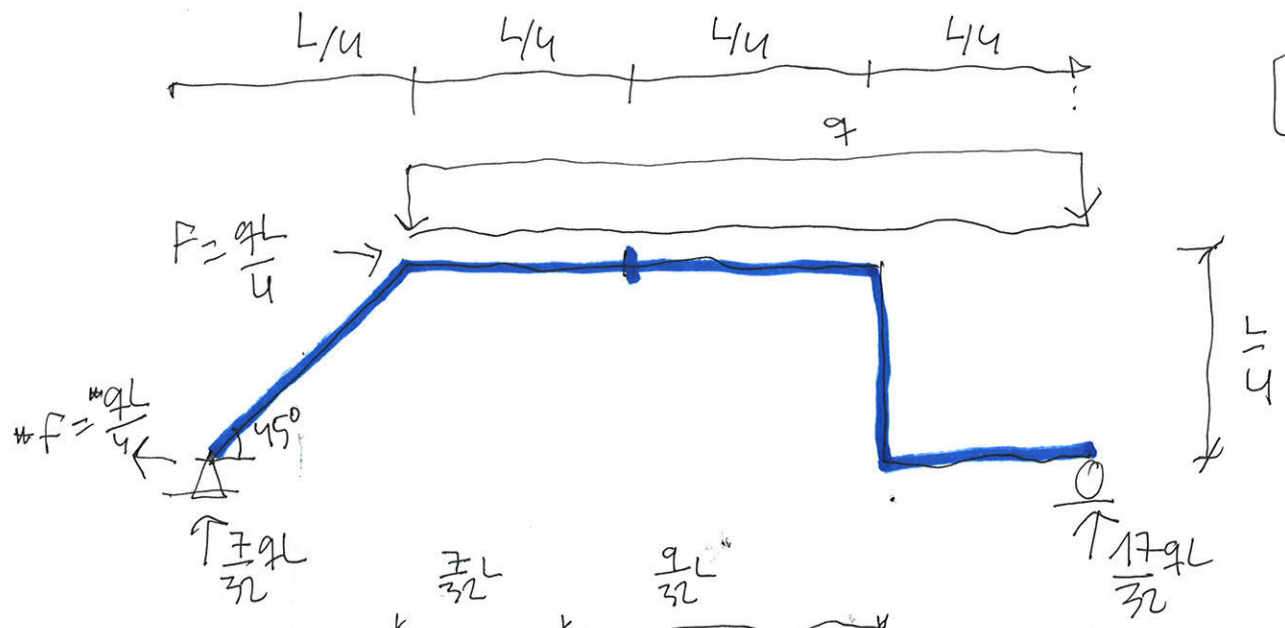


M

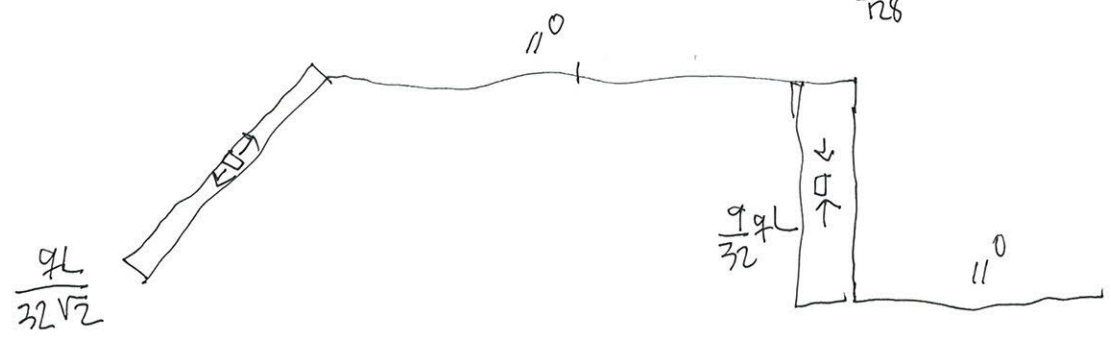


deform

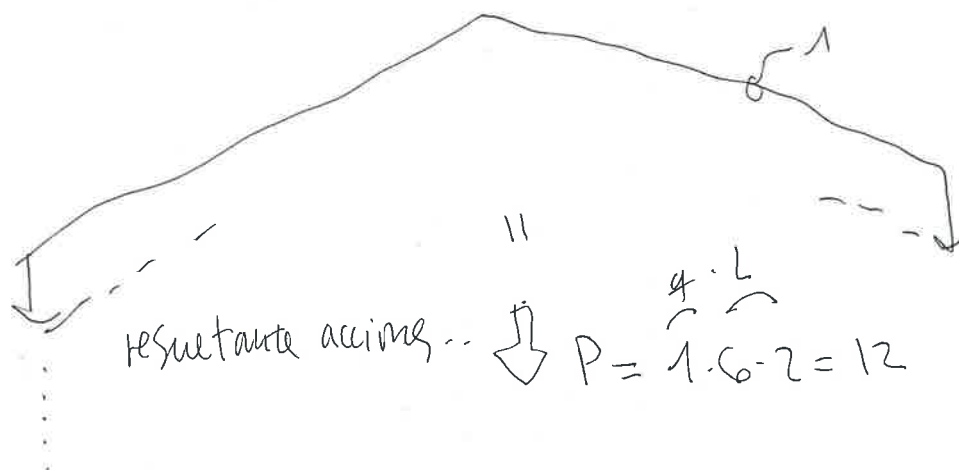
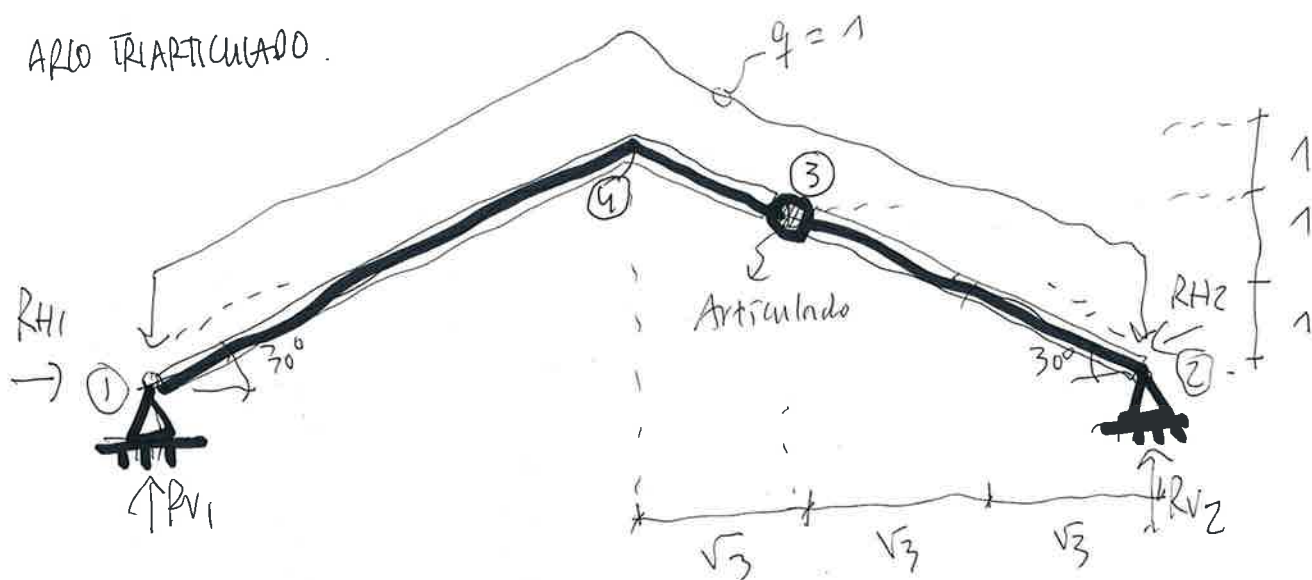
tracing can be seen



M_{max}
 $= \frac{578qL^2}{4096} = \frac{18.06}{128} qL^2$



ARCO TRIARTICULADO.



$$RV1 \uparrow = \frac{12}{2} = 6$$

las reacciones
Verticales son
independientes de
empuje

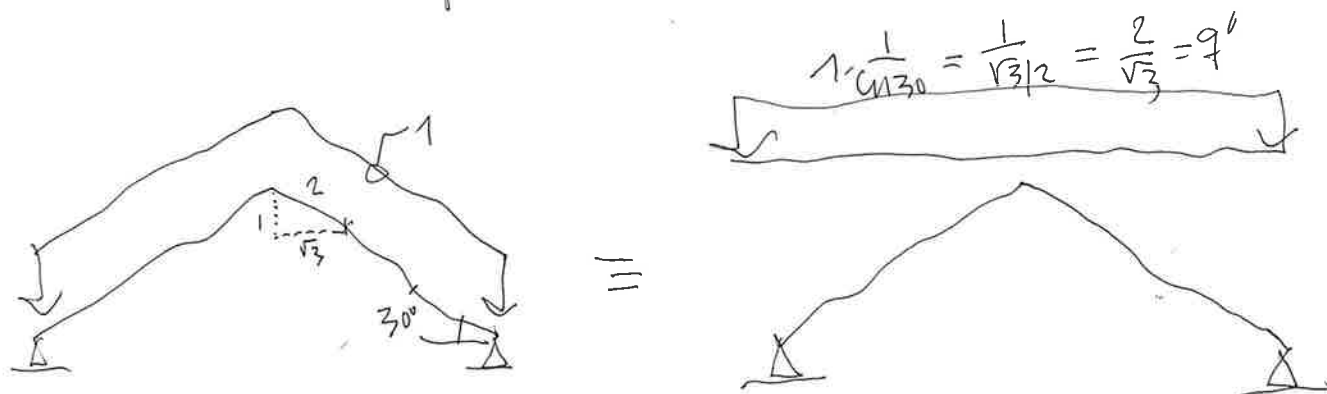
$$\left\{ \begin{array}{l} \uparrow RV2 \\ = \frac{12}{2} = 6 \end{array} \right.$$

en general, considerando $H=H'$ según la dirección que
me en arcos, $RV1$ y $RV2$
son también independientes
del empuje H' .

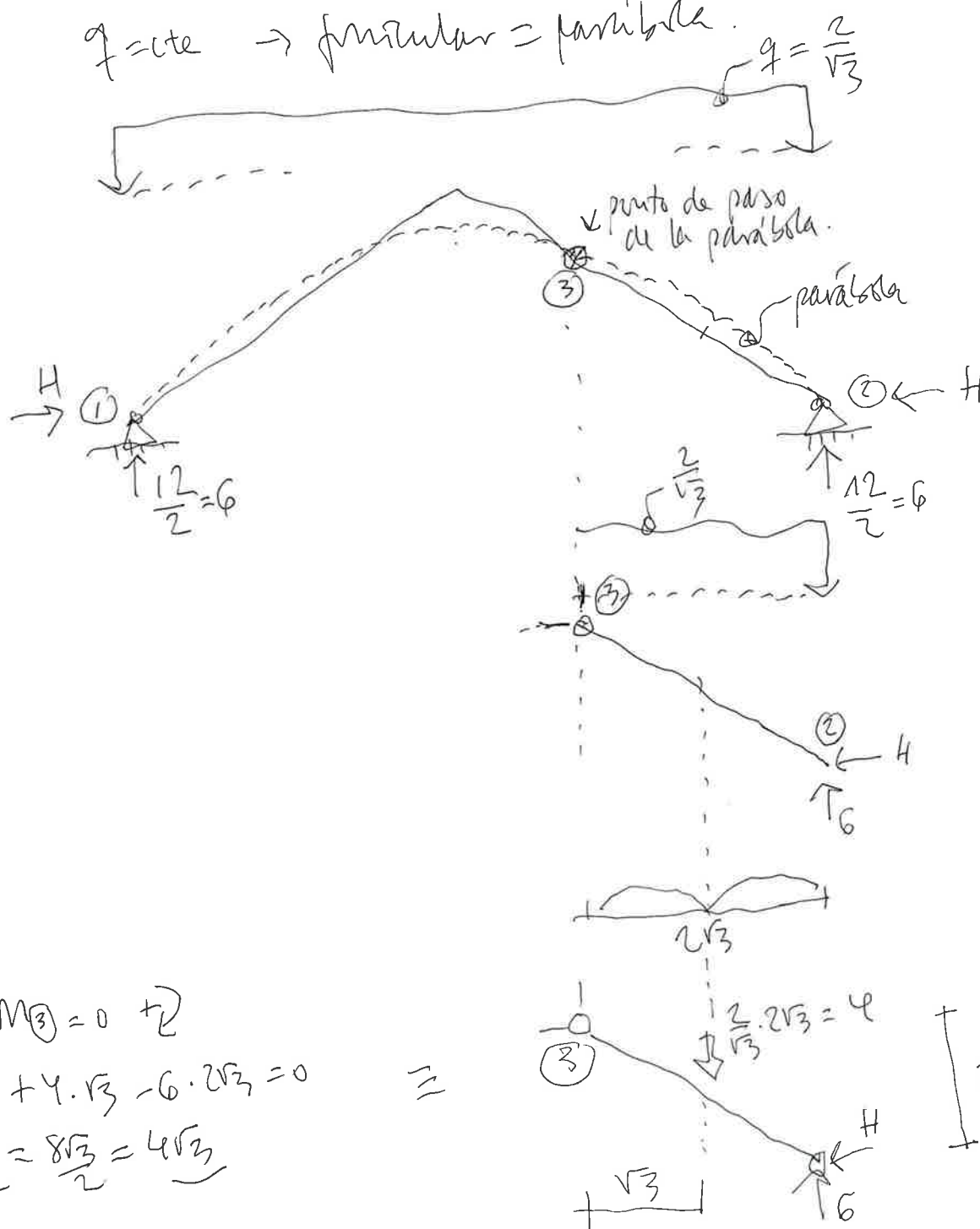


Si se proyecta la curva horizontalmente la visualiza mejor la solución.

2



$q = \text{cte} \rightarrow \text{función} = \text{parábola}$

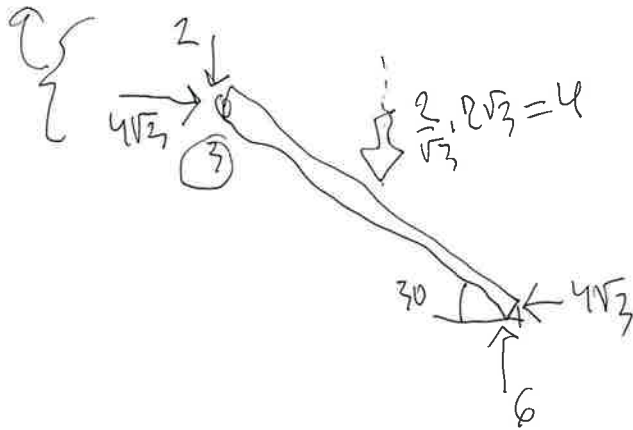


$$\sum M_3 = 0 + \curvearrowright$$

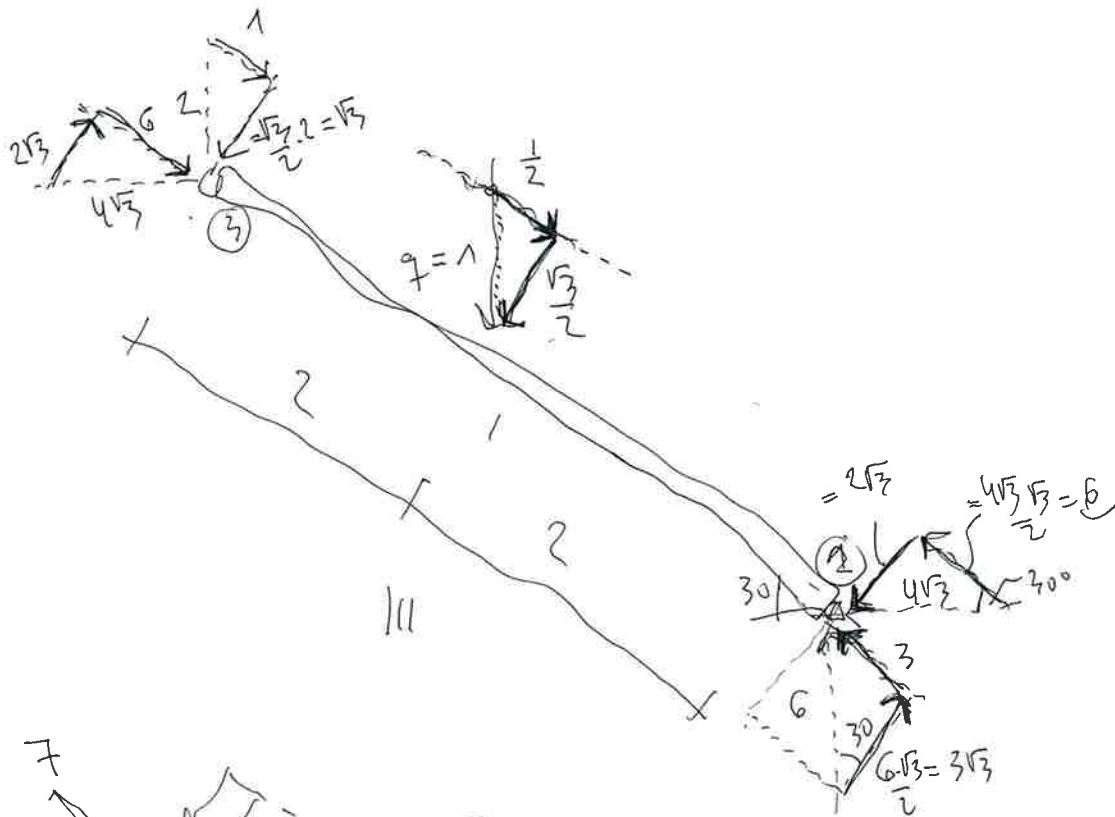
$$H \cdot 2 + 4 \cdot \sqrt{3} - 6 \cdot 2\sqrt{3} = 0$$

$$H = \frac{8\sqrt{3}}{2} = 4\sqrt{3}$$

2 forces en ③

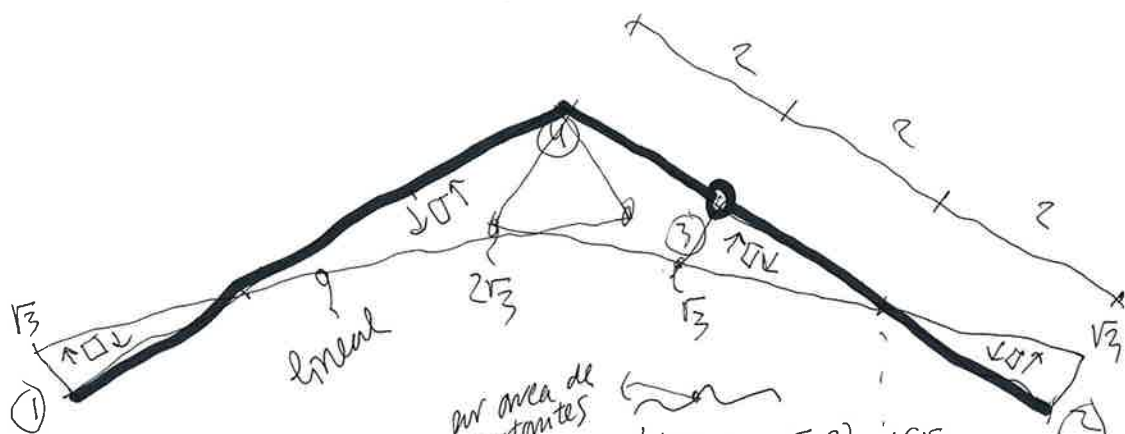
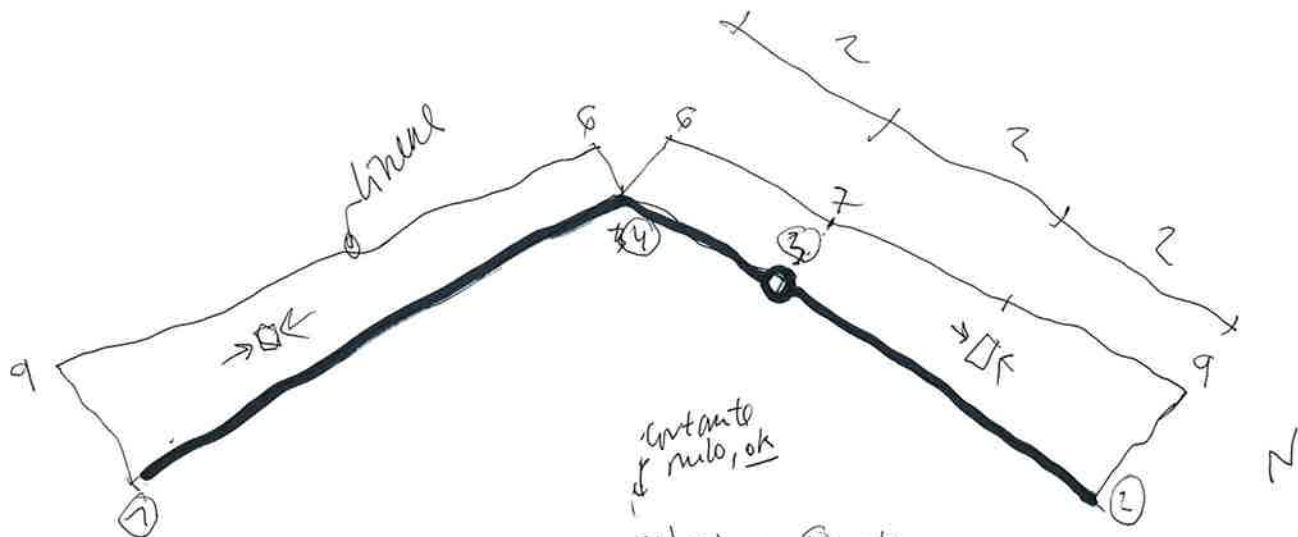


décomposer selon la direction de la barre.



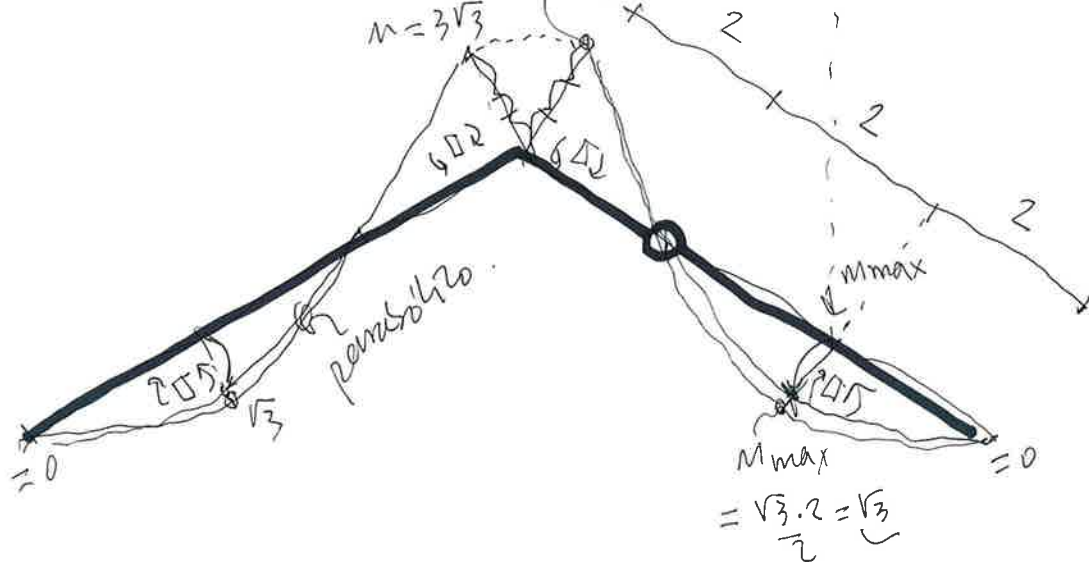
$$\left. \begin{array}{l} \sum F_{x'} = 0 \\ 7 + \frac{1}{2} \sqrt{3} = 9 \\ \text{ok} \end{array} \right\} \text{"gene"}$$

$$\left. \begin{array}{l} \sum F_{y'} = 0 \\ \frac{\sqrt{3}}{2} \cdot 2 = \sqrt{3} \\ \text{ok} \end{array} \right\}$$

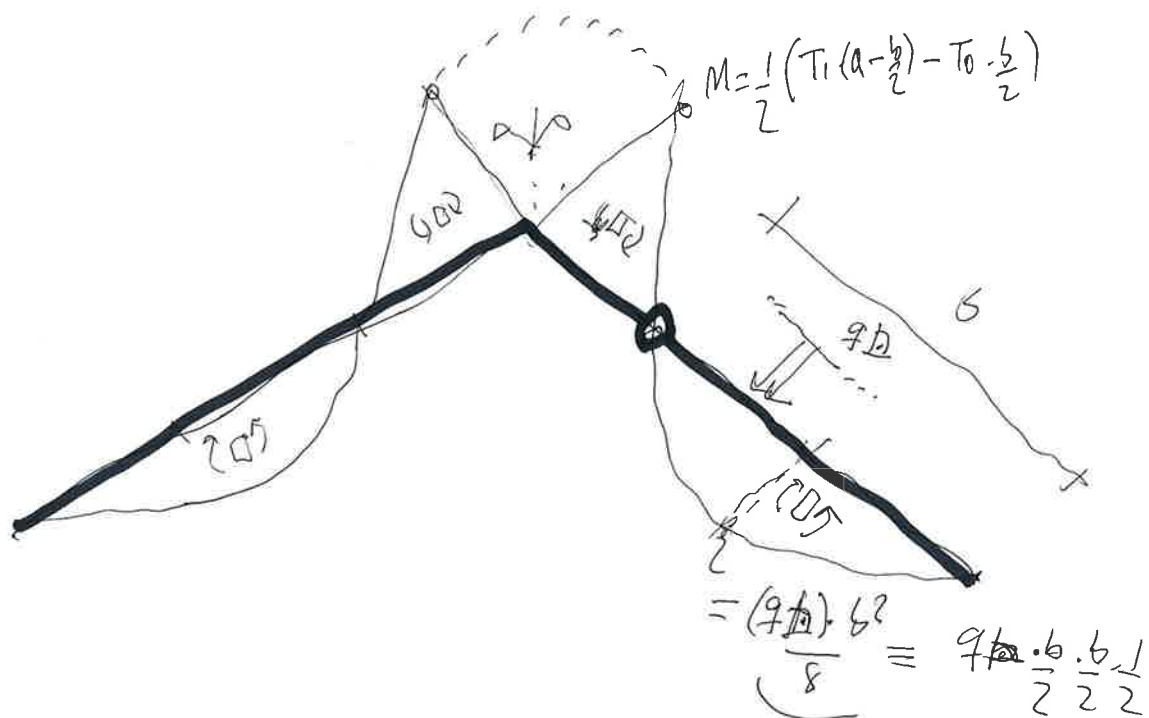
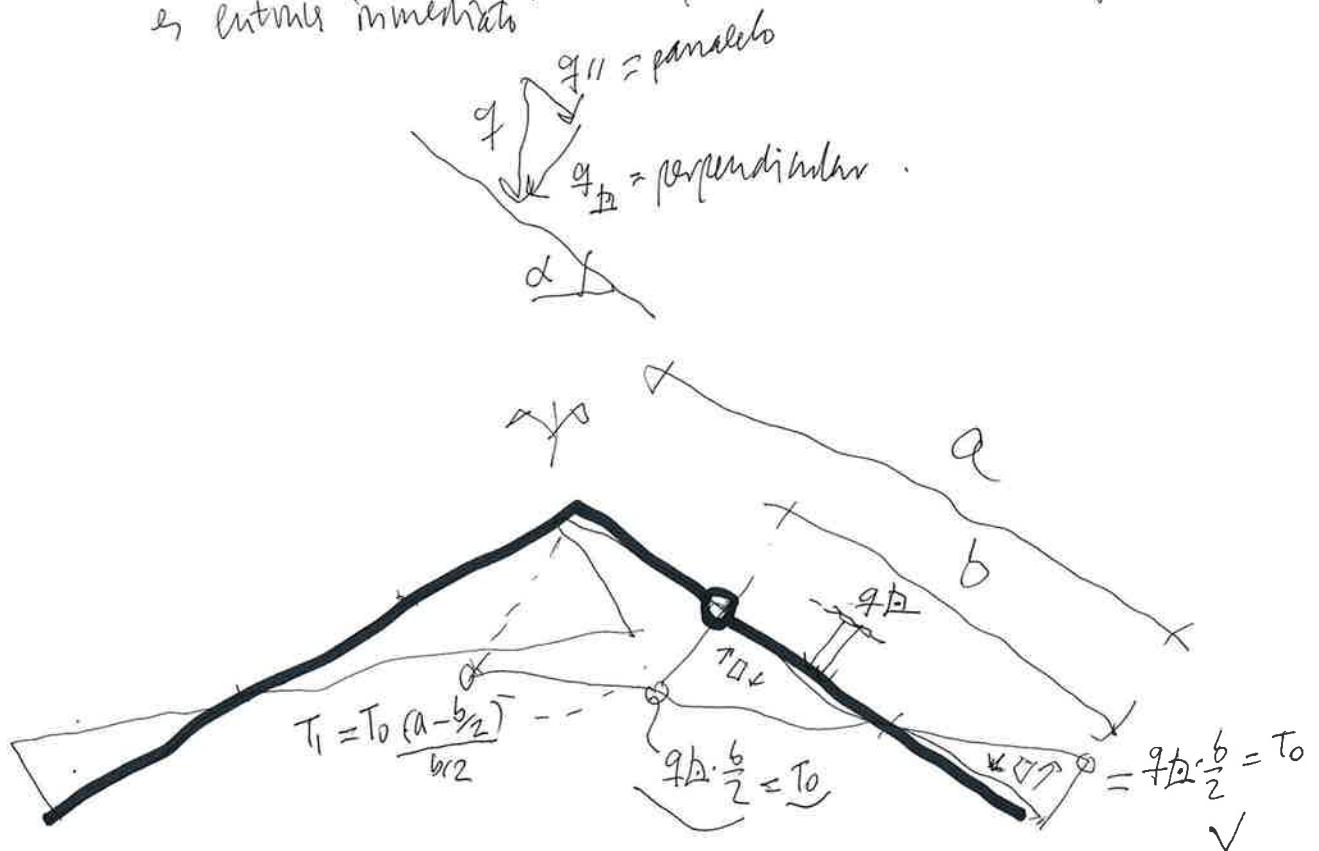


por area de constantes

$$M = \frac{1}{2} (2\sqrt{3} \cdot 4 - \sqrt{3} \cdot 2) = \frac{1}{2} (8\sqrt{3} - 2\sqrt{3}) = \frac{6\sqrt{3}}{2} = 3\sqrt{3}$$



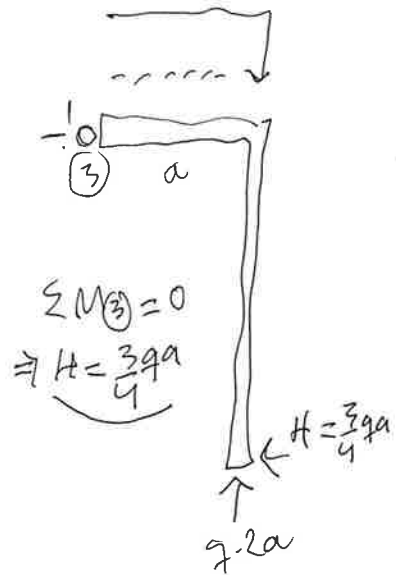
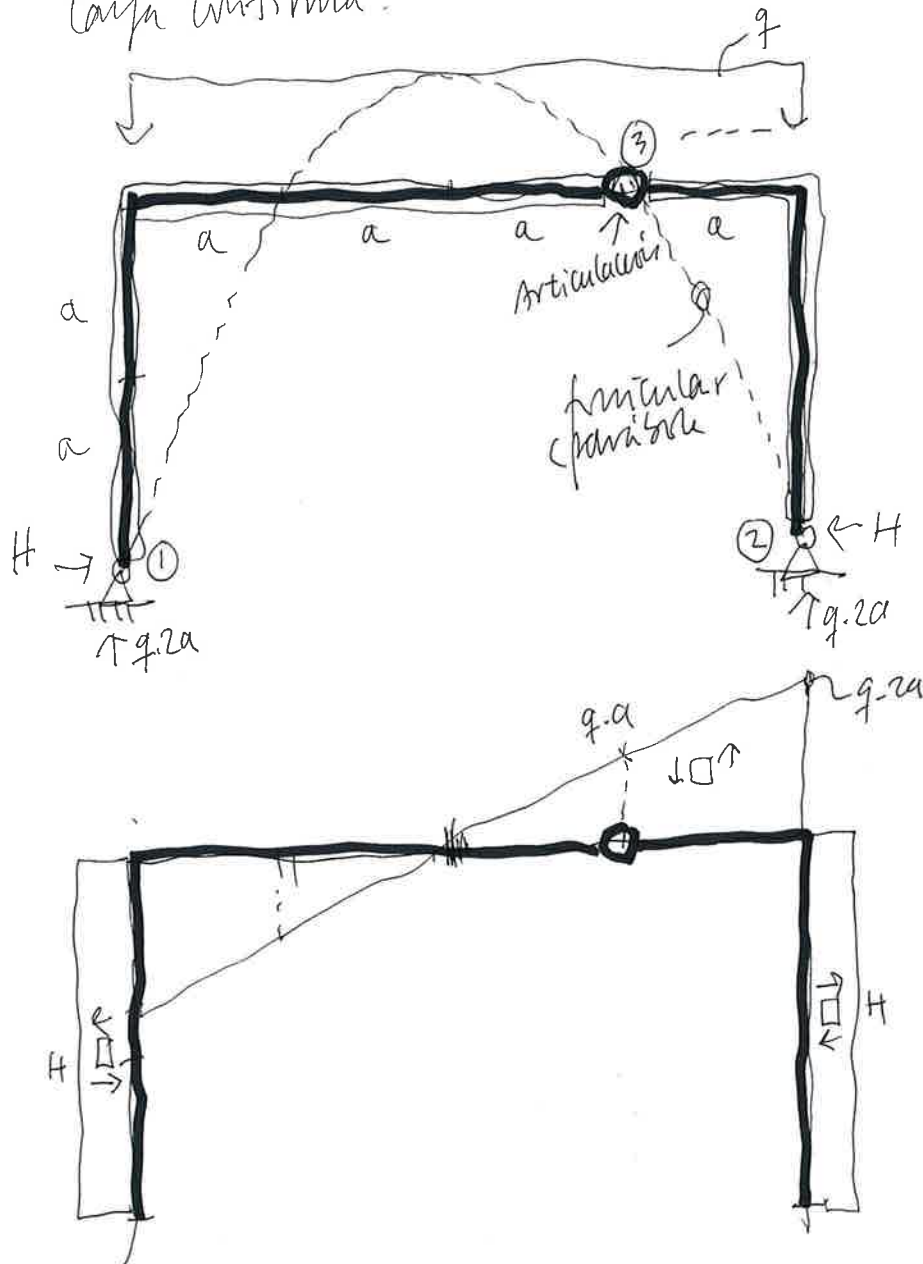
dada la simetría, el proceso para obtener los diagramas es entóns inmediato



y por tanto \checkmark y M son función de q_{\perp} y de la posición de la rótula.

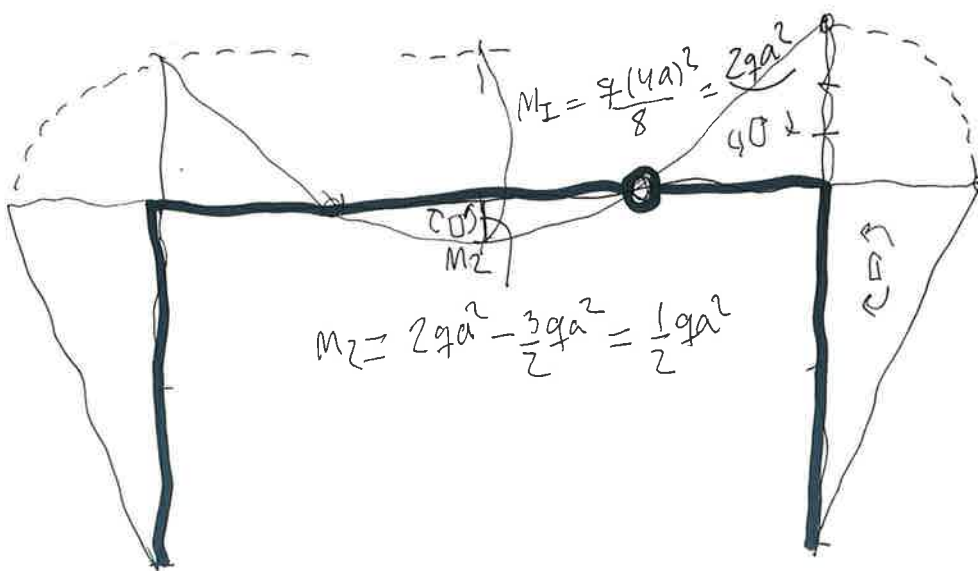
el normal depende del empuje que a su vez depende del parate (canto) del arco.

de forma similar, con otra geometria, pero tambien un ARCO TRARTICULADO y una carga continua.



$$\sum M_3 = 0$$

$$\Rightarrow H = \frac{3qa}{4}$$



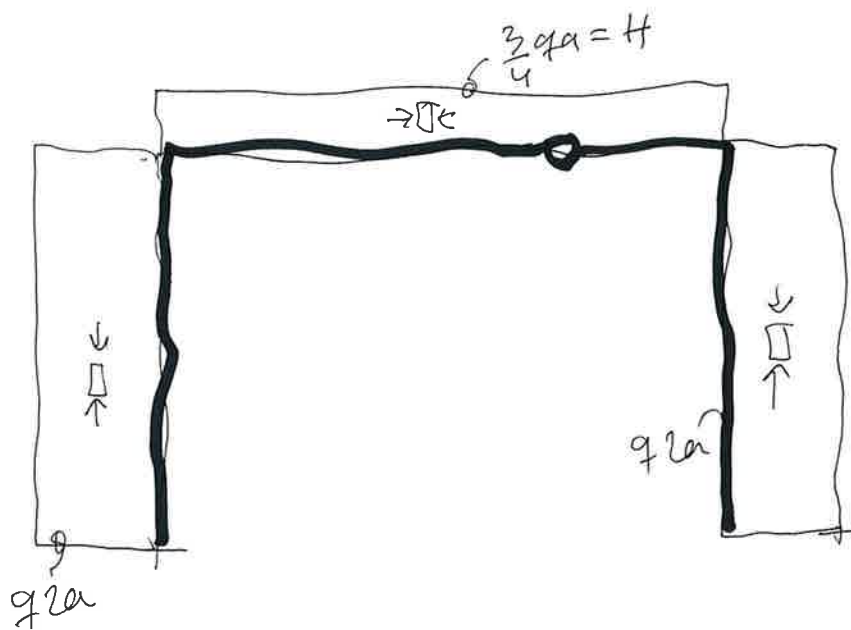
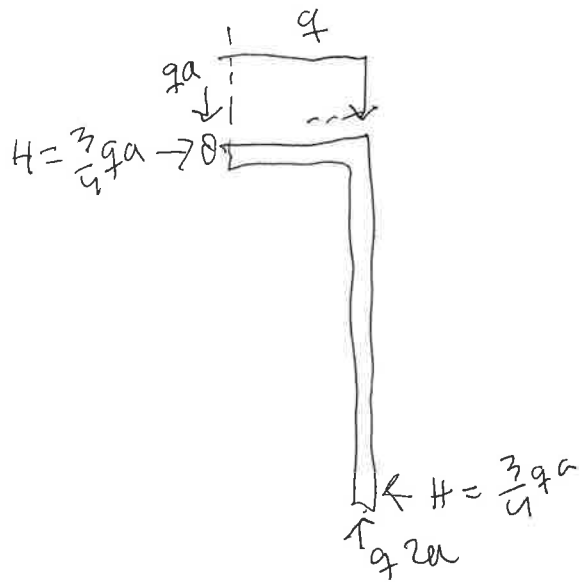
$$M_1 = \frac{q(4a)^2}{8} = \frac{2qa^2}{4}$$

$$M_2 = 2qa^2 - \frac{3qa^2}{2} = \frac{1}{2}qa^2$$

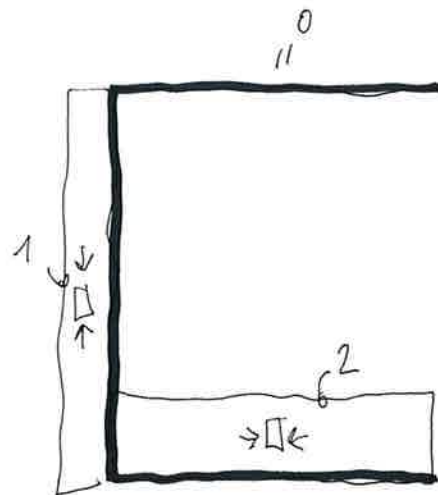
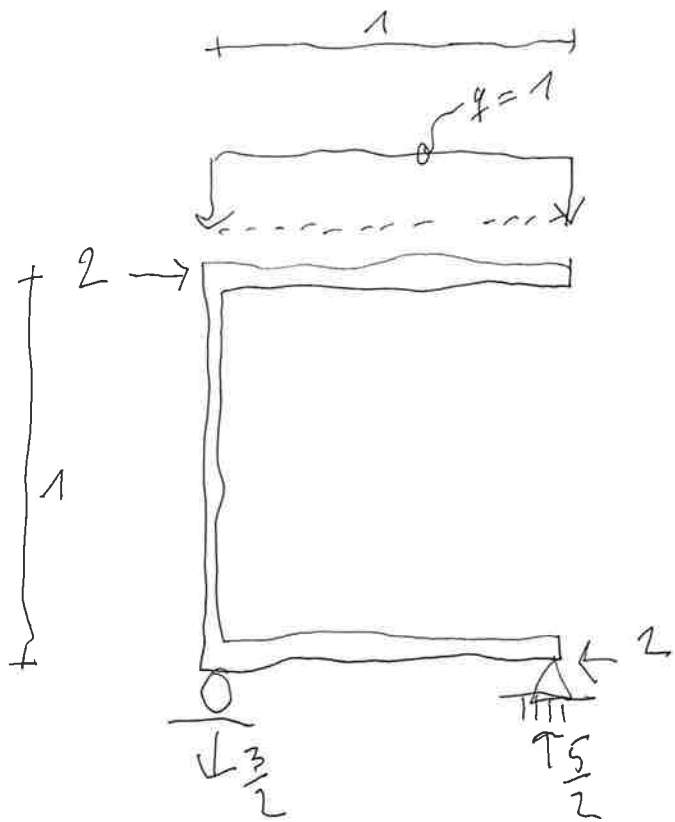
$$M_1 = H \cdot 2a = \frac{3}{4}qa \cdot 2a$$

$$= \frac{3}{2}qa^2$$

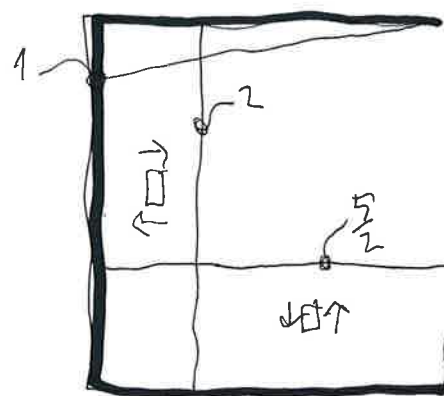
... normaler



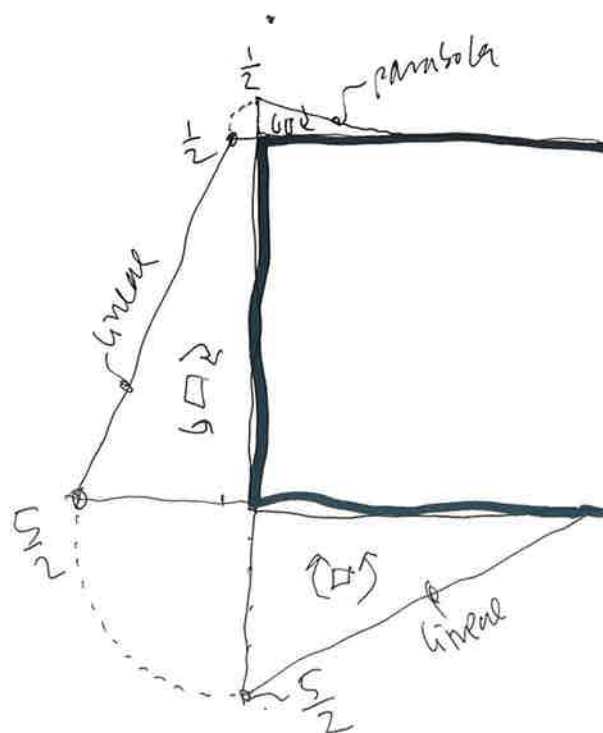
2



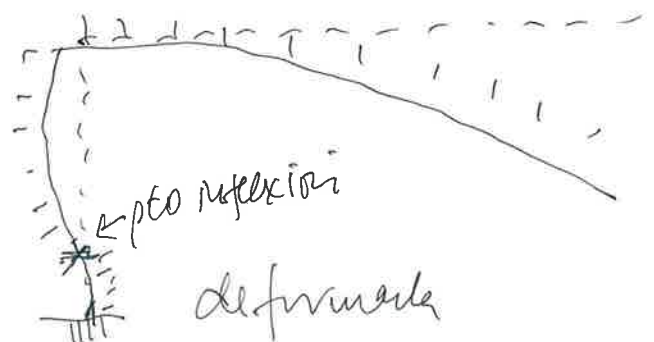
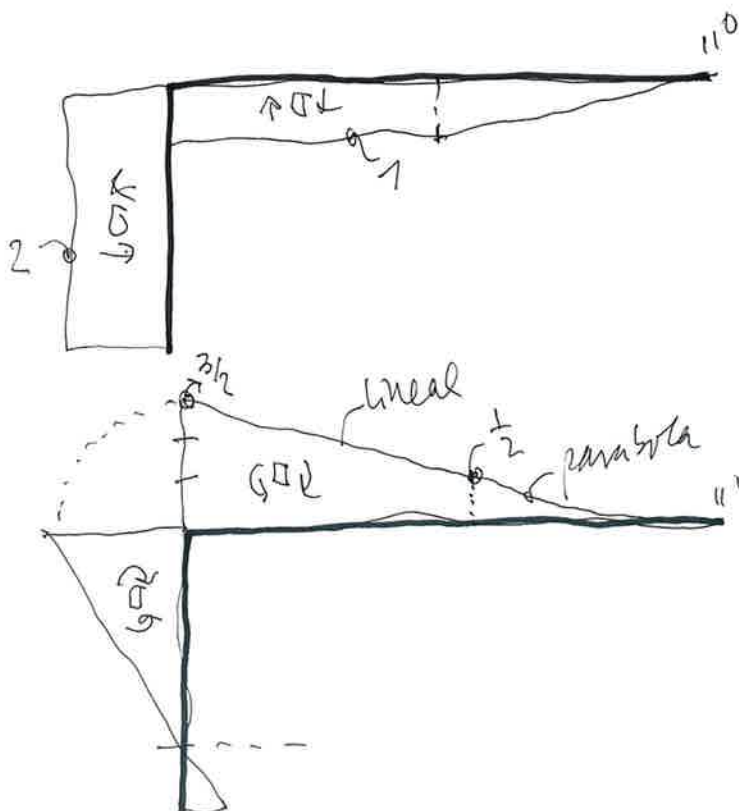
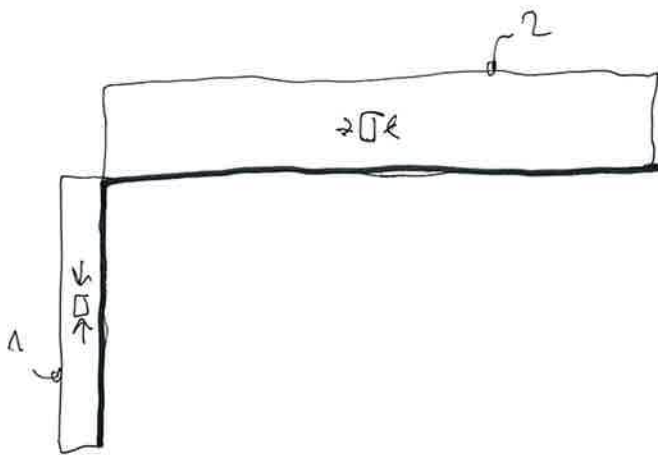
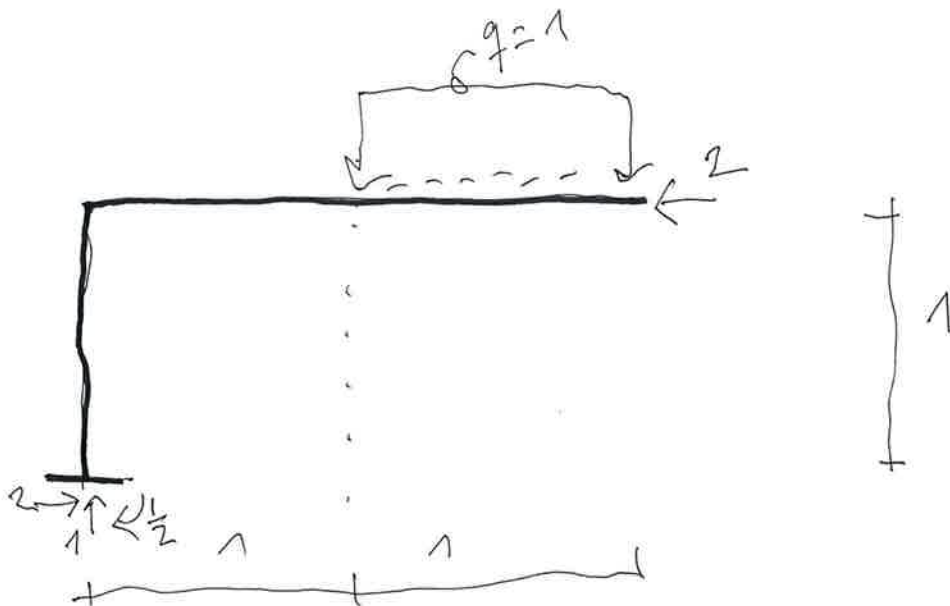
(N)

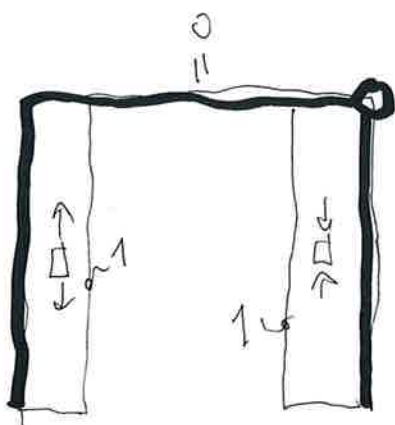
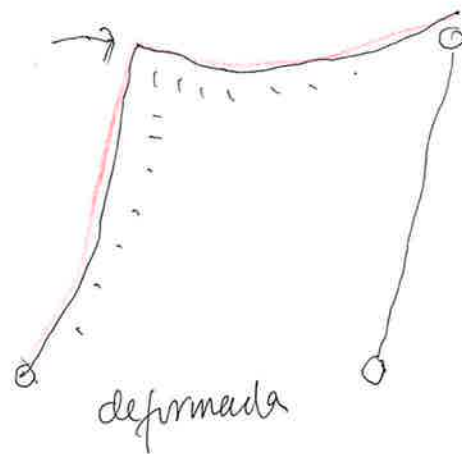
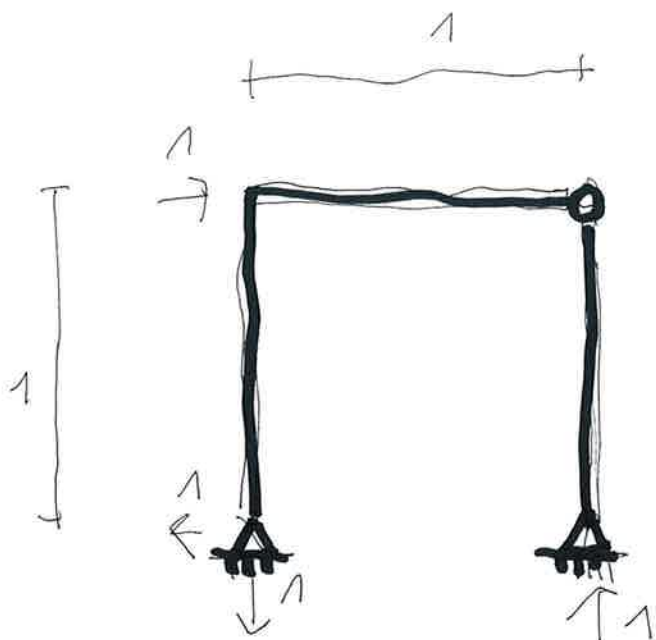


(V)

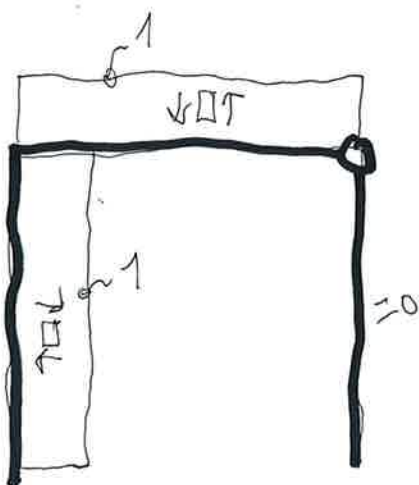


(M)

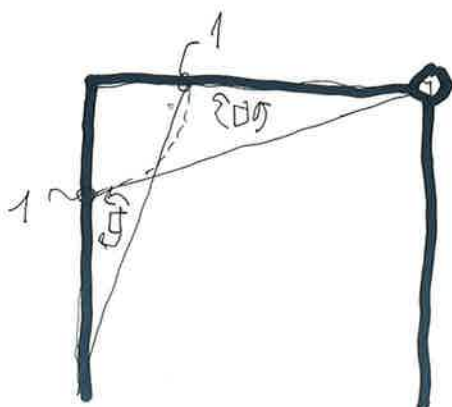




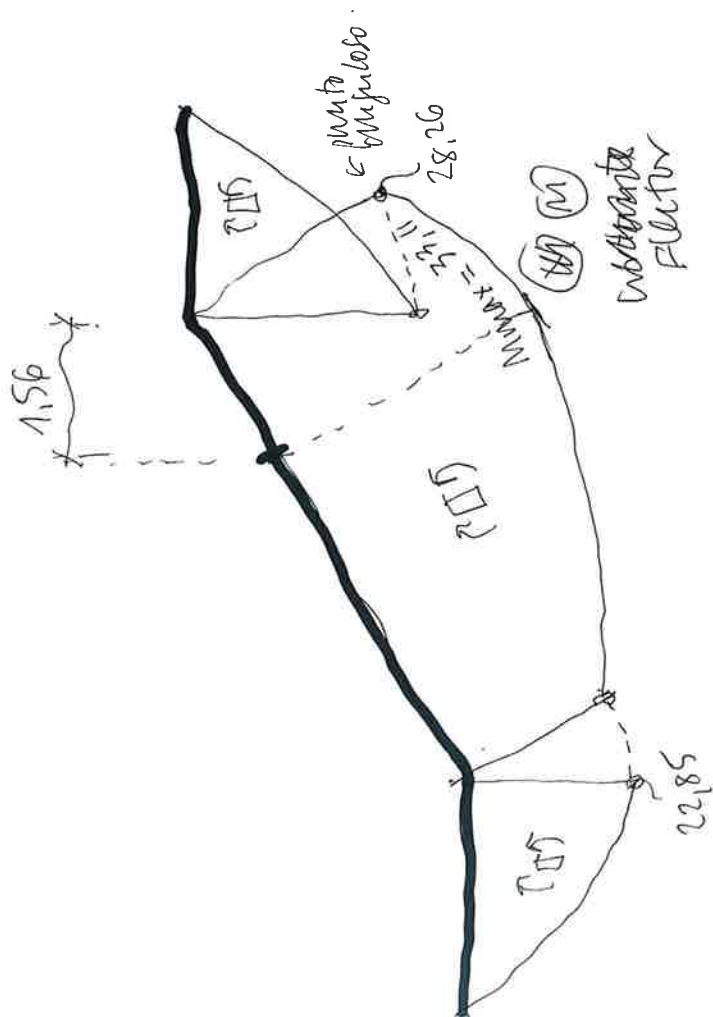
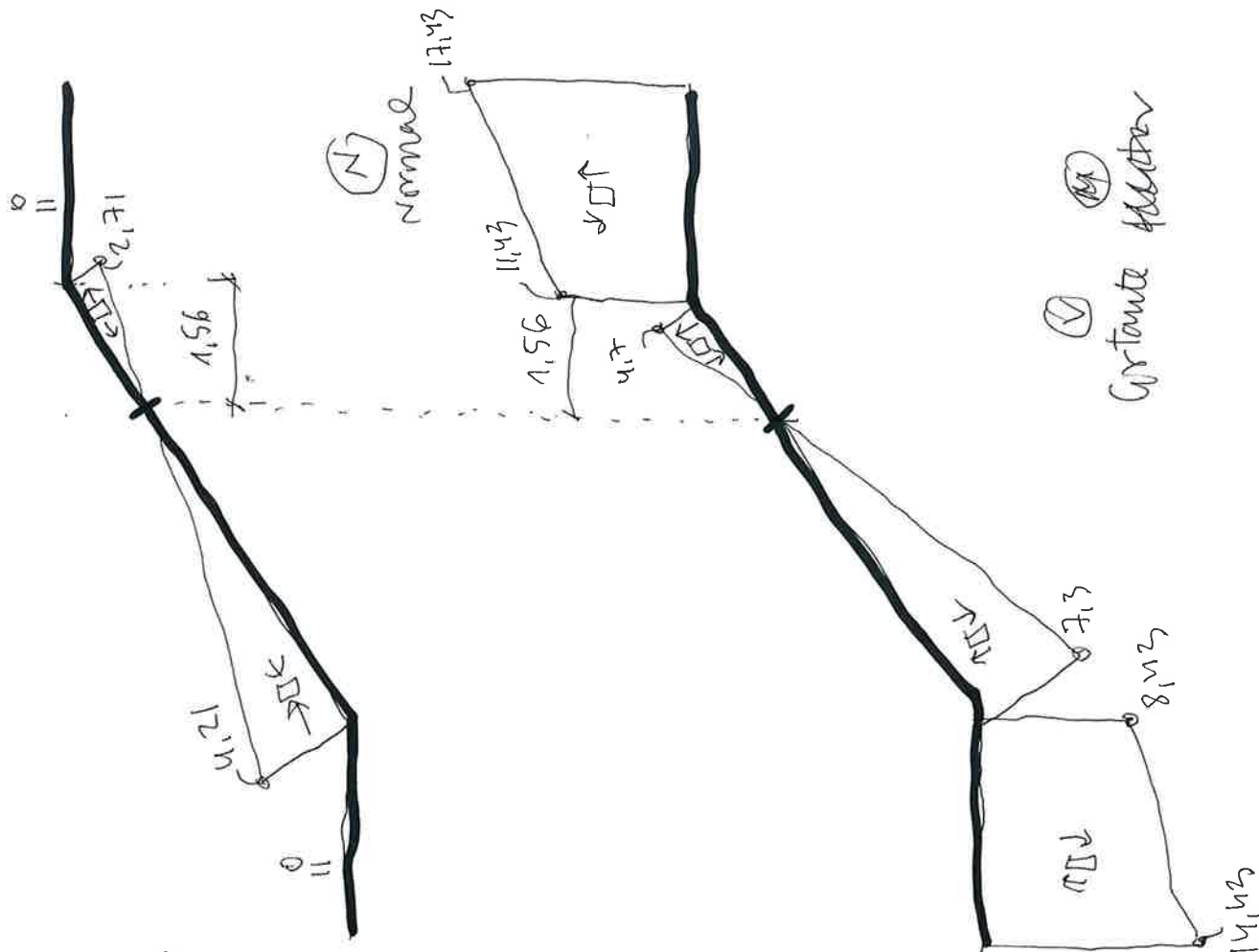
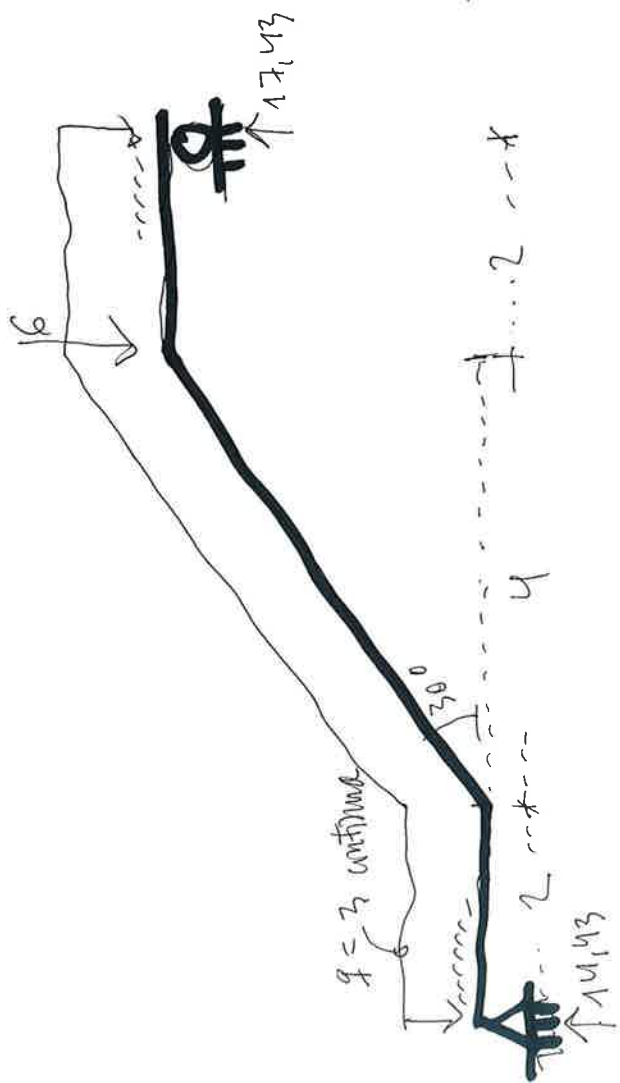
(2)



(V)

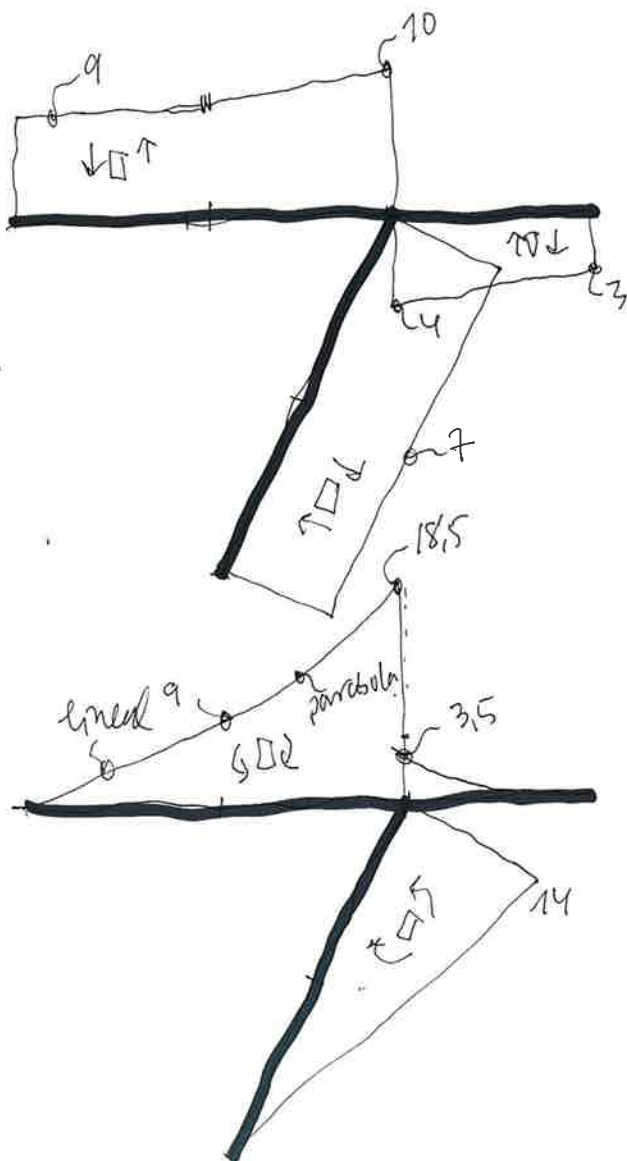
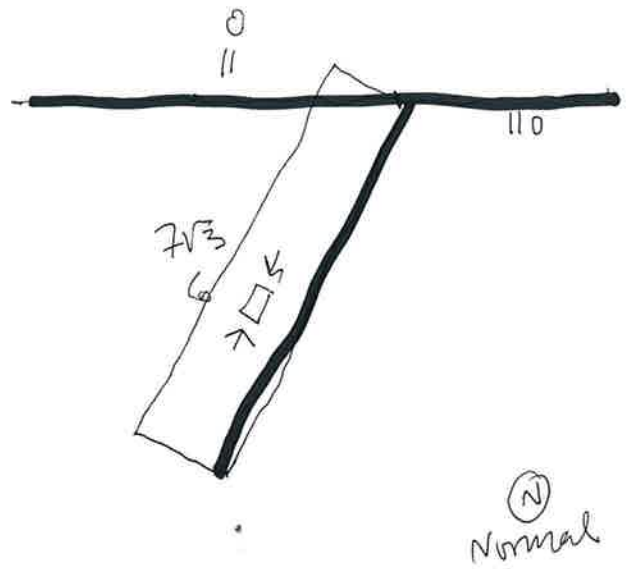
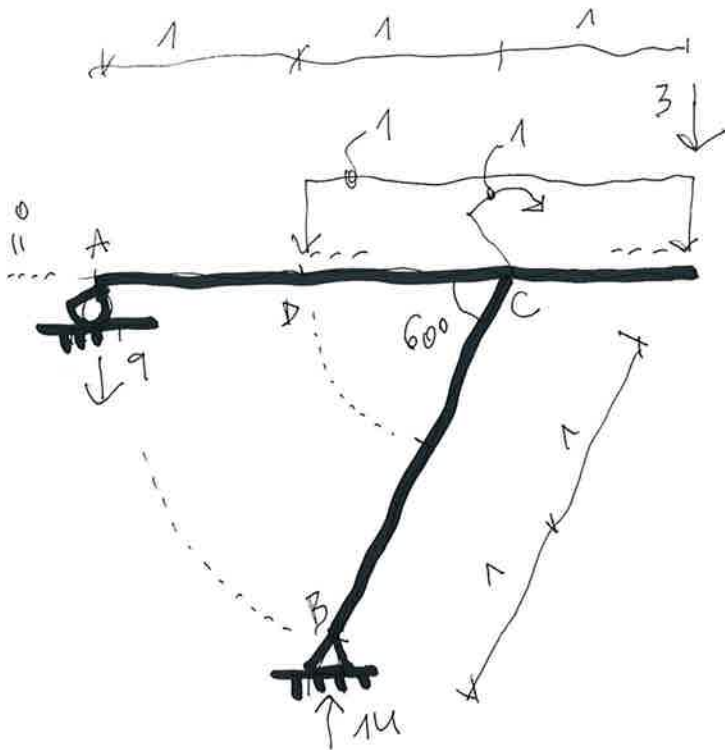


(M)



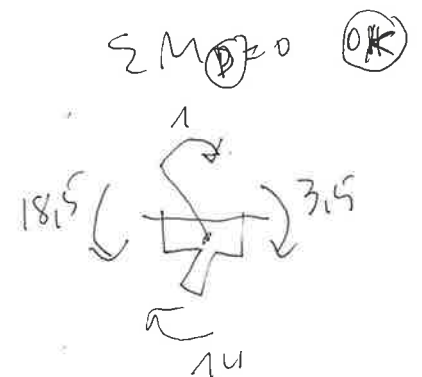
Gravante Huetter

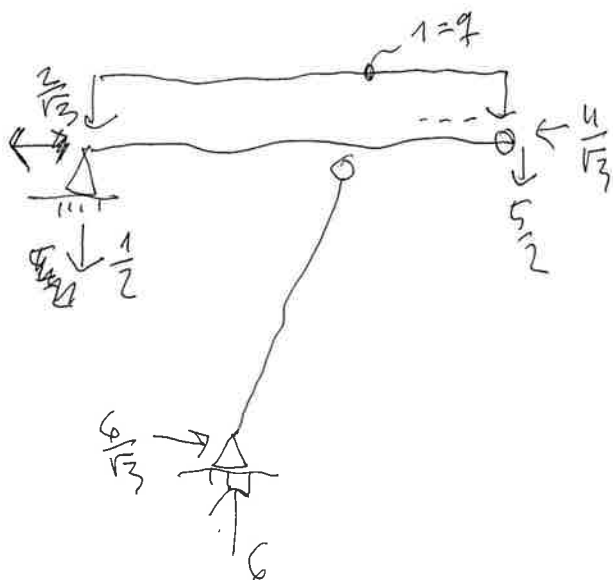
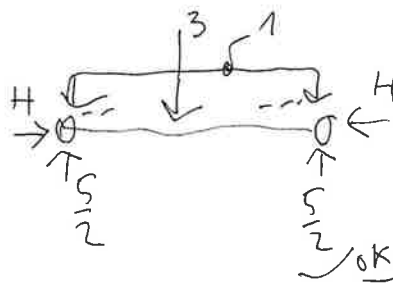
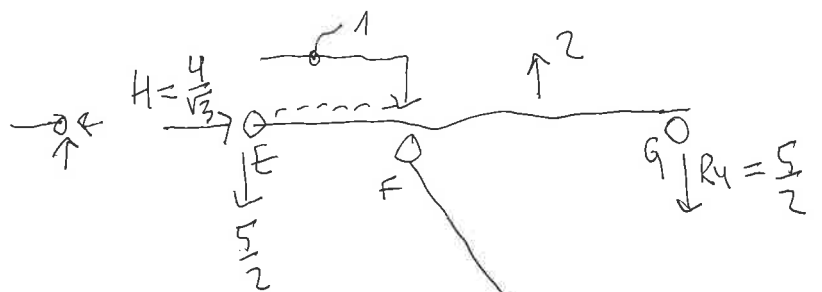
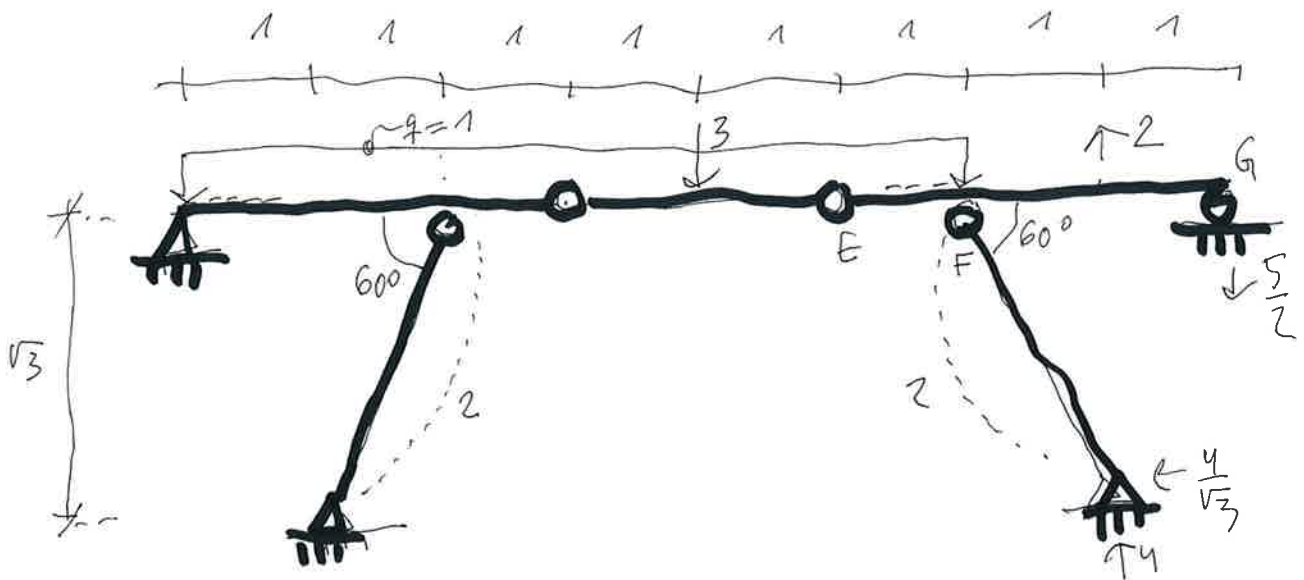
Instante Fluctu

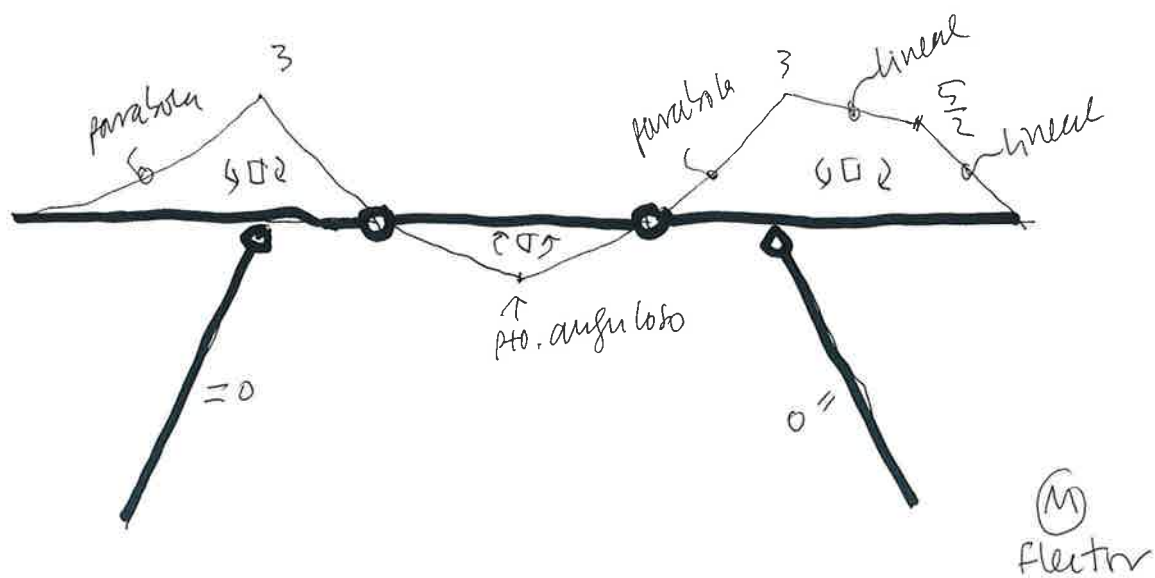
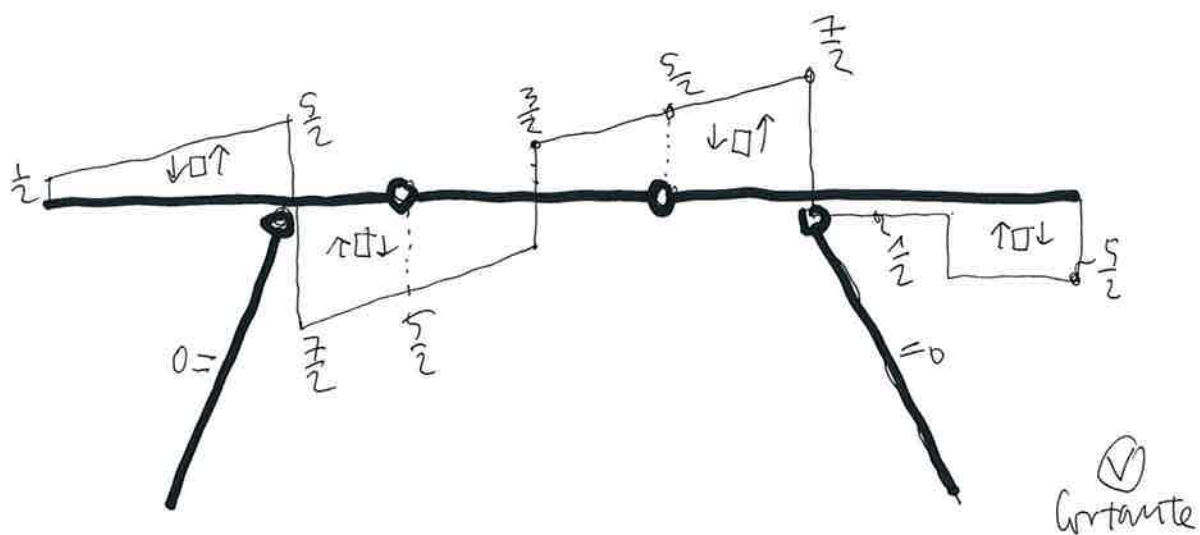
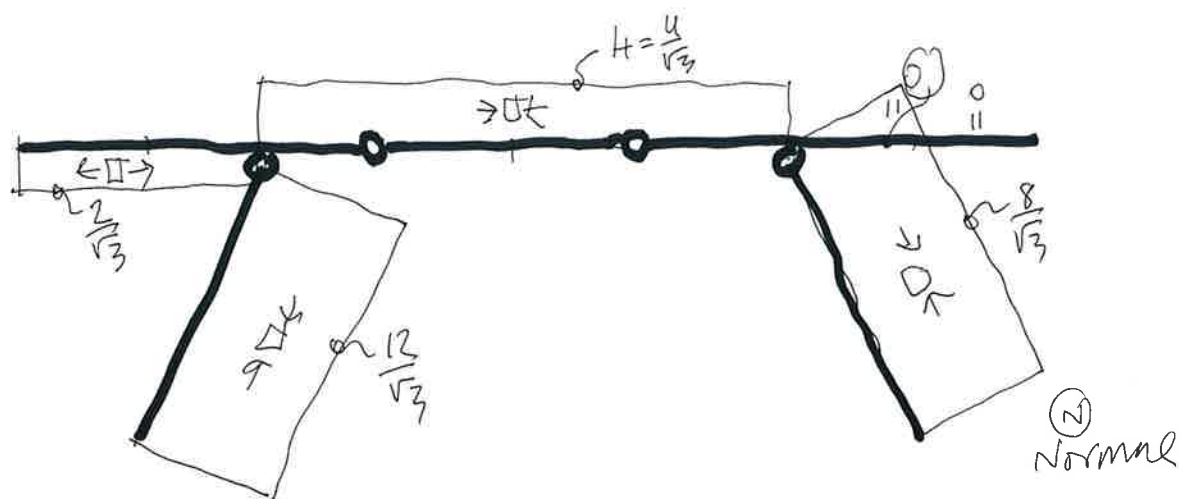


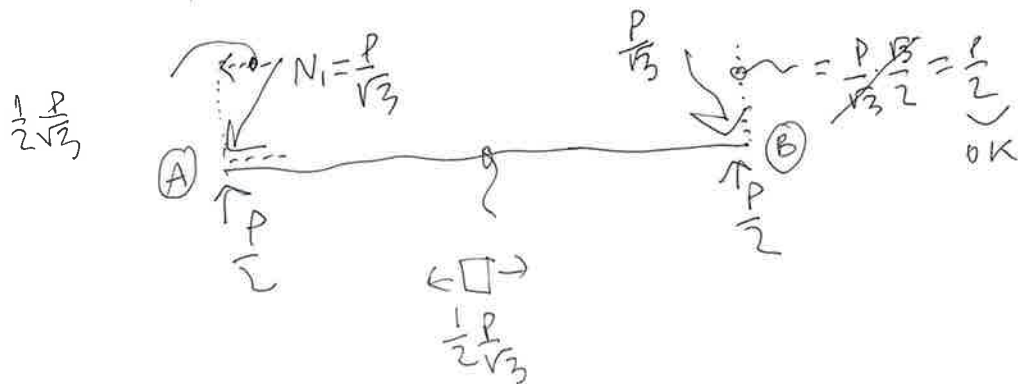
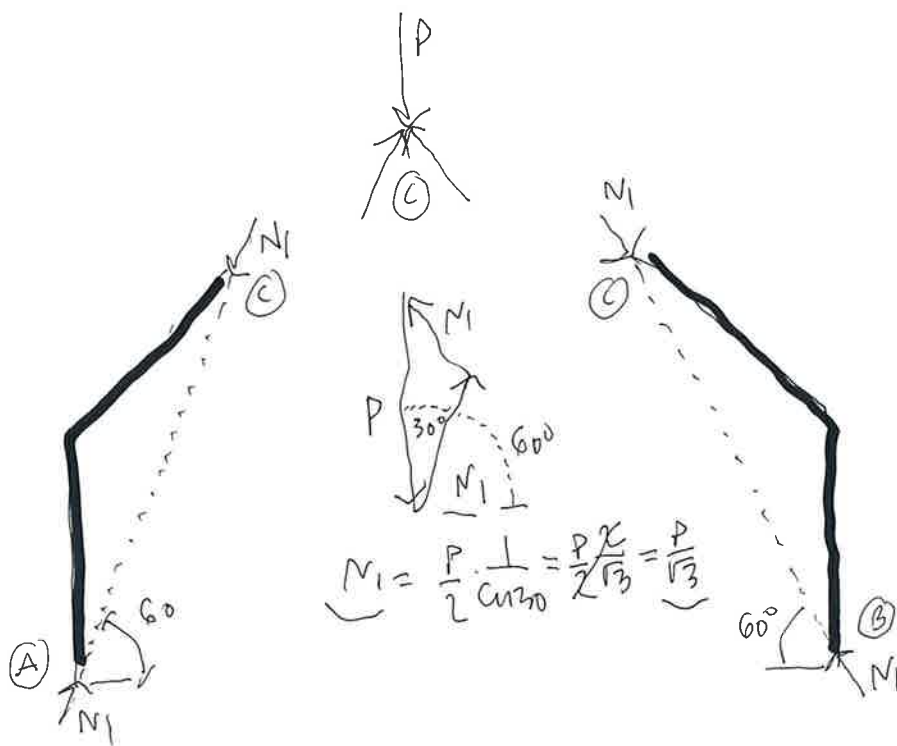
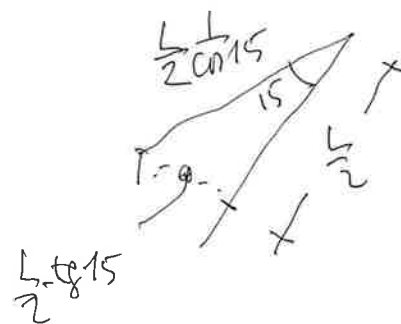
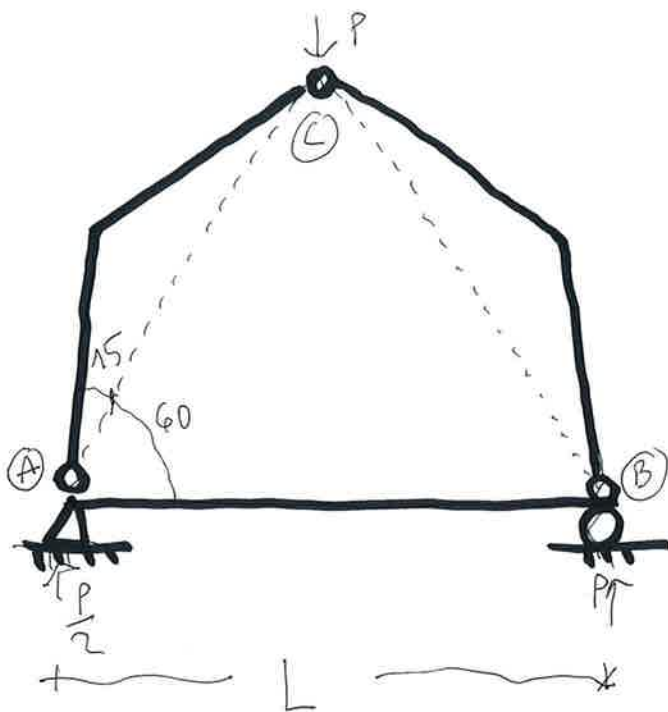
(V)
cortante

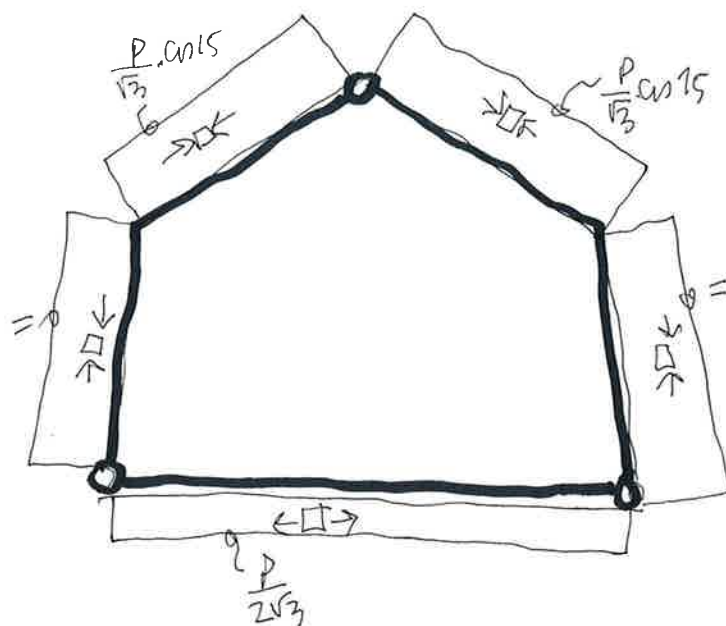
(M)
flexor



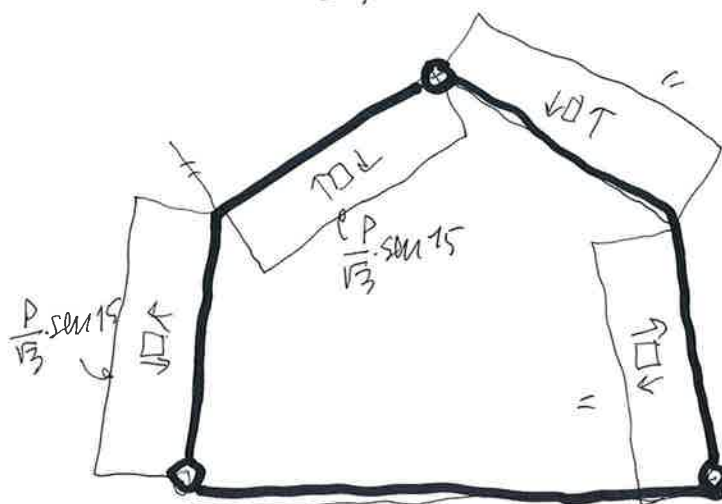




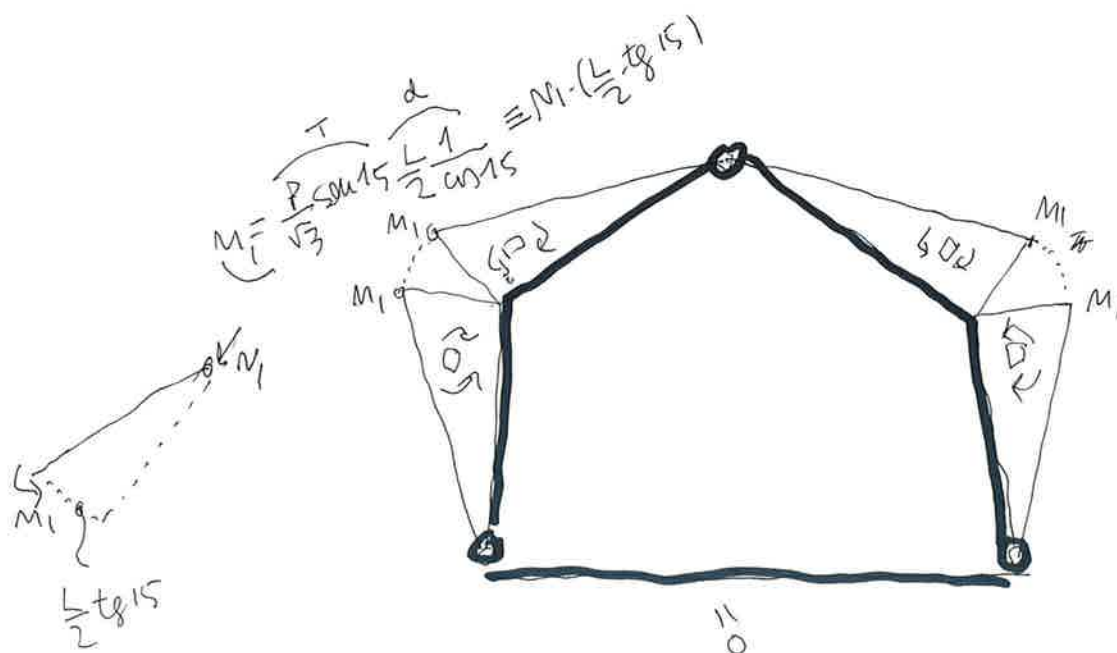




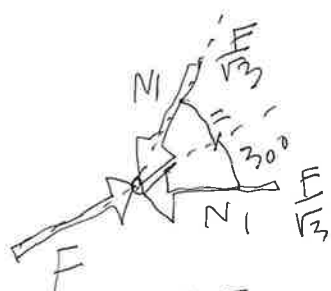
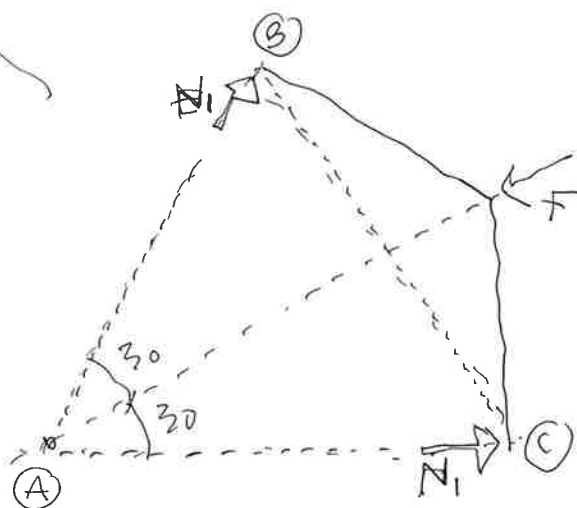
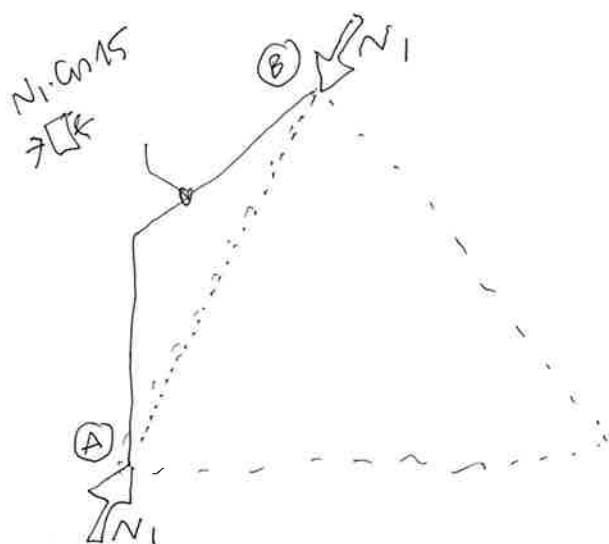
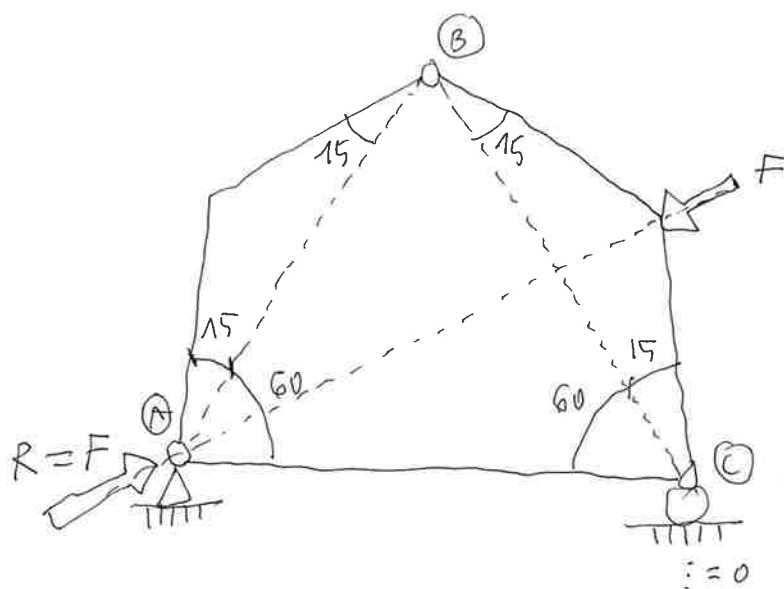
Normal



Constante



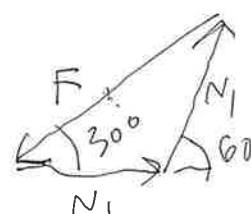
Flexão



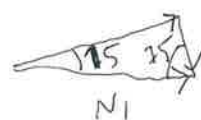
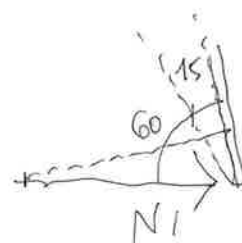
"Gewe"

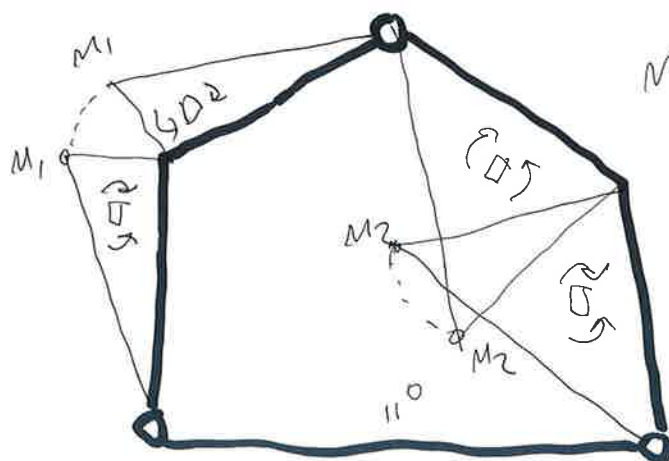
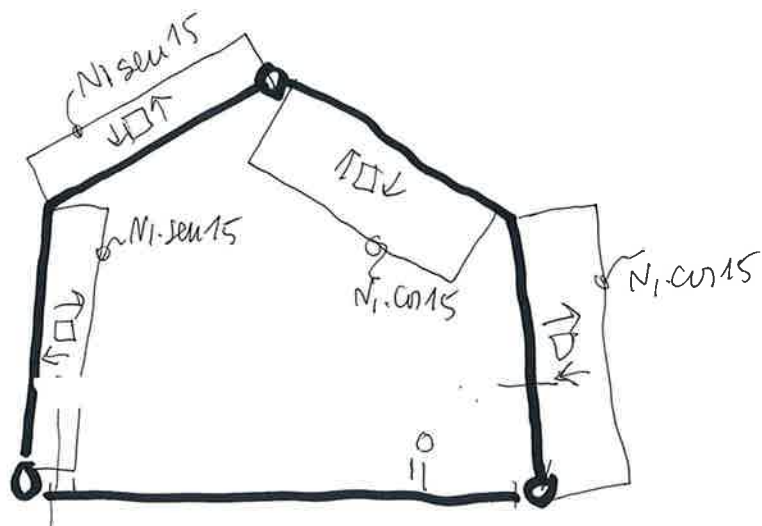
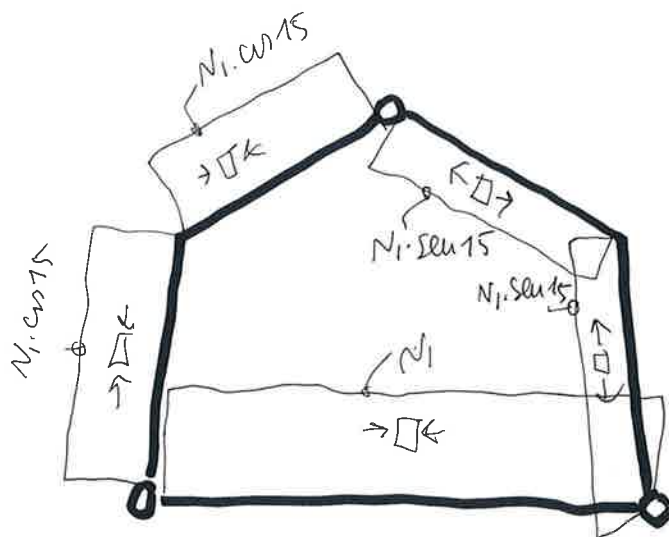
$$2 \cdot \frac{F}{\sqrt{3}} \cdot \cos 30^\circ = 2 \cdot \frac{F}{\sqrt{3}} \cdot \frac{\sqrt{3}}{2} = F$$

hat
equilibrium



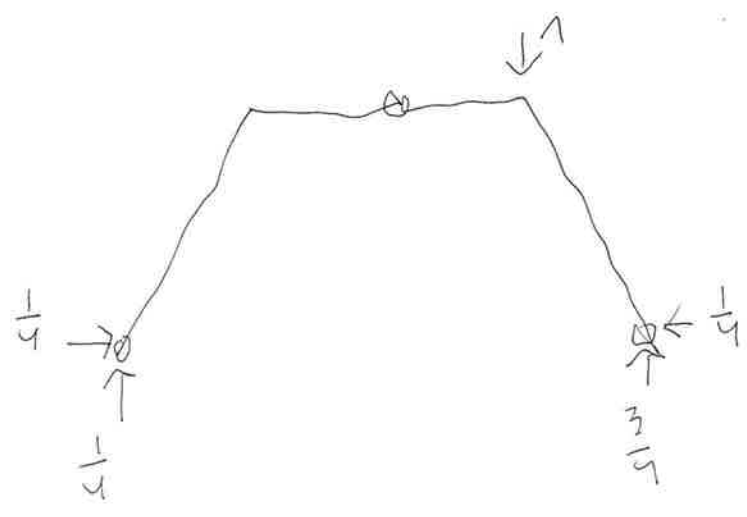
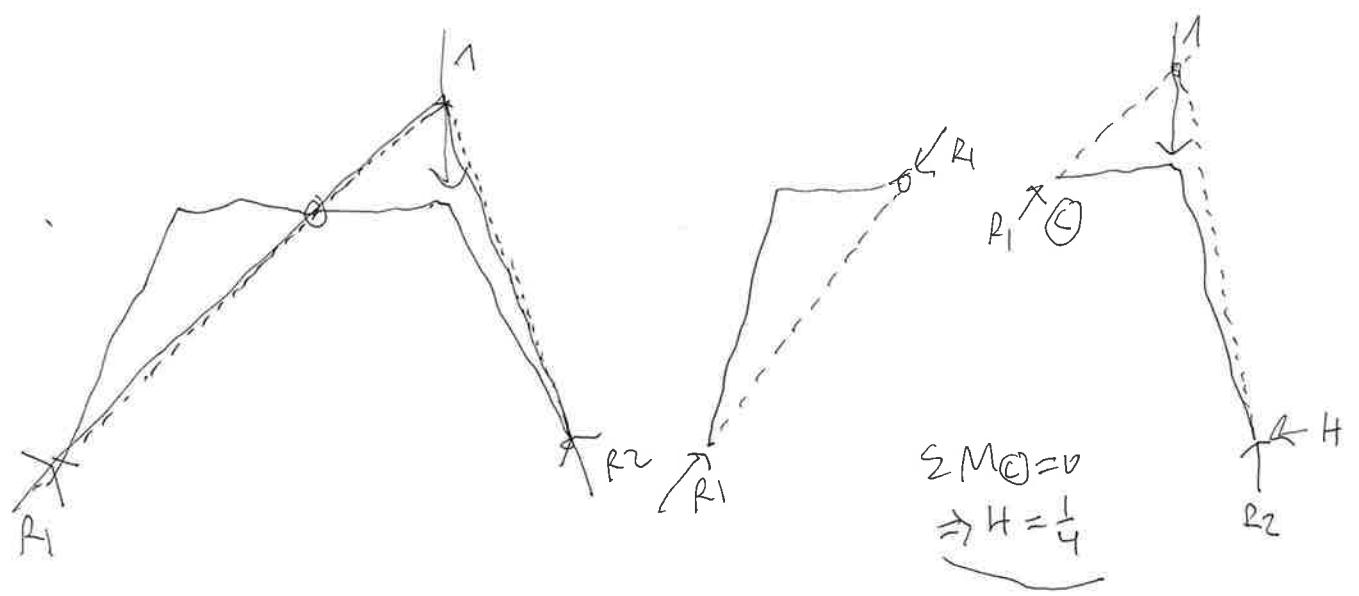
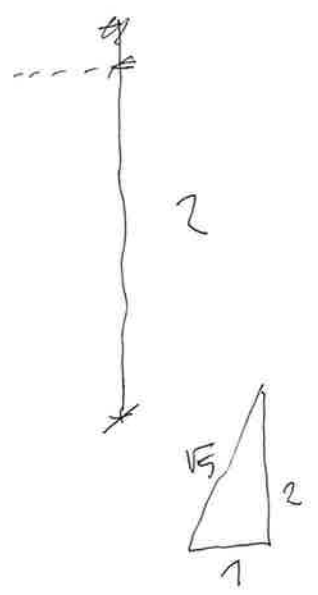
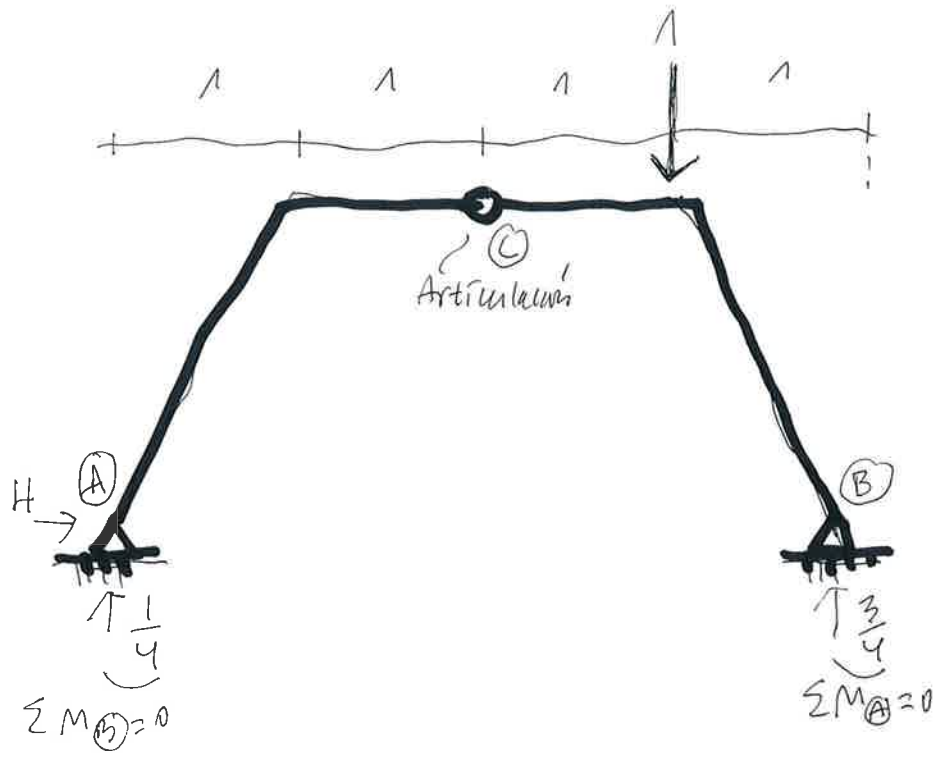
$$N_1 = \frac{F}{2} \cdot \frac{1}{\cos 30^\circ} = \frac{F}{2} \cdot \frac{2}{\sqrt{3}} = \frac{F}{\sqrt{3}}$$

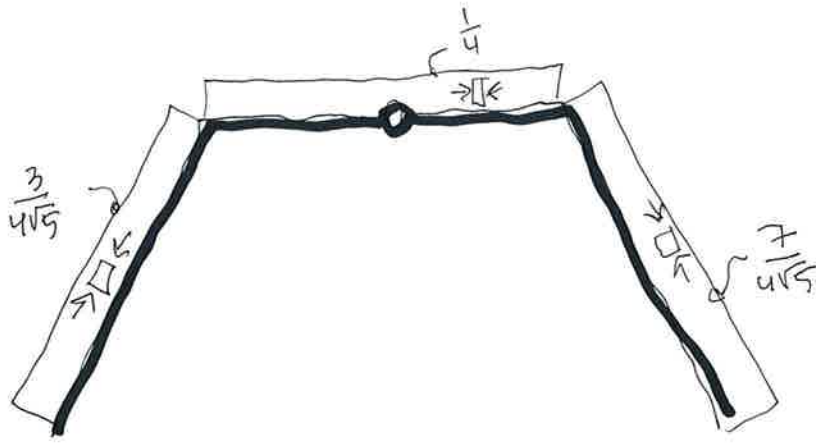




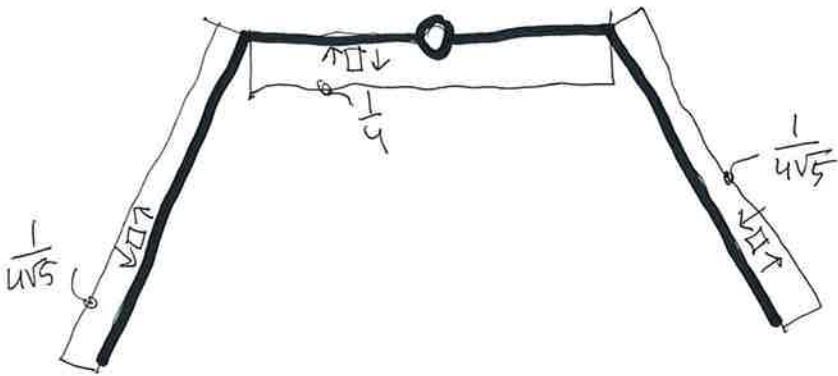
$$M_1 = N_1 \cdot \frac{L}{2} \cdot \tan 15$$

$$M_2 = N_1 \cdot \cos 15 \cdot \frac{L}{2} \cdot \frac{1}{\cos 15}$$

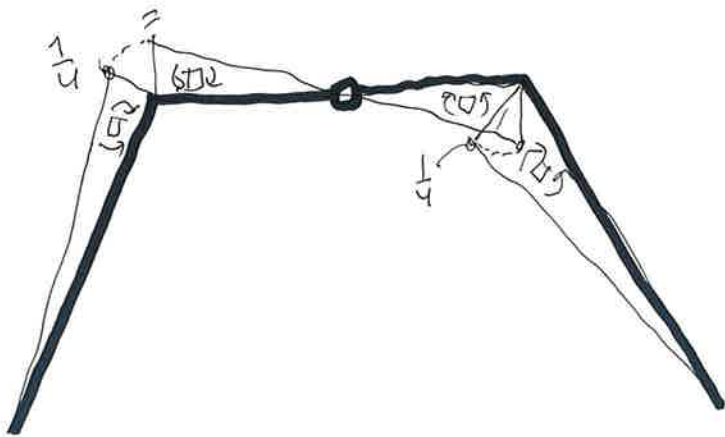




(N)
Normal



(V)
Artante



(M)
Flector.